

Learning Nonexpansive Operators

Mathematical Models for Plug-and-Play Image Restoration

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The denoising problem

Original



Noisy image



Denoised image



Figure: Denoising process with the ROF model¹. Source: Wikipedia

Inverse problems

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$$z = \arg \min_{y \in \mathcal{X}} \frac{1}{2} \|y - x\|^2 + R(y) =: \text{prox}_R(x).$$

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Theorem. Let $T : \mathcal{X} \rightarrow \mathcal{X}$ be a firmly nonexpansive operator such that $\text{Fix } T \neq \emptyset$. Let $x_0 \in \mathcal{X}$ and set

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↪ $\text{prox}_R, R \in \Gamma_0(X)$, is firmly nonexpansive + “firmly nonexpansive \Leftrightarrow nonexpansive.”

Nonexpansive operators

Recall: N nonexpansive if, for every $x, x' \in X$, we have $\|N(x) - N(x')\| \leq \|x - x'\|$.

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Consider $\{(\bar{x}_i, \bar{y}_i)\}_{i=1}^n$ set of noisy/clean pairs. We want to solve:

$$\hat{N} \in \arg \min_{N \in \mathcal{N}} \frac{1}{n} \sum_{i=1}^n \|N(\bar{x}_i) - \bar{y}_i\|^2. \quad (\text{EP})$$

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\rightsquigarrow We propose a “piecewise affine” version of (EP).

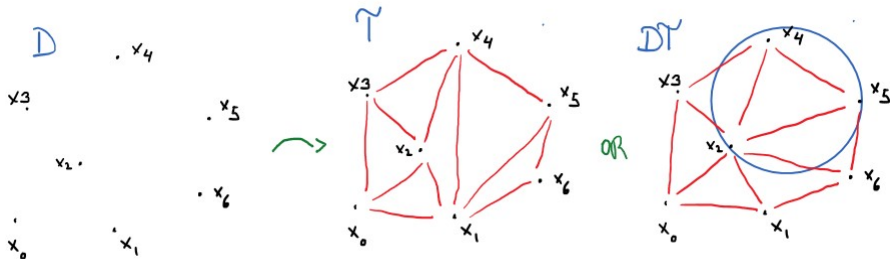
What do we mean with piecewise affine?

Step 1. Given $D := \{x_i\}_{i=1}^m$, $x_i \in \mathbb{R}^d$, we want to consider a “good” simplicial partition \mathfrak{T} of $\text{conv}(D)$;

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- (P1) Every simplex has nonempty interior;
- (P2) the intersection of every two simplexes has to be, either empty, or coincide with the convex envelope of its common vertices.



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$$x = \sum_{i=0}^d \lambda_i x_i \quad \rightsquigarrow \quad N : \text{conv}(D) \rightarrow \mathbb{R}^d; \quad N(x) := \sum_{i=0}^d \lambda_i N(x_i),$$

being $N(x_i) := y_i$, for a given set $\{y_i\}_{i=1}^m$.

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Define

$$\text{PA}(\mathfrak{T}) := \left\{ N : \text{conv}(D) \rightarrow \mathbb{R}^d : N(x) := \sum_{i=0}^d \lambda_i N(x_i) \right\}.$$

The piecewise affine problem

Our piecewise affine problem:

$$\min_{N \in \mathcal{N} \cap \text{PA}(\mathfrak{T})} \frac{1}{n} \sum_{i=1}^n \|N(\bar{x}_i) - \bar{y}_i\|^2. \quad (\text{PAP})$$

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Some observations:

- ▶ (PAP) is not a computational-friendly formulation.
- ▶ Can we find a condition in $\{(\bar{x}_i, N(\bar{x}_i))\}_{i=1}^n$ so that the extended operator (in the piecewise affine sense) is 1-Lipschitz?

Seeking for a condition

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$$N(x) := \sum_{i=1}^n \lambda_i y_i = BA^{-1}(x - x_0) + y_0,$$

where $A = (x_1 - x_0 \mid \dots \mid x_d - x_0)$, and $B = (y_1 - y_0 \mid \dots \mid y_d - y_0)$.

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Theorem

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$$\begin{aligned} \min_{y_1, \dots, y_m} \quad & \frac{1}{n} \sum_{i=1}^n \|y_i - \bar{y}_i\|^2 \\ \text{s.t.} \quad & \|B(y_1, \dots, y_m)A^{-1}\| \leq 1, \text{ for every simplex.} \end{aligned} \tag{FP}$$

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Then,

Theorem

Problems (FP) and (PAP) are equivalent.

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Can we prove that, in some sense, that (PAP) converges to (EP) at least in $\text{conv}(D)$?

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there exists a subsequence $\{k_j\}_{j=1}^\infty$ such that $\hat{N}_{k_j} \xrightarrow{*} \hat{N}$, being

$$\hat{N} \in \arg \min_{N \in \mathcal{N}} \frac{1}{n} \sum_{i=1}^n \|N(\bar{x}_i) - \bar{y}_i\|^2.$$

Experiments

In practice, we search for

$$\arg \min_{x \in \mathbb{R}^{n \times n}} \frac{1}{2\alpha} \|x - y\|^2 + G(Dx),$$

where $(Dx)_i = (x_{i+1,j} - x_{i,j}, x_{i,j+1} - x_{i,j})$, $i = 1, \dots, n^2$. To solve the dimensionality problem of simplicial partitions, we suppose G is of the form

$$G(v) = \sum_{i=1}^{n^2} G_i(v_i), \quad \text{for every } v \in \mathbb{R}^{n^2 \times 2},$$

where $G_i : \mathbb{R}^2 \rightarrow (-\infty, +\infty]$. With this, we learn $\text{prox}_{G_i} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$.

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Example: If $G = \|\cdot\|^2$, $\|Dx\|^2 = \sum_{i=1}^{n^2} \|(Dx)_i\|^2$ and so

$$\text{prox}_{\|\cdot\|^2}(x_1, \dots, x_{n^2}) = (\text{prox}_{\|\cdot\|^2}(x_1), \dots, \text{prox}_{\|\cdot\|^2}(x_{n^2})).$$

Some pictures

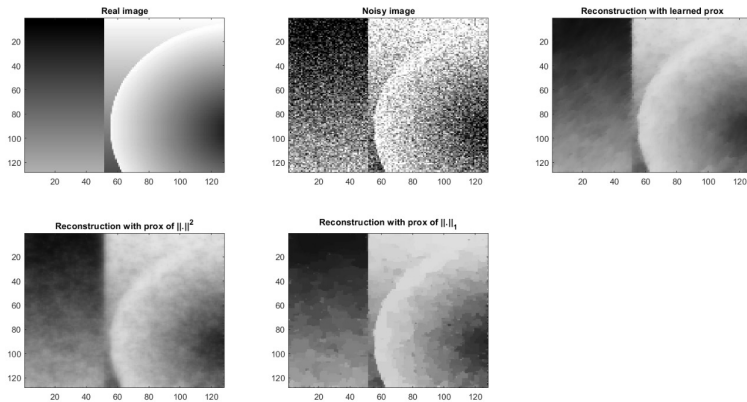


Figure: Classic regularizers compared to ours.

Conclusions

- ▶ We provide a constructive method to learn **nonexpansive** (and therefore also firmly nonexpansive) operators,
- ▶ classic optim. algorithms such as Chambolle–Pock, Douglas–Rachford, Forward-Backward Splitting or ADMM have their corresponding convergent PnP version,
- ▶ we prove that the approximate problem that we define converges to the original empirical one,
- ▶ preprint will be soon (I hope) on arXiv!

¡Muchas gracias!

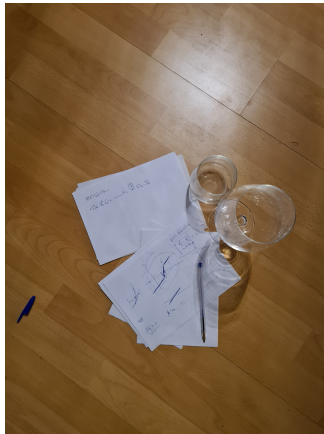


Figure: vino y teoremas