



Invariant cone and synchronization state stability of the mean field models

W. Oukil, Ph. Thieullen & A. Kessi

To cite this article: W. Oukil, Ph. Thieullen & A. Kessi (2019) Invariant cone and synchronization state stability of the mean field models, *Dynamical Systems*, 34:3, 422-433, DOI: [10.1080/14689367.2018.1547683](https://doi.org/10.1080/14689367.2018.1547683)

To link to this article: <https://doi.org/10.1080/14689367.2018.1547683>



Accepted author version posted online: 15 Nov 2018.
Published online: 28 Nov 2018.



Submit your article to this journal [↗](#)



Article views: 53



View Crossmark data [↗](#)



Invariant cone and synchronization state stability of the mean field models

W. Oukil ^a, Ph. Thieullen^b and A. Kessi^c

^aDepartment of Mathematics and Computer Science, Médéa University, Médéa, Algeria; ^bInstitute of Mathematics of Bordeaux, Bordeaux University, Talence, France; ^cFaculty of Mathematics, University of Houari Boumediene, Algiers, Algeria

ABSTRACT

In this article we prove the stability of some mean field systems similar to the Winfree model in the synchronized state. The model is governed by the coupling strength parameter κ and the natural frequency of each oscillator. The stability is proved independently of the number of oscillators and the distribution of the natural frequencies. The main result is proved using the positive invariant cone method for the linearized system. This method can be applied to other mean field models as in the Kuramoto model.

ARTICLE HISTORY

Received 9 February 2018
Accepted 9 November 2018

KEYWORDS

Stability; coupled oscillators; mean field; interconnected systems; synchronization; Winfree model

**2010 MATHEMATICS
SUBJECT CLASSIFICATION**
37C75

1. Introduction and main result

In 1967 Winfree [8] proposed a mean field model describing the synchronization of a population of organisms or *oscillators* that interact simultaneously [1, 7]. The mean field models are used, for example, in the Neurosciences to study of neuronal synchronization in the brain [2, 3]. The Winfree model is given by the following differential equation

$$\begin{aligned}\dot{x}_i &= \omega_i - \kappa \sigma(x) R(x_i), \quad t \geq 0, \quad x = (x_1, \dots, x_n), \\ \sigma(x) &:= \frac{1}{n} \sum_{j=1}^n P(x_j), \quad \forall x = (x_1, \dots, x_n) \in \mathbb{R}^n, \\ \sup_{x \in \mathbb{R}} P(x) R(x) &> 0, \quad P, R \in C^2(\mathbb{R}) \text{ are } 2\pi\text{-periodic},\end{aligned}\tag{1}$$

where $n \geq 1$ is the number of oscillators, $\sigma(x)$ is the mean field interaction, $x_i(t)$ is the phase of the i th oscillator, and $x(t) = (x_1(t), \dots, x_n(t))$ is the global state of the system. We assume that the *natural frequencies* are chosen indifferently in some interval about $\omega = 1$,

$$\omega_i \in (1 - \gamma, 1 + \gamma), \quad \text{where } \gamma \in (0, 1).\tag{2}$$

CONTACT W. Oukil  oukil.walid@gmail.com

This article has been republished with minor changes. These changes do not impact the academic content of the article.

The coupling strength κ is taken in the interval $(0, 1)$. Let

$$M := 16 \max\{\|P^{(i)}\|_\infty \|R^{(j)}\|_\infty : 0 \leq i, j \leq 2\}, \tag{3}$$

be a constant used explicitly in some estimates measuring the size of the mean field.

We first define the notions of invariance and stability. Let $n \in \mathbb{N}^*$ and $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a C^1 vector field. Denote DF its Jacobian and assume

$$\max \left\{ \sup_{z \in \mathbb{R}^n} \|F(z)\|, \sup_{z \in \mathbb{R}^n} \|DF(z)\| \right\} < \infty.$$

where $\|\cdot\|$ is the usual matrix norm. Let $\phi^t : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be the flow of the autonomous system

$$\dot{x} = F(x), \quad t \geq 0. \tag{4}$$

Definition 1.1 (Invariance): Let $C \subset \mathbb{R}^n$ be an open set. We say that C is ϕ^t -positively invariant for the system (4), if $\phi^t(C) \subset C$ for all $t \geq 0$.

Definition 1.2 (Stability): Let $C \subset \mathbb{R}^n$ be an open set. We say that the system(4) is ϕ^t -positively stable on C , if C is ϕ^t -positively invariant and

$$\begin{aligned} \exists \lambda > 0, \quad \forall x \in C, \exists \delta > 0, \forall y \in C : \\ \|x - y\| < \delta \implies \|\phi^t(x) - \phi^t(y)\| \leq \lambda \|x - y\|, \quad \forall t \geq 0. \end{aligned}$$

Let Φ^t be the flow of the Winfree model (1). The existence of a synchronization state in the Winfree model is proved in [5] for every number n of oscillators and every choice of natural frequencies. We recall the main synchronization hypothesis used in [5],

$$\int_0^{2\pi} \frac{P(s)R'(s)}{1 - \kappa P(s)R(s)} ds > 0, \quad \forall \kappa \in (0, \kappa_*), \tag{H}$$

where κ_* is the locking bifurcation critical parameter κ_* defined by

$$\kappa_* := \left(\sup_{x \in \mathbb{R}} P(x)R(x) \right)^{-1}. \tag{5}$$

We proved in [5] there exists an open set

$$U \subset \left\{ (\gamma, \kappa) \in (0, 1) \times (0, \kappa_*) : 1 - \gamma - \frac{\kappa}{\kappa_*} > 0 \right\}$$

containing in its closure $\{0\} \times [0, \kappa_*]$, such that for every $n \geq 1$ and every parameter $(\gamma, \kappa) \in U$ there exist two constants $D \in (0, 1)$ and $\alpha(\gamma, \kappa, D)$,

$$\begin{aligned} 1 - \gamma - M\kappa D - \kappa/\kappa_* > 0, \\ \alpha(\gamma, \kappa, D) := \frac{2\gamma + M\kappa D^2}{1 - \kappa/\kappa_*} + \frac{(2\gamma + M\kappa D^2 + M\kappa D)(\gamma + M\kappa D)}{(1 - \gamma - M\kappa D - \kappa/\kappa_*)(1 - \kappa/\kappa_*)}, \end{aligned} \tag{6}$$

and a C^2 2π -periodic function $\Delta_{\gamma, \kappa} : \mathbb{R} \rightarrow (0, D)$ solution of

$$\frac{d}{ds} \Delta_{\gamma, \kappa}(s) = -\frac{\kappa P(s)R'(s)}{1 - \kappa P(s)R(s)} \Delta_{\gamma, \kappa}(s) + \alpha(\gamma, \kappa, D), \tag{7}$$

and a Φ^t -positively invariant open set $C_{\gamma,\kappa}^n$ independent of choice of the natural frequencies $(\omega_i)_{i=1}^n$,

$$C_{\gamma,\kappa}^n := \left\{ x = (x_i)_{i=1}^n \in \mathbb{R}^n : \max_{i,j} |x_j - x_i| < \Delta_{\gamma,\kappa} \left(\frac{1}{n} \sum_{i=1}^n x_i \right) \right\}. \tag{8}$$

The following main result asserts that $C_{\gamma,\kappa}^n$ is positively stable.

Consider the Winfree model (1) and assume that hypothesis (H) is satisfied. Then for every parameter $(\gamma, \kappa) \in U$, for every $n \geq 1$ and every choice of natural frequencies $(\omega_i)_{i=1}^n$ as in (2), the Winfree model (1) is Φ^t -positively stable on $C_{\gamma,\kappa}^n$.

Using a more refined version of Theorem 2 in Saito, see [4, 6], one can prove the existence of a uniform rotation vector $\rho \in \mathbb{R}^n$ such that for every initial condition $x \in C_{\gamma,\kappa}^n$

$$\Phi^t(x) = \rho t + p_x(t), \quad \forall t \geq 0$$

where $p_x(t)$ is an almost periodic function.

2. Invariant cone and stability

We study in this section the stability of a system of the form (4) using the positive invariant cone method for the linearized equation. Propositions 2.3 and 2.5 are the two main ingredients that guarantee the stability of the Winfree model. We actually consider more generally a parametrized linear system of the form,

$$\dot{y} = A(x, t)y, \quad t \geq 0, x \in C, \tag{9}$$

where C is an open set and $A(x, t)$ is a continuous $n \times n$ matrix function on $C \times \mathbb{R}^+$. Let Ψ_x^t be the fundamental matrix of (9) parametrized by $x \in C$. The fundamental matrix cocycle of the system (9) is denoted by

$$\Psi_x^{t,t'}(z) := \Psi_x^t(\Psi_x^{t'})^{-1}(z), \quad \forall z \in \mathbb{R}^n, \forall t \geq t' \geq 0.$$

Let V_+ be the positive cone defined by

$$V_+ := \{(z_1, \dots, z_n) \in \mathbb{R}^n : z_i \geq 0, \forall i = 1, \dots, n\}. \tag{10}$$

Definition 2.1: Consider the linear system (9). We say that the cone V_+ is Ψ_x^t -positively invariant uniformly in $x \in C$ if

$$\exists \delta > 0, \forall x \in C, \exists t_x \in [0, \delta] : \Psi_x^{t_x}(V_+) \subset V_+, \quad \forall t \geq t_x.$$

Definition 2.2: Consider the linear system (9). Let Ψ_x^t be its fundamental matrix. We say that (9) is Ψ_x^t -positively stable uniformly in C if

$$\exists \lambda > 0, \forall x \in C, \forall t \geq 0, \quad \|\Psi_x^t\| \leq \lambda.$$

We study in the next proposition the stability of some classes of nonlinear systems using the positive invariant cone method.

Proposition 2.3: Consider the system (4). Let be $F := (f_1, \dots, f_n)$. Suppose that there exists a ϕ^t -positively invariant open set $C \subset \mathbb{R}^n$ and there exists $\alpha > 0$ such that

$$f_i(\phi^t(x)) \geq \alpha, \quad \forall x \in C, \forall t \geq 0, \forall i \in \{1, \dots, n\}.$$

Let $x \in C$ and Ψ_x^t be the fundamental matrix of the linearized system

$$\dot{y} = DF(\phi^t(x))y, \quad t \geq 0. \quad (11)$$

Suppose that V_+ as in (10) is Ψ_x^t -positively invariant uniformly in C , then (4) is ϕ^t -positively stable on C .

To prove Proposition 2.3 we use the next Lemma which gives a sufficient condition of the stability of the system (4) as defined in Definition 1.2.

Lemma 2.4: Consider the system (4). Suppose that there exists a ϕ^t -positively invariant open set $C \subset \mathbb{R}^n$ such that the linear system

$$\dot{y} = DF(\phi^t(x))y, \quad \forall t \geq 0, \forall x \in C, \quad (12)$$

is Ψ_x^t -positively stable uniformly in C . Then (4) is ϕ^t -positively stable on C .

Proof: The system (4) can be written as

$$\frac{d}{dt}D\phi^t(x) = DF(\phi^t(x))D\phi^t(x) \quad \text{with} \quad \Psi_x^t = D\phi^t(x).$$

Since the system (12) is Ψ_x^t -positively stable uniformly in C , we have

$$\exists \lambda > 0, \forall x \in C, \forall t \geq 0, \quad \|F(z)\| (x) \leq \lambda. \quad (13)$$

Let $(z_1, z_2) \in C \times C$ such that $z(s) := (1 - s)z_2 + sz_1 \in C$ for all $s \in [0, 1]$. Then

$$\begin{aligned} \|\phi^t(z_1) - \phi^t(z_2)\| &= \left\| \int_0^1 \frac{d}{ds} \phi^t(z(s)) ds \right\| = \left\| \int_0^1 D\phi^t(z(s)) \frac{dz(s)}{ds} ds \right\|, \\ &= \left\| \int_0^1 D\phi^t(z(s))(z_1 - z_2) ds \right\| \leq \sup_{s \in [0,1]} \|D\phi^t(z(s))(z_1 - z_2)\|. \end{aligned}$$

Finally, use the fact $z(s) \in C$ and use equation (13) to obtain

$$\|\phi^t(z_1) - \phi^t(z_2)\| \leq \lambda \|z_1 - z_2\|, \quad \forall t \geq 0,$$

which implies that the (4) is ϕ^t -positively stable on C . ■

Proof: Since V_+ is Ψ_x^t -positively invariant uniformly in C ,

$$\exists \delta > 0, \forall x \in C, \exists t_x \in [0, \delta] : z \in V_+ \implies \Psi_x^{t, t_x}(z) \in V_+, \quad \forall t \geq t_x.$$

Let be $\eta := \alpha^{-1}, x \in C, y \in \mathbb{R}^n$, and denote

$$z^+ := \eta \|y\| F(\phi^{t_x}(x)) + y \quad \text{and} \quad z^- := \eta \|y\| F(\phi^{t_x}(x)) - y.$$

On the one hand, $z^+ := (z_1^+, \dots, z_n^+) \in V_+$ and $z^- := (z_1^-, \dots, z_n^-) \in V_+$,

$$\min_{1 \leq i \leq n} \{z_i^-, z_i^+\} \geq \eta \|y\| \min_{1 \leq i \leq n} \left\{ \inf_{x \in C} f_i(\phi^{t_x}(x)) \right\} - \|y\| \geq (\eta\alpha - 1) \|y\| = 0.$$

On the other hand, $F(\phi^t(x))$ is solution of the linearized system (11)

$$\begin{aligned} \frac{d}{ds} F(\phi^s(x)) &= DF(\phi^s(x))F(\phi^s(x)), \\ F(\phi^t(x)) &= \Psi_x^{t, t_*} F(\phi^{t_*}(x)). \end{aligned}$$

Since V_+ is Ψ_x^t -positively invariant uniformly in C , we obtain

$$\begin{aligned} \eta \|y\| F(\phi^t(x)) + \Psi_x^{t, t_x}(y) &= \Psi_x^{t, t_x}(z^+) \in V_+, \quad \forall t \geq t_x, \\ \eta \|y\| F(\phi^t(x)) - \Psi_x^{t, t_x}(y) &= \Psi_x^{t, t_x}(z^-) \in V_+, \quad \forall t \geq t_x. \end{aligned}$$

Put $r := \max\{\|F(\phi^t(x))\|, \|DF(\phi^t(x))\|\} < +\infty$ we obtain

$$\begin{aligned} \|\Psi_x^{t, t_x}(y)\| &\leq \eta r \|y\|, \quad \forall t \geq \delta, \quad \|\Psi_x^t\| \leq \exp(r\delta), \quad \forall t \in [0, \delta], \\ \|\Psi_x^t(y)\| &\leq \lambda \|y\|, \quad \forall x \in C, \quad \forall t \geq 0, \end{aligned}$$

where $\lambda := \eta r \exp(r\delta)$. The linearized system (11) is Ψ_x^t -positively stable uniformly in C . Lemma 2.4 implies that (4) is ϕ^t -positively stable on C . ■

We give in the following proposition a sufficient condition for the invariance of the cone V_+ .

Proposition 2.5: *Let $p, q : \mathbb{R} \rightarrow \mathbb{R}$ be continuous 2π -periodic functions, and $g_i, h_{i,j} : [0, +\infty) \rightarrow \mathbb{R}, 1 \leq i, j \leq n$, be continuous functions. Consider the linear non-autonomous ODE*

$$\frac{dz_i}{ds} = g_i(s)z_i + \frac{1}{n} \sum_{j=1}^n (p(s) + h_{i,j}(s))z_j, \quad \forall s \geq 0, \quad \forall 1 \leq i \leq n. \tag{14}$$

Assume there exists a constant $D > 0$ and a continuous 2π -periodic function $\delta : \mathbb{R} \rightarrow (0, D)$ such that

- $\int_0^{2\pi} p(s) ds > 0$,
- $d\delta/ds = -p(s)\delta + q(s), \forall s \geq 0$,
- $0 \leq g_i(s) \leq q(s)/4D, |h_{i,j}(s)| \leq q(s)/8D, \forall s \geq 0$.

Let $\Psi^{s,s'}$ be the fundamental matrix of (14). Then there exists $s_* \in [0, 2\pi]$ such that $\Psi^{s,s_*}(V_+) \subset V_+$ for all $s \geq s_*$.

Proof: Let be $s_* \in [0, 2\pi]$ satisfying

$$\max_{s \in [0, 2\pi]} \delta(s) = \delta(s_*). \tag{15}$$

Let $\Psi^{s,s'} = (\Psi_1^{s,s'}, \dots, \Psi_n^{s,s'})$ be the fundamental matrix cocycle of (14). Let V_+ be the interior of the set V_+ , $z_* \in V_+$ fixed, and $z(s) = \Psi^{s,s_*}(z_*)$. By continuity,

$$\exists s_1 > s_* : z(s) \in V_+, \quad \forall s \in [s_*, s_1].$$

Define

$$S := \sup \{s > s_* : z(s') \in V_+, \forall s' \in [s_*, s]\}.$$

The proposition is proved if we show $S = +\infty$. By contradiction, suppose that $S < +\infty$, then

$$z(S) \notin V_+. \tag{16}$$

Define

$$\mu(s) := \frac{1}{n} \sum_{i=1}^n z_i(s).$$

By uniqueness of solutions $\mu(s) > 0, \forall s \in [s_*, S]$. Then for all $s \in [s_*, S]$,

$$\frac{dz_i}{ds} = g_i(s)z_i + (p(s) + h_i(s))\mu(s),$$

where

$$h_i(s) := \frac{\sum_{j=1}^n h_{ij}(s)z_j(s)}{\sum_{j=1}^n z_j(s)}.$$

Define

$$g(s) := \frac{\sum_{i=1}^n g_i(s)z_i(s)}{\sum_{i=1}^n z_i(s)}, \quad \text{and} \quad h(s) := \frac{1}{n} \sum_{i=1}^n h_i(s).$$

Then

$$0 \leq g(s) \leq \frac{q(s)}{4D}, \quad |h_i(s)| \leq \frac{q(s)}{8D}, \quad |h(s)| \leq \frac{q(s)}{8D}.$$

Define

$$a(s) := g(s) + p(s) + h(s), \quad \forall s \geq s_*.$$

Then

$$\frac{d\mu}{ds} = a(s)\mu, \quad \mu(s) = \mu(s_*) \exp\left(\int_{s_*}^s a(\zeta) d\zeta\right).$$

Since $|p(s) + h_i(s) - a(s)| = |-g(s) + h_i(s) - h(s)| \leq q(s)/(2D)$, we have

$$\begin{aligned} \frac{dz_i}{ds} &\geq (p(s) + h_i(s))\mu(s), \\ &\geq (p(s) + h_i(s))\mu(s_*) \exp\left(\int_{s_*}^s a(\zeta) d\zeta\right), \\ \frac{z_i(s) - z_i(s_*)}{\mu(s_*)} &\geq \int_{s_*}^s (p(s') + h_i(s') - a(s')) \exp\left(\int_{s_*}^{s'} a(\zeta) d\zeta\right) ds' \\ &\quad + \int_{s_*}^s a(s') \exp\left(\int_{s_*}^{s'} a(\zeta) d\zeta\right) ds' \\ &\geq \exp\left(\int_{s_*}^s a(\zeta) d\zeta\right) - 1 - \int_{s_*}^s \frac{q(s')}{2D} \exp\left(\int_{s_*}^{s'} a(\zeta) d\zeta\right) ds'. \end{aligned}$$

Multiplying by $\delta(s_*) \exp(-\int_{s_*}^s a(\zeta) d\zeta)$ and using $\delta(s_*) < D$, we get

$$\begin{aligned} \frac{\delta(s_*)z_i(s)}{\mu(s)} &\geq \delta(s_*) - \delta(s_*) \exp\left(-\int_{s_*}^s a(\zeta) d\zeta\right) \\ &\quad - \int_{s_*}^s \frac{q(s')}{2} \exp\left(-\int_{s'}^s a(\zeta) d\zeta\right) ds'. \end{aligned}$$

Let $\tilde{\delta}(s)$ be the unique solution of

$$\frac{d\tilde{\delta}}{ds} = -a(s)\tilde{\delta} + \frac{q(s)}{2}, \quad \forall s \in [s_*, S], \quad \tilde{\delta}(s_*) = \delta(s_*).$$

Then

$$\begin{aligned} \tilde{\delta}(s) &= \delta(s_*) \exp\left(-\int_{s_*}^s a(\zeta) d\zeta\right) \\ &\quad \times \int_{s_*}^s \frac{q(s')}{2} \exp\left(-\int_{s'}^s a(\zeta) d\zeta\right) ds', \\ \frac{\delta(s_*)z_i(s)}{\mu(s)} &\geq \delta(s_*) - \tilde{\delta}(s), \quad \forall s \in [s_*, S]. \end{aligned} \tag{17}$$

Notice that

$$a(s) = g(s) + p(s) + h(s) \geq p(s) - \frac{q(s)}{2D}, \quad \forall s \in [s_*, S].$$

Then

$$\frac{d\tilde{\delta}}{ds} \leq -p(s)\tilde{\delta} + \frac{q(s)}{2} \left(1 + \frac{\tilde{\delta}}{D}\right), \quad \forall s \in [s_*, S].$$

To obtain $z(S) \in V_+$ and get a contradiction with (16), it is sufficient to prove that $\tilde{\delta}(s) \leq \delta(s)$, $\forall s \in (s_*, S]$. For that, we use the comparison principle of differential equations. Since

$0 < \tilde{\delta}(s_*) = \delta(s_*) < D$ and

$$\frac{d\tilde{\delta}}{ds}(s_*) < -p(s_*)\tilde{\delta}(s_*) + q(s_*) = \frac{d\delta}{ds}(s_*)$$

there exists $\epsilon > 0$ such that $\tilde{\delta}(s) < \delta(s)$ for all $s \in (s_*, s_* + \epsilon)$. Define

$$\tilde{S} := \sup \{s \in [s_*, S] : \tilde{\delta}(s') < \delta(s'), \forall s' \in (s_*, s]\}.$$

We show that that $\tilde{S} = S$. By contradiction, if $\tilde{S} < S$, then $\tilde{\delta}(\tilde{S}) = \delta(\tilde{S})$,

$$\frac{d\tilde{\delta}}{ds}(\tilde{S}) < -p(\tilde{S})\tilde{\delta}(\tilde{S}) + q(\tilde{S}) = \frac{d\delta}{ds}(\tilde{S}),$$

and we could find $s < \tilde{S}$ close enough to \tilde{S} such that $\tilde{\delta}(s) > \delta(s)$. We have obtained a contradiction. Then $\tilde{S} = S$ and $\tilde{\delta}(\tilde{S}) < \delta(\tilde{S}) \leq \delta(s_*)$. Equation (17) implies $z(S) \in V_+$, which is a contradiction with (16). We have obtained $z(s) \in V_+$ for all $s \geq s_*$. By continuity of the fundamental matrix cocycle, we have proved that $z(s) \in V_+$ for all $z(s_*) \in V_+$ and all $s \geq s_*$. ■

3. Proof of the main result

We prove in this Section the Main result of Section 1. We consider the Winfree model (1) and its associated flow Φ^t . We recall that the Winfree model satisfies the hypothesis (H). The *linearized Winfree model* is given by

$$\begin{aligned} \frac{dy}{dt} &= D\mathcal{W}(\Phi^t(x))y, \quad t \geq 0, \quad y = (y_1, \dots, y_n), \\ \mathcal{W}_i(x) &:= \omega_i - \kappa \sigma(x)R(x_i), \quad x = (x_1, \dots, x_n) \in \mathbb{R}^n, \\ \frac{\partial \mathcal{W}_i}{\partial x_j} &= -\kappa \left[\sigma(x)R'(x_i)\delta_{ij} + \frac{R(x_i)P'(x_j)}{n} \right]. \end{aligned} \tag{18}$$

We fix $(\gamma, \kappa) \in U$ and an initial condition $x_* \in C_{\gamma, \kappa}^n$ defined in (8). We denote by $\Psi_{x_*}^t$ the fundamental matrix of (18). Let $x(t) = \Phi^t(x_*)$ be the solution of (1) starting at x_* , and

$$\mu(t) := \frac{1}{n} \sum_{i=1}^n x_i(t), \quad \forall t \geq 0.$$

The main idea of the proof is to rewrite the linearized Winfree model by making a change of time $t \leftrightarrow s$ and a linear change of the tangent vectors $y \leftrightarrow z$. We first notice that the velocity of μ is strictly positive,

$$\begin{aligned} \frac{d\mu}{dt} &= \frac{1}{n} \sum_{i=1}^n \omega_i - \kappa \sigma(x) \frac{1}{n} \sum_{i=1}^n R(x_i), \\ &\geq (1 - \kappa \sigma(\mu)R(\mu)) - (\gamma + \kappa MD) \geq 1 - \kappa/\kappa_* - \gamma - \kappa MD > 0. \end{aligned}$$

The first inequality uses the definition of the constant M in (3), the estimates (2) on the

natural frequencies, the fact that $C_{\gamma,\kappa}^n$ is positively invariant, that $\Delta_{\gamma,\kappa}$ defined in (7) is bounded from above by D , and the simple estimate,

$$|x_i - \mu| \leq \Delta_{\gamma,\kappa}(\mu) \leq D, \quad \forall 1 \leq i \leq n,$$

$$\left| \sigma(\mu)R(\mu) - \frac{1}{n} \sum_{i=1}^n \sigma(x_i)R(x_i) \right| \leq \frac{M}{n} \sum_{i=1}^n |x_i - \mu| \leq MD.$$

The second inequality uses the definition of κ_* in (5) and the third inequality uses the bound from below (6). Let be $s_* := \mu(0)$. The map

$$t \in [0, +\infty) \mapsto \mu(t) \in [s_*, +\infty)$$

is a smooth diffeomorphism admitting as inverse map

$$s \in [s_*, +\infty) \mapsto \tau(s) \in [0, +\infty).$$

Define for $t = \tau(s) \Leftrightarrow s = \mu(t)$,

$$v(s) := \frac{d\mu}{dt}(t),$$

$$f_i(s) := \frac{\kappa \sigma(x(t))R'(x_i(t))}{v(s)}$$

$$f(s) := \max_{1 \leq i \leq n} f_i(s),$$

$$z_i(s) := y_i(t) \exp \left(\int_{s_*}^s f(u) du \right),$$

$$g_i(s) := f(s) - f_i(s),$$

$$p(s) := -\frac{\kappa P'(s)R(s)}{1 - \kappa P(s)R(s)},$$

$$q(s) := \frac{(1 - \kappa/\kappa_*)\alpha(\gamma, \kappa, D)}{1 - \kappa P(s)R(s)},$$

$$h_{i,j}(s) := -\frac{\kappa R(x_i(t))P'(x_j(t))}{v(s)} + \frac{\kappa P'(s)R(s)}{1 - \kappa P(s)R(s)}.$$

Lemma 3.1: *Then*

- (1) $dz_i/ds = g_i(s)z_i + (1/n) \sum_{j=1}^n (p(s) + h_{i,j}(s))z_j, \forall s \geq 0, \forall 1 \leq i \leq n,$
- (2) $\int_0^{2\pi} p(s) ds > 0,$
- (3) $p, q : \mathbb{R} \rightarrow \mathbb{R}$ are continuous and 2π -periodic,
- (4) $0 \leq g_i(s) \leq q(s)/4D, |h_{i,j}(s)| \leq q(s)/8D.$

Proof: Using the change of variable $\tilde{z}_i(s) = y_i \circ \tau(s)$, $\tilde{x}_i(s) = x_i \circ \tau(s)$, equation (18) becomes, $v(s) := d/dt\mu \circ \tau(s)$,

$$\begin{aligned} \frac{d\tilde{z}_i}{ds}(s) &= \frac{1}{v(s)} \frac{dy_i}{dt}(t) = -\frac{\kappa}{v(s)} \left(\sigma(\tilde{x})R'(\tilde{x}_i)\tilde{z}_i + \frac{1}{n} \sum_{j=1}^n R(\tilde{x}_i)P'(\tilde{x}_j)\tilde{z}_j \right), \\ &= -f_i(s)\tilde{z}_i + \frac{1}{n} \sum_{j=1}^n (p(s) + h_{i,j}(s))\tilde{z}_j \end{aligned}$$

Making the scaling $z_i(s) := \tilde{z}_i(s) \exp(\int_{s_*}^s f(u) du)$, one obtains item (1). Item (2) is a consequence of hypothesis (H) and

$$\begin{aligned} \frac{d}{ds} \log \left(\frac{1}{1 - \kappa P(s)R(s)} \right) &= p(s) - \frac{\kappa P(s)R'(s)}{1 - \kappa P(s)R(s)}, \\ \int_0^{2\pi} p(s) ds &= \int_0^{2\pi} \frac{\kappa P(s)R'(s)}{1 - \kappa P(s)R(s)} ds > 0. \end{aligned}$$

Item (3) is true by definition of p and q . Using $|\tilde{x}_i(s) - s| \leq D$, the estimate on $h_{i,j}$ is given by

$$\begin{aligned} |h_{i,j}(s)| &\leq \frac{\kappa |R(s)P'(s) - R(\tilde{x}_i)P'(\tilde{x}_i)|}{1 - \kappa P(s)R(s)} \\ &\quad + \frac{\kappa |R(\tilde{x}_i)| |P'(\tilde{x}_i)| |v(s) - (1 - \kappa P(s)R(s))|}{v(s)(1 - \kappa P(s)R(s))} \\ &\leq \frac{\kappa M}{8(1 - \kappa P(s)R(s))} \left[D + \frac{\gamma + \kappa MD}{1 - \kappa/\kappa_* - \gamma - \kappa MD} \right] \\ &\leq \frac{\alpha(\gamma, \kappa, D)}{8D} \frac{1 - \kappa/\kappa_*}{1 - \kappa P(s)R(s)} = \frac{q(s)}{8D}. \end{aligned}$$

The estimate on g_i is given by

$$\begin{aligned} g_i(s) &\leq \max_{1 \leq i,j \leq n} \frac{\kappa |\sigma(\tilde{x})| |R'(\tilde{x}_i) - R'(\tilde{x}_j)|}{v(s)} \\ &\leq \frac{\kappa MD}{4(1 - \kappa P(s)R(s))} + \frac{\kappa MD(1 - \kappa P(s)R(s) - v(s))}{4v(s)(1 - \kappa P(s)R(s))} \\ &\leq \frac{\kappa MD}{4(1 - \kappa P(s)R(s))} \left[1 + \frac{\gamma + \kappa MD}{1 - \kappa/\kappa_* - \gamma - \kappa MD} \right] \leq \frac{q(s)}{4D}. \quad \blacksquare \end{aligned}$$

We now conclude the proof of the main results: we will show that V_+ is Ψ_x^t -positively invariant uniformly in $C_{\gamma,\kappa}^n$; proposition 2.3 will imply that the Winfree model is Φ^t -positively stable uniformly on $C_{\gamma,\kappa}^n$.

The fact that V_+ is positively invariant is a direct consequence of Proposition 2.5 applied to the linearized Winfree model written in terms of the new variables $z(s) = (z_1(s), \dots, z_n(s))$. Part of the hypotheses of Proposition 2.5 have been proved in Lemma 3.1. We prove in the following lemma the remaining hypothesis.

Lemma 3.2: *There exists a continuous 2π -periodic function $\delta : \mathbb{R} \rightarrow (0, D)$ such that*

$$\frac{d\delta}{ds} = -p(s)\delta + q(s), \quad \forall s \geq 0.$$

Proof: Let $\Delta_{\gamma, \kappa}(s)$ be the positive 2π -periodic function as in (7). Define

$$\delta(s) := \frac{1 - \kappa/\kappa_*}{1 - \kappa P(s)R(s)} \Delta_{\gamma, \kappa}(s).$$

Then $\delta \leq \Delta_{\gamma, \kappa} < D$, and

$$\begin{aligned} \frac{d\delta}{ds} &= \frac{(1 - \kappa/\kappa_*)\kappa(P'(s)R(s) + P(s)R'(s))}{(1 - \kappa P(s)R(s))^2} \Delta_{\gamma, \kappa} + \frac{1 - \kappa/\kappa_*}{1 - \kappa P(s)R(s)} \frac{d\Delta_{\gamma, \kappa}}{ds}, \\ &= \frac{\kappa P'(s)R(s)}{1 - \kappa P(s)R(s)} \delta + \frac{(1 - \kappa/\kappa_*)\alpha(\gamma, \kappa, D)}{1 - \kappa P(s)R(s)} = -p(s)\delta + q(s). \quad \blacksquare \end{aligned}$$

4. Conclusion

We studied the stability of the Winfree model in its synchronized state. The proof is based on the positive invariant cone method. The main synchronization hypothesis used in [5] is again a critical hypothesis for the linear stability.

Acknowledgements

We would like to thank the referee for his/her precise remarks and corrections that helped us to improve the final text.

Disclosure statement

No potential conflict of interest was reported by the authors.

ORCID

W. Oukil  <http://orcid.org/0000-0002-1851-1496>

References

- [1] J.T. Ariaratnam and S.H. Strogatz, *Phase diagram for the Winfree model of coupled nonlinear oscillators*, Phys. Rev. Lett. 86 (2001), pp. 4278.
- [2] D. Cumin and C.P. Unsworth, *Generalising the Kuramoto model for the study of neuronal synchronization in the brain*, Phys. D: Nonlinear Phenom. 226(2) (2007), pp. 181–196.
- [3] G.B. Ermentrout, M. Pascal, and B.S. Gutkin, *The effects of spike frequency adaptation and negative feedback on the synchronization of neural oscillators*, Neural. Comput. 13(6) (2001), pp. 1285–1310.
- [4] A.M. Fink, *Almost Periodic Differential Equations*. Lecture Notes in Mathematics 377, Springer-Verlag, Springer, Berlin, 1974.
- [5] W. Oukil, A. Kessi, and Ph. Thieullen, *Synchronization hypothesis in the Winfree model*, Dyn. Syst. 32(3) (2017), pp. 326–339. Taylor & Francis.

- [6] T. Saito, *On dynamical systems in n -dimensional torus*. Proceedings of the Symposium on Differential Equations and Dynamical Systems, Lecture Notes in Mathematics Vol. 206, 1971, pp. 18–19.
- [7] D.D. Quinn, R.H. Rand, and S.H. Strogatz, *Singular unlocking transition in the Winfree model of coupled oscillators*. Phys. Rev. E 75 (2007), pp. 036218.
- [8] A.T. Winfree, *Biological rhythms and the behavior of populations of coupled oscillators*, J. Theor. Biol. 16 (1967), pp. 15–42.