

General boundary conditions for the Boussinesq-Abbott model with varying bathymetry

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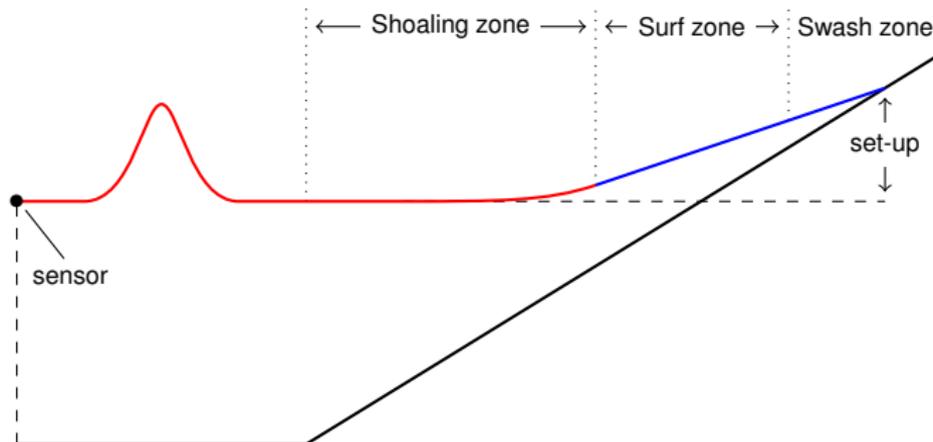
Supervision : David Lannes and Philippe Bonneton

Long term goal: study extreme waves in littoral area



- Need accurate dispersive model: **Boussinesq-type systems**
- Boundary conditions are difficult to deal with

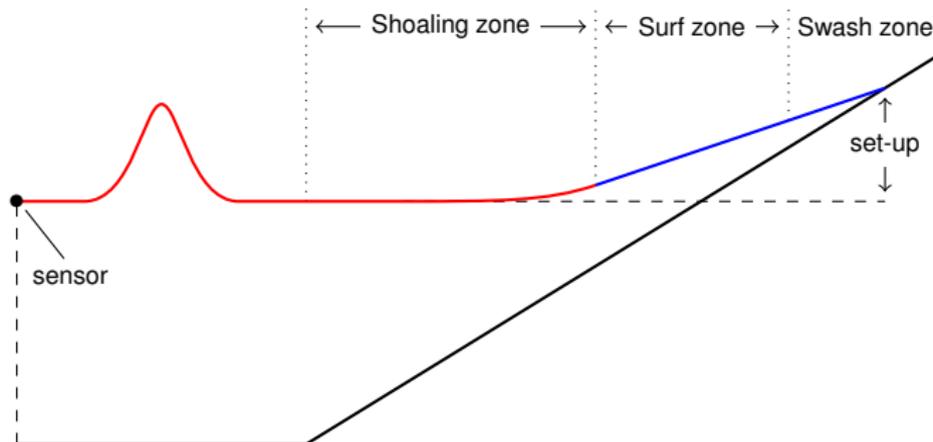
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- Need accurate dispersive model: **Boussinesq-type systems**
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Recently: Perfectly Matched Layer, source function method → costly

→ We propose a new and efficient method for boundary conditions.



Consider the Boussinesq-Abbott system

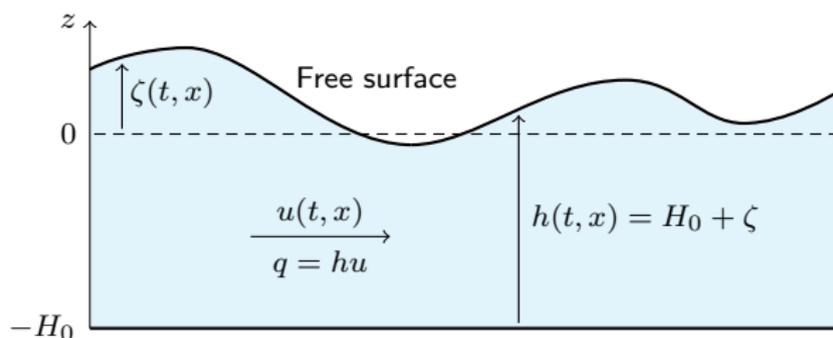
$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ (1 - \kappa^2 \partial_{xx}^2) \partial_t q + \partial_x f_{\text{NSW}}(\zeta, q) = 0 \end{cases} \quad \text{in } (0, \ell) \quad (\text{BA})$$

with *generating boundary conditions*

$$\zeta(t, 0) = g_0(t), \quad \zeta(t, \ell) = g_\ell(t), \quad (1)$$

where $g_0, g_\ell \in C(0, T)$ and

$$\kappa^2 = H_0^2/3, \quad f_{\text{NSW}}(\zeta, q) = \frac{q^2}{h} + \frac{g}{2} h^2$$



How to account for boundary conditions? How to recover $q|_{x=0,\ell}$?

- Hyperbolic case ($\kappa = 0$) : Riemann invariants
- Dispersive case ($\kappa > 0$) : need to invert $(1 - \kappa^2 \partial_{xx}^2)$ → requires knowledge on $\partial_t q|_{x=0,\ell}$

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Lannes and Weynans 2020

Equivalent writing of Boussinesq-Abbott with flat bottom over $(0, \infty)$

- substitute $(1 - \kappa^2 \partial_{xx}^2)$ for nonlocal flux & dispersive boundary layer
- ODE on $q|_{x=0}$
- local existence and unicity
- 1st order scheme

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Lannes and Beck 2022

Extension to wave-structure interactions

- transmission problem → ODE
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Outline of the talk

- 1 Reformulation over bounded domain
- 2 General boundary cond. & scheme
- 3 Varying bathymetry
- 4 Some perspectives

Reformulation of the model (flat bottom)

Recall the discharge equation:

$$(1 - \kappa^2 \partial_{xx}^2) \partial_t q + \partial_x f_{\text{NSW}}(\zeta, q) = 0 \quad \text{in } (0, \ell)$$

Fix $0 \leq t \leq T$, then $y(x) = \partial_t q(t, x)$ satisfies an ODE of the form

$$\begin{cases} y - \kappa^2 y'' = \phi(x) \\ y(0) = \dot{q}_{l_0}, \quad y(\ell) = \dot{q}_{l_\ell} \end{cases}$$

Equivalently: $y = y_h + y_b$ with $\begin{cases} y_h - \kappa^2 y_h'' = 0 \\ y_h(0) = \dot{q}_{l_0}, \quad y_h(\ell) = \dot{q}_{l_\ell} \end{cases}$ and $\begin{cases} y_b - \kappa^2 y_b'' = \phi(x) \\ y_b(0) = y_b(\ell) = 0 \end{cases}$

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Define R^0 as the inverse of $(1 - \kappa^2 \partial_{xx}^2)$ with **homogeneous Dirichlet** conditions at $x = 0, \ell$

$$\Rightarrow \partial_t q = \underbrace{-R^0 \partial_x f_{NSW}}_{y_b} + \underbrace{s_{(0)} \dot{q}_{l_0} + s_{(\ell)} \dot{q}_{l_\ell}}_{y_h}$$

where $\begin{cases} (1 - \kappa^2 \partial_{xx}^2) s_{(0)} = 0 \\ s_{(0)}(0) = 1, \quad s_{(0)}(\ell) = 0 \end{cases}$ and $\begin{cases} (1 - \kappa^2 \partial_{xx}^2) s_{(\ell)} = 0 \\ s_{(\ell)}(0) = 0, \quad s_{(\ell)}(\ell) = 1 \end{cases}$. (2)

Reformulation of the model (flat bottom)

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Proposition 1 (D. Lannes, R.)

Let (ζ, q) initially equal to $(\zeta^{\text{in}}, q^{\text{in}})$. The two assertions are equivalent:

- 1 The pair (ζ, q) satisfies (BA) with generating conditions $\zeta(\cdot, 0) = g_0$ and $\zeta(\cdot, \ell) = g_\ell$
- 2 The pair (ζ, q) satisfies

$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ \partial_t q + \partial_x (R^1 f_{\text{NSW}}) = s_{(0)} \dot{q}_{|_0} + s_{(\ell)} \dot{q}_{|\ell} \end{cases} \quad \text{in } (0, \ell), \quad (3)$$

with the trace ODEs

$$\begin{pmatrix} s'_{(0)}(0) & s'_{(\ell)}(0) \\ s'_{(0)}(\ell) & s'_{(\ell)}(\ell) \end{pmatrix} \begin{pmatrix} \dot{q}_{|_0} \\ \dot{q}_{|\ell} \end{pmatrix} = \frac{1}{\kappa^2} \begin{pmatrix} (R^1 - \text{id})_{|_0} f_{\text{NSW}} \\ (R^1 - \text{id})_{|\ell} f_{\text{NSW}} \end{pmatrix} - \begin{pmatrix} \ddot{g}_0 \\ \ddot{g}_\ell \end{pmatrix} \quad (4)$$

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Sketch of the proof:

- To get (3), check that $R^0 \partial_x = \partial_x R^1$.
- Apply ∂_x to the discharge eq. from (3); take the trace at $x = 0, \ell$ to get (4).

$$\underbrace{\partial_{xt}^2 q}_{-\partial_{tt}^2 \zeta} + \underbrace{(\partial_{xx} R^1 f_{\text{NSW}})}_{\frac{1}{\kappa^2} (R^1 - \text{id}) f_{\text{NSW}}} = s'_{(0)} \dot{q}_0 + s'_{(\ell)} \dot{q}_\ell$$

Advantages of the reformulated model

- Furnishes evolution equation on $(q_{|_0}, q_{|\ell})$
- Under some assumptions[†] and denoting $\mathcal{S} = H^n(0, \ell) \times H^{n+1}(0, \ell)$ for $n \geq 1$:
 - If $(\zeta^{\text{in}}, q^{\text{in}}) \in \mathcal{S}$, reformulated model can be seen as an ODE on $(\zeta, q, q_{|_0}, q_{|\ell})(t) \in \mathcal{S} \times \mathbb{R}^2$
 - Local existence and uniqueness by Cauchy-Lipschitz theorem

[†] Assumptions for well-posedness:

$$h_{|_{t=0}} > 0; \quad g_0, g_\ell \in C^\infty(\mathbb{R}_+); \quad \begin{cases} \zeta_{|_{t=0}}(0) = g_0(0), \\ \dot{g}_0(0) + \partial_x q^{\text{in}}(0) = 0 \end{cases} \quad \text{and} \quad \begin{cases} \zeta_{|_{t=0}}(\ell) = g_\ell(0), \\ \dot{g}_\ell(0) + \partial_x q^{\text{in}}(\ell) = 0 \end{cases}$$

Possibility to enforce general boundary conditions

$$\xi_0^+(\zeta_0, q_0)(t) = g_0(t), \quad \xi_\ell^-(\zeta_\ell, q_\ell)(t) = g_\ell(t). \quad (5)$$

For instance, ξ^\pm given by q or Saint-Venant Riemann invariants

$$\mathcal{R}_\pm(U) = u \pm 2\sqrt{gh}$$

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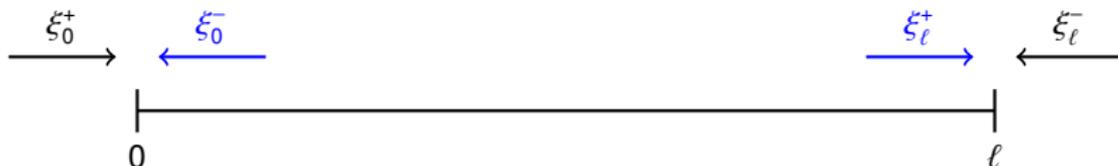
$$\xi_0^+(\zeta_{l_0}, \mathbf{q}_{l_0})(t) = g_0(t), \quad \xi_\ell^-(\zeta_{l_\ell}, \mathbf{q}_{l_\ell})(t) = g_\ell(t). \quad (5)$$

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Adapt trace ODE in terms of **missing data (outgoing information ξ_0^- and ξ_ℓ^+)**

$$\begin{pmatrix} s'_{(0)}(0) & s'_{(\ell)}(0) \\ s'_{(0)}(\ell) & s'_{(\ell)}(\ell) \end{pmatrix} \frac{d}{dt} \begin{pmatrix} q(\xi_0^+, \xi_0^-) \\ q(\xi_\ell^+, \xi_\ell^-) \end{pmatrix} = \frac{1}{\kappa^2} \begin{pmatrix} (R^1 - \text{id})_{l_0} f_{\text{NSW}} \\ (R^1 - \text{id})_{l_\ell} f_{\text{NSW}} \end{pmatrix} - \frac{d^2}{dt^2} \begin{pmatrix} \zeta(\xi_0^+, \xi_0^-) \\ \zeta(\xi_\ell^+, \xi_\ell^-) \end{pmatrix}$$



Introduce smooth reconstruction maps $\mathcal{H}_0, \mathcal{H}_\ell$:

$$\begin{cases} \mathcal{H}_0(\xi_0^+(\zeta, q), \xi_0^-(\zeta, q)) = (\zeta, q) \\ \mathcal{H}_\ell(\xi_\ell^+(\zeta, q), \xi_\ell^-(\zeta, q)) = (\zeta, q) \end{cases}$$

Use chain rule to rewrite trace ODEs in term of (ξ_0^-, ξ_ℓ^+) :

$$\frac{d}{dt} \begin{pmatrix} q_{|_0} \\ q_{|\ell} \end{pmatrix} = \frac{d}{dt} \begin{pmatrix} \mathcal{H}_{0,2}(g_0, \xi_0^-) \\ \mathcal{H}_{\ell,2}(\xi_\ell^+, g_\ell) \end{pmatrix}, \quad \frac{d^2}{dt^2} \begin{pmatrix} \zeta_{|_0} \\ \zeta_{|\ell} \end{pmatrix} = \frac{d^2}{dt^2} \begin{pmatrix} \mathcal{H}_{0,1}(g_0, \xi_0^-) \\ \mathcal{H}_{\ell,1}(\xi_\ell^+, g_\ell) \end{pmatrix}$$

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Three cases considered here:

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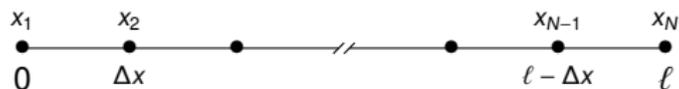
$$\xi_0^+(\zeta, q) = \xi_\ell^-(\zeta, q) = q, \quad \xi_0^-(\zeta, q) = \xi_\ell^+(\zeta, q) = \zeta.$$

- 3 Incoming Riemann invariant enforced

$$\xi_0^+(\zeta, q) = \xi_\ell^+(\zeta, q) = u + 2\sqrt{gh}, \quad \xi_0^-(\zeta, q) = \xi_\ell^-(\zeta, q) = u - 2\sqrt{gh}.$$

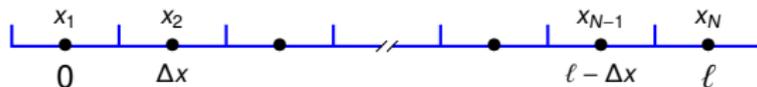
Numerical schemes for the reformulated system

Discretize $(0, \ell)$ as follows:



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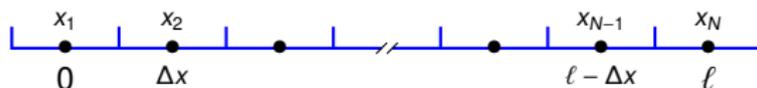
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Note $U_i^n = (\zeta_i^n, q_i^n)^T$ the approximation of $\frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \begin{pmatrix} \zeta \\ q \end{pmatrix} (t^n, s) ds$.

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Time stepping procedure

Step 1: Define $\underline{R}_{\text{NSW}}^1$ as the vector $v \in \mathbb{R}^N$ satisfying

$$\begin{cases} v_i - \kappa^2 \frac{v_{i+1} - 2v_i + v_{i-1}}{\Delta x^2} = f_{\text{NSW}}(U_i^n) & \text{for } 2 \leq i \leq N-1 \\ \frac{v_2 - v_1}{\Delta x} = \frac{v_N - v_{N-1}}{\Delta x} = 0 \end{cases}$$

Similar definition for boundary layer functions $\underline{s}_{(0)}$ and $\underline{s}_{(\ell)}$.

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$$(\zeta_1^{n+1}, q_1^{n+1}) = \mathcal{H}_0(g_0^{n+1}, (\xi_0^-)^{n+1}); \quad (\zeta_N^{n+1}, q_N^{n+1}) = \mathcal{H}_\ell((\xi_\ell^+)^{n+1}, g_\ell^{n+1})$$

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Step 4: For $2 \leq i \leq N$, finite volumes update with Lax-Friedrichs numerical flux

$$\begin{cases} \frac{\zeta_i^{n+1} - \zeta_i^n}{\Delta t} + \frac{1}{\Delta x} (q_{i+1/2}^n - q_{i-1/2}^n) = 0 \\ \frac{q_i^{n+1} - q_i^n}{\Delta t} + \frac{1}{\Delta x} ((\underline{R}^1 f_{\text{NSW}}^n)_{i+1/2} - (\underline{R}^1 f_{\text{NSW}}^n)_{i-1/2}) = (\bar{s}_{(0)})_i \delta_t q_1^n + (\bar{s}_{(\ell)})_i \delta_t q_N^n \end{cases}$$

Second order extension: MacCormack prediction-correction method

Beck, Lannes, Weynans (preprint 2023)

- left upwinding during prediction
- right upwinding during correction
- final stage: average prediction and correction (similar to Heun)

Adapt to finite domain $(0, \ell)$ + general boundary conditions

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Solitary wave testcase: wave travelling without deforming

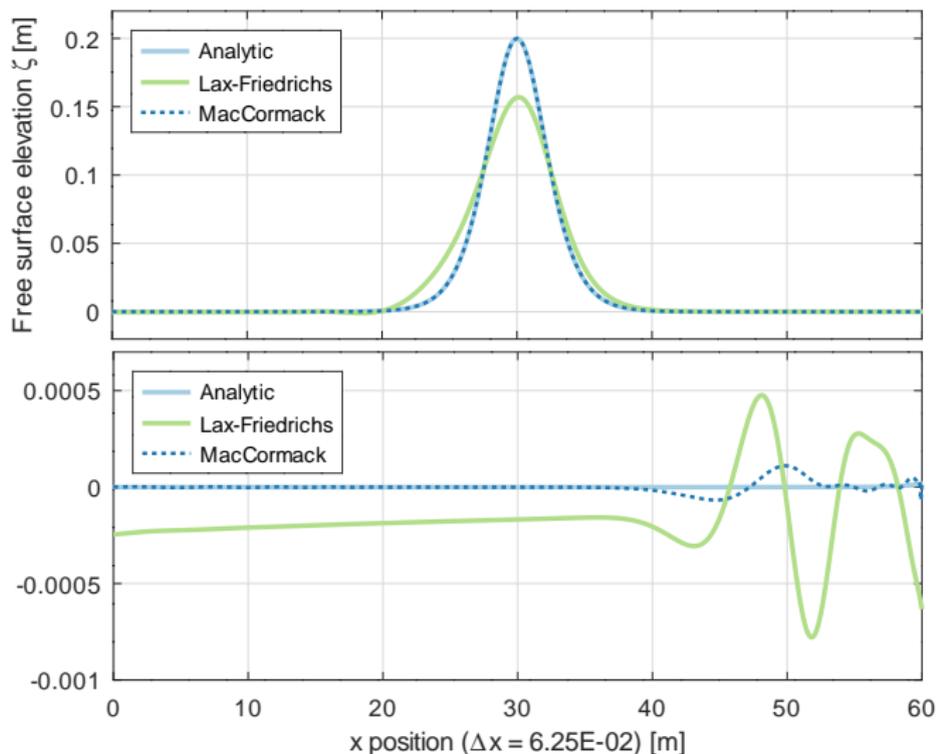
$$\zeta(t, x) = \tilde{\zeta}(x - ct), \quad q(t, x) = \tilde{q}(x - ct)$$

Compare different boundary conditions in two settings:

- 1 Generation of an incoming solitary wave
- 2 Evacuation of a solitary wave initially in the domain

→ no sponge layer shall be used

Figure: Top: incoming solitary wave, bottom: outgoing solitary wave



Δx	ζ enforced		q enforced		R^\pm enforced	
	L^2 -error	Order	L^2 -error	Order	L^2 -error	Order
6.25E-02	3.263E-03	–	3.484E-03	–	3.312E-03	–
4.42E-02	2.387E-03	0.90	2.539E-03	0.91	2.420E-03	0.91
3.12E-02	1.727E-03	0.93	1.833E-03	0.94	1.750E-03	0.93
2.21E-02	1.244E-03	0.95	1.318E-03	0.95	1.260E-03	0.95
1.56E-02	8.906E-04	0.97	9.411E-04	0.97	9.015E-04	0.97

Table: Lax-Friedrichs scheme for the incoming solitary wave

Solitary wave testcase

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3.12E-02	1.322E-03	0.87	1.514E-03	0.85	8.401E-05	0.70
2.21E-02	9.725E-04	0.89	1.119E-03	0.87	6.503E-05	0.74
1.56E-02	7.053E-04	0.93	8.145E-04	0.92	4.939E-05	0.79
1.11E-02	5.098E-04	0.94	5.903E-04	0.93	3.711E-05	0.83

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Solitary wave testcase

Δx	ζ enforced		q enforced		R^\pm enforced	
	L^2 -error	Order	L^2 -error	Order	L^2 -error	Order
5.00E-01	2.473E-03	–	3.789E-03	–	2.783E-03	–
2.50E-01	6.670E-04	1.89	1.026E-03	1.89	7.199E-04	1.95
1.25E-01	1.696E-04	1.98	2.662E-04	1.95	1.832E-04	1.97
6.25E-02	4.312E-05	1.98	6.804E-05	1.97	4.624E-05	1.99
3.12E-02	1.107E-05	1.96	1.731E-05	1.97	1.162E-05	1.99

Table: MacCormack scheme for the incoming solitary wave.

Solitary wave testcase

Δx	ζ enforced		q enforced		R^\pm enforced	
	L^2 -error	Order	L^2 -error	Order	L^2 -error	Order
5.00E-01	2.473E-03	–	3.789E-03	–	2.783E-03	–
2.50E-01	6.670E-04	1.89	1.026E-03	1.89	7.199E-04	1.95
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Table: MacCormack scheme for the incoming solitary wave.

Δx	ζ enforced		q enforced		R^\pm enforced	
	L^2 -error	Order	L^2 -error	Order	L^2 -error	Order
5.00E-01	1.885E-03	–	4.437E-03	–	1.993E-03	–
2.50E-01	5.568E-04	1.76	1.257E-03	1.82	5.607E-04	1.83
1.25E-01	1.459E-04	1.93	3.252E-04	1.95	1.318E-04	2.09
6.25E-02	3.674E-05	1.99	8.223E-05	1.98	2.826E-05	2.22
3.12E-02	9.162E-06	2.00	2.067E-05	1.99	7.085E-06	2.00

Table: MacCormack scheme for the outgoing solitary wave.

Boussinesq-Abbott system with varying bottom

The Boussinesq-Abbott system now reads

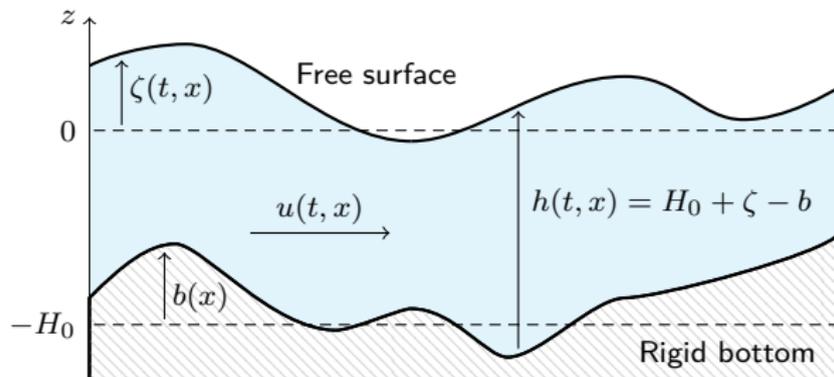
$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ (1 + h_b \mathcal{T}_b) \partial_t q + \partial_x f_{\text{NSW}} = -gh \partial_x b \end{cases} \quad \text{in } (0, \ell), \quad (\text{BA})$$

under generating boundary conditions

$$\zeta(t, 0) = g_0(t), \quad \zeta(t, \ell) = g_\ell(t),$$

with $h_b = H_0 - b$ (depth at rest) and

$$\mathcal{T}_b(\cdot) = -\frac{1}{3h_b} \partial_x \left(h_b^3 \partial_x \frac{(\cdot)}{h_b} \right) + \frac{(\cdot)}{2} \partial_{xx}^2 b, \quad (6)$$



Recall of the main problematic

To invert $(1 + h_b \mathcal{T}_b)$, we need knowledge on $(\dot{q}_{l_0}, \dot{q}_{l_\ell})$

- Extend nonlocal reformulation to varying bottoms
- Obtain trace ODEs for missing data (q_{l_0}, q_{l_ℓ})

Recall of the main problematic

To invert $(1 + h_b \mathcal{T}_b)$, we need knowledge on $(\dot{q}|_0, \dot{q}|_\ell)$

- Extend nonlocal reformulation to varying bottoms
- Obtain trace ODEs for missing data $(q|_0, q|_\ell)$

Version adapted to well-balancedness

Lake at rest $(\zeta, q) = (0, 0)$ is a steady state $\Rightarrow \partial_x f_{\text{NSW}}(0, 0) = -gh_b \partial_x b$

$$(BA) \Leftrightarrow \begin{cases} \partial_t \zeta + \partial_x q = 0 \\ (1 + h_b \mathcal{T}_b) \partial_t q + \partial_x \left(\underbrace{f_{\text{NSW}}(\zeta, q) - f_{\text{NSW}}(0, 0)}_{\tilde{f}_{\text{NSW}}(\zeta, q)} \right) = -g \underbrace{(h - h_b)}_{\zeta} \partial_x b \end{cases} \quad \text{in } (0, \ell),$$

$$\tilde{f}_{\text{NSW}}(\zeta, q) = \frac{q^2}{h} + \frac{g}{2} (\zeta^2 + 2H_0 \zeta) \quad \zeta$$

- we have $\tilde{f}_{\text{NSW}}(\zeta, q) = -g\zeta \partial_x b = 0$ if $(\zeta, q) = (0, 0)$
- easy to preserve at discrete level \rightarrow scheme naturally well-balanced
- advantage: can be generalized to other steady states

Note R_b^0 the inverse of $(1 + h_b \mathcal{T}_b)$ with **homogeneous Dirichlet** conditions at $x = 0, \ell$

$$\Rightarrow \partial_t \mathbf{q} = -R_b^0 \partial_x \widetilde{f}_{\text{NSW}} + R_b^0 (-g \zeta \partial_x b) + \mathfrak{s}_{(b,0)} \dot{\mathbf{q}}|_0 + \mathfrak{s}_{(b,\ell)} \dot{\mathbf{q}}|_\ell \quad (7)$$

where $\left\{ \begin{array}{l} (1 + h_b \mathcal{T}_b) \mathfrak{s}_{(b,0)} = 0 \\ \mathfrak{s}_{(b,0)}(0) = 1, \quad \mathfrak{s}_{(b,0)}(\ell) = 0 \end{array} \right.$ and $\left\{ \begin{array}{l} (1 + h_b \mathcal{T}_b) \mathfrak{s}_{(b,\ell)} = 0 \\ \mathfrak{s}_{(b,\ell)}(0) = 0, \quad \mathfrak{s}_{(b,\ell)}(\ell) = 1 \end{array} \right.$.

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Lemma 1 (generalization of $R^0 \partial_x = \partial_x R^1$)

We can construct a nonlocal operator R_b^1 such that

$$R_b^0 \partial_x (\cdot) = \left(\partial_x + \beta + \frac{\partial_x \alpha}{\alpha} \right) \left[\frac{h_b^2}{\alpha} R_b^1 \left(\frac{(\cdot)}{h_b^2} \right) \right] - R_b^0 ((\cdot) \beta) \quad \text{with} \quad \begin{cases} h_b = H_0 - b \\ \alpha = 1 + \frac{1}{4} (\partial_x b)^2 \\ \beta = \frac{3}{2} h_b^{-1} \partial_x b \end{cases}$$

Note R_b^0 the inverse of $(1 + h_b \mathcal{T}_b)$ with **homogeneous Dirichlet** conditions at $x = 0, \ell$

$$\Rightarrow \partial_t q = -R_b^0 \partial_x \tilde{f}_{\text{NSW}} + R_b^0 (-g \zeta \partial_x b) + \mathfrak{s}_{(b,0)} \dot{q}|_0 + \mathfrak{s}_{(b,\ell)} \dot{q}|_\ell \quad (7)$$

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Definition 1 (Nonlocal flux and source terms)

$$\mathfrak{f} = \frac{h_b^2}{\alpha} R_b^1 \left(\frac{\tilde{f}_{\text{NSW}}}{h_b^2} \right), \quad \mathfrak{B} = R_b^0 \left(-gh \partial_x b + \beta \tilde{f}_{\text{NSW}} \right) - \left(\beta + \frac{\partial_x \alpha}{\alpha} \right) \mathfrak{f}$$

Proposition 2 (D. Lannes, R.)

Let (ζ, q) initially equal to $(\zeta^{\text{in}}, q^{\text{in}}) \in H^n(0, \ell) \times H^{n+1}(0, \ell)$. The two assertions are equivalent:

- 1 The pair (ζ, q) satisfies (BA) with generating conditions $\zeta(\cdot, 0) = g_0$ and $\zeta(\cdot, \ell) = g_\ell$
- 2 The pair (ζ, q) satisfies

$$\begin{cases} \partial_t \zeta + \partial_x q = 0, \\ \partial_t q + \partial_x \mathfrak{f}(\zeta, q) = \mathfrak{B}(\zeta, q) + \mathfrak{s}_{(b,0)} \dot{q}_{l_0} + \mathfrak{s}_{(b,\ell)} \dot{q}_{l_\ell} \end{cases} \quad \text{in } (0, \ell) \quad (8)$$

and the trace equations

$$\begin{pmatrix} \mathfrak{s}'_{(b,0)}(0) & \mathfrak{s}'_{(b,\ell)}(0) \\ \mathfrak{s}'_{(b,0)}(\ell) & \mathfrak{s}'_{(b,\ell)}(\ell) \end{pmatrix} \frac{d}{dt} \begin{pmatrix} q_{l_0} \\ q_{l_\ell} \end{pmatrix} = \begin{pmatrix} \mathcal{F}_0(\zeta, q, \zeta_{l_0}, q_{l_0}) \\ \mathcal{F}_\ell(\zeta, q, \zeta_{l_\ell}, q_{l_\ell}) \end{pmatrix} - \frac{d^2}{dt^2} \begin{pmatrix} \zeta_{l_0} \\ \zeta_{l_\ell} \end{pmatrix} \quad (9)$$

where $\mathcal{F}_0, \mathcal{F}_\ell : H^n(0, \ell) \times H^{n+1}(0, \ell) \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are known.

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where $\mathcal{F}_0, \mathcal{F}_\ell : H^n(0, \ell) \times H^{n+1}(0, \ell) \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are known.

- Can be adapted to general boundary conditions $(\xi_0^+, \xi_\ell^-) = (g_0, g_\ell)$
- Local existence and unicity by Cauchy-Lipschitz
- Numerical discretization same as before

Setup:

- Reference solution on $(-\ell, 2\ell)$ with periodic conditions (very fine mesh)
- Generate boundary conditions for small domain $(0, \ell)$
- Compare simulations in $(0, \ell)$ with reference solution

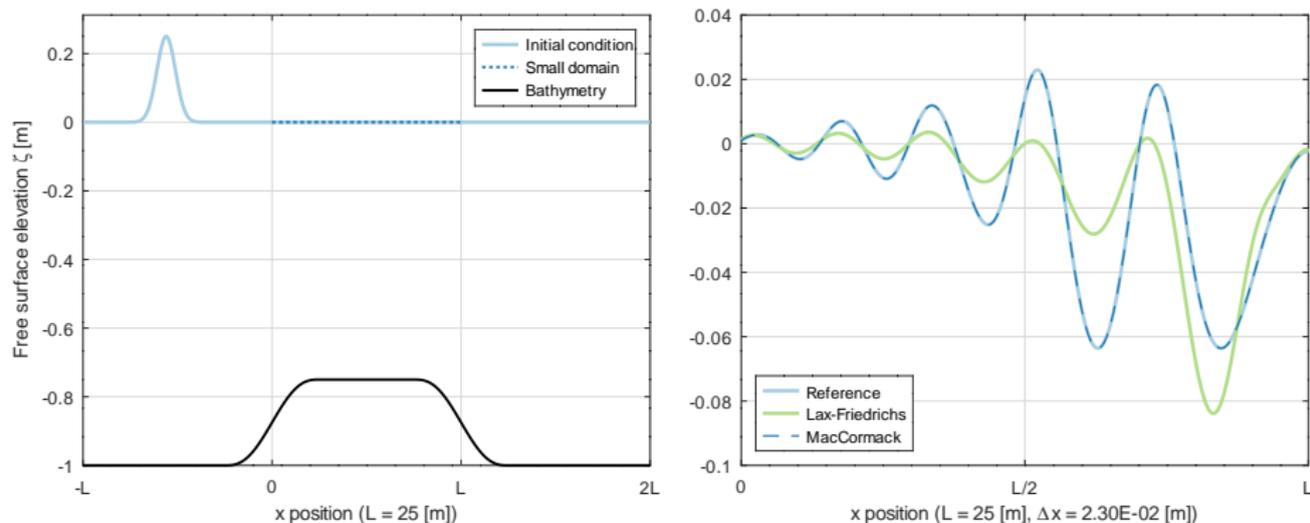


Figure: Gaussian over bump (left: initial time, right: $t = 15$ [s])

Question: starting from a wrong initial condition, can we recover the reference solution by enforcing appropriate boundary conditions?

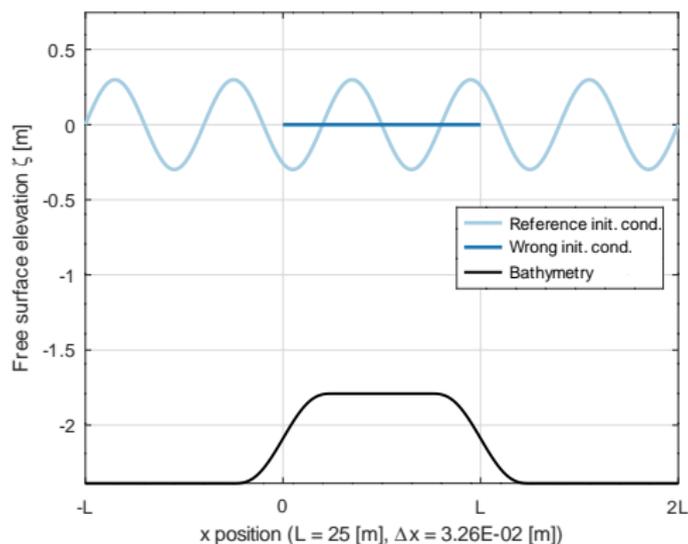


Figure: Sine over bump (shallowness $(2\pi H_0)^2 / \lambda^2 = 1$)

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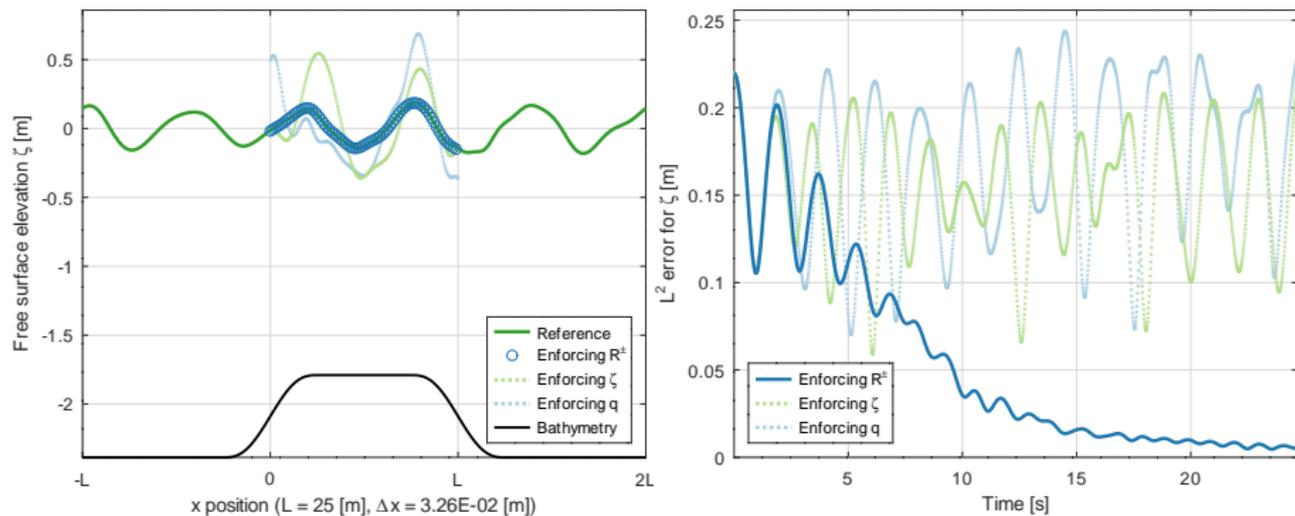


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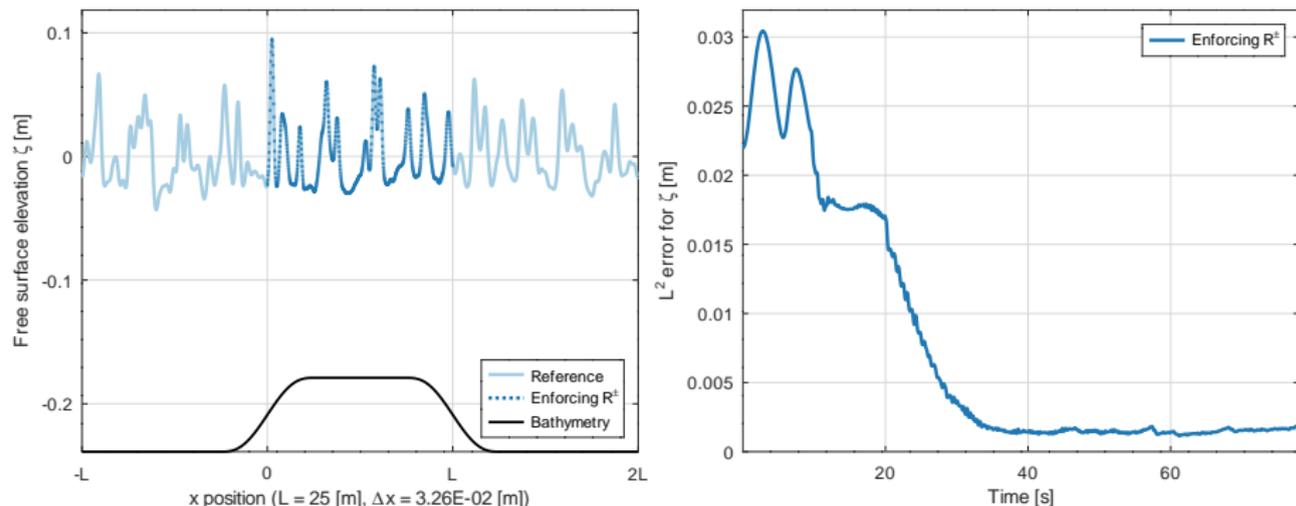


Figure: Sine over bump (shallowness $(2\pi H_0)^2/\lambda^2 = 10^{-2}$)

Motivation: wave breaking with dispersive models \rightarrow non physical oscillations.



Structure-preserving schemes (entropy stable, well-balanced)

Perspectives: coupling with the shallow water model

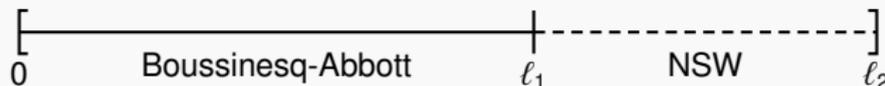
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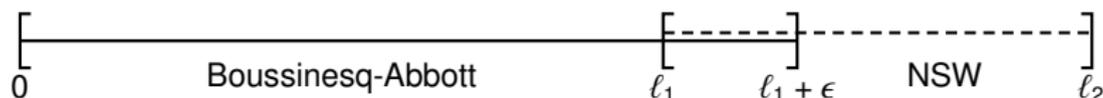
$$\left\{ \begin{array}{ll} \partial_t \zeta_L + \partial_x q_L = 0 & \text{in } (0, \ell_1) \\ \partial_t q_L + \partial_x \tilde{f}(\zeta_L, q_L) = \mathfrak{B}(\zeta_L, q_L) + s_{(0)} \dot{q}_{L|x=0} + s_{(\ell_1)} \dot{q}_{L|x=\ell_1} & \\ \partial_t \zeta_R + \partial_x q_R = 0 & \text{in } (\ell_1, \ell_2) \\ \partial_t q_R + \partial_x \tilde{f}_{\text{NSW}}(U_R) = -gh_R \partial_x b & \end{array} \right.$$

Coupling conditions: $\xi_{\ell_1}^+(U_{R|\ell_1}) = \xi_{\ell_1}^+(U_{L|\ell_1}), \quad \xi_{\ell_1}^-(U_{L|\ell_1}) = \xi_{\ell_1}^-(U_{R|\ell_1})$



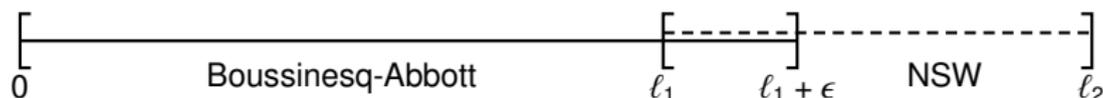
Preliminary observations and ideas

- Weird artifacts near coupling interface
- Much improved with a spatial overlapping...
- ... but difficult to interpret at continuous level



Preliminary observations and ideas

- Weird artifacts near coupling interface
- Much improved with a spatial overlapping...
- ... but difficult to interpret at continuous level



- 1 Approx. U_R^{n+1} with FV scheme + hydrostatic reconstruction; $\mathcal{R}_+(U_R)|_{l_1} = \mathcal{R}_+(U_L)|_{l_1}$
- 2 Approx. U_L^{n+1} with Lax-Friedrichs scheme + trace equations; $\mathcal{R}_-(U_L)|_{l_1+\epsilon} = \mathcal{R}_-(U_R)|_{l_1+\epsilon}$
- 3 Convex combination in overlapping area: $U_i^{n+1} = \rho(x_i)U_{L,i}^{n+1} + (1 - \rho(x_i))U_{R,i}^{n+1}$.

Figure: Initial condition

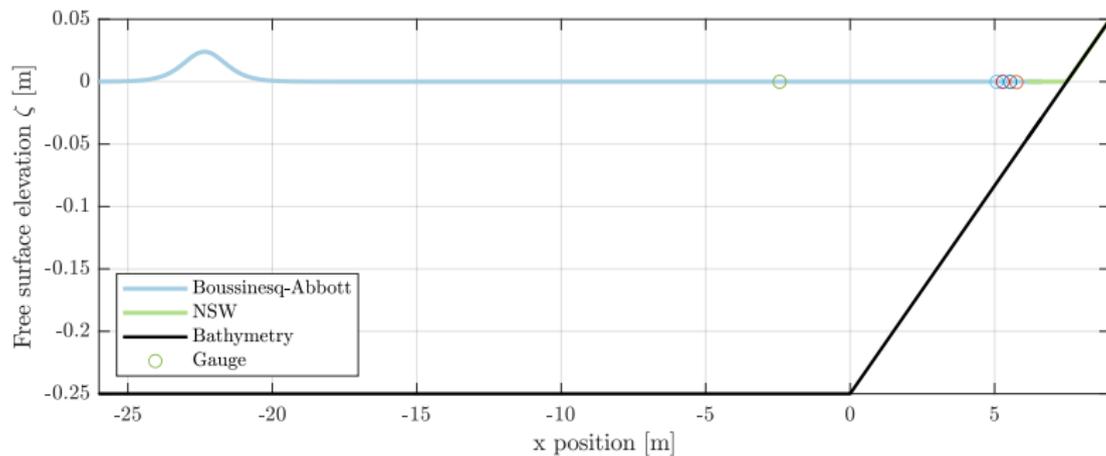
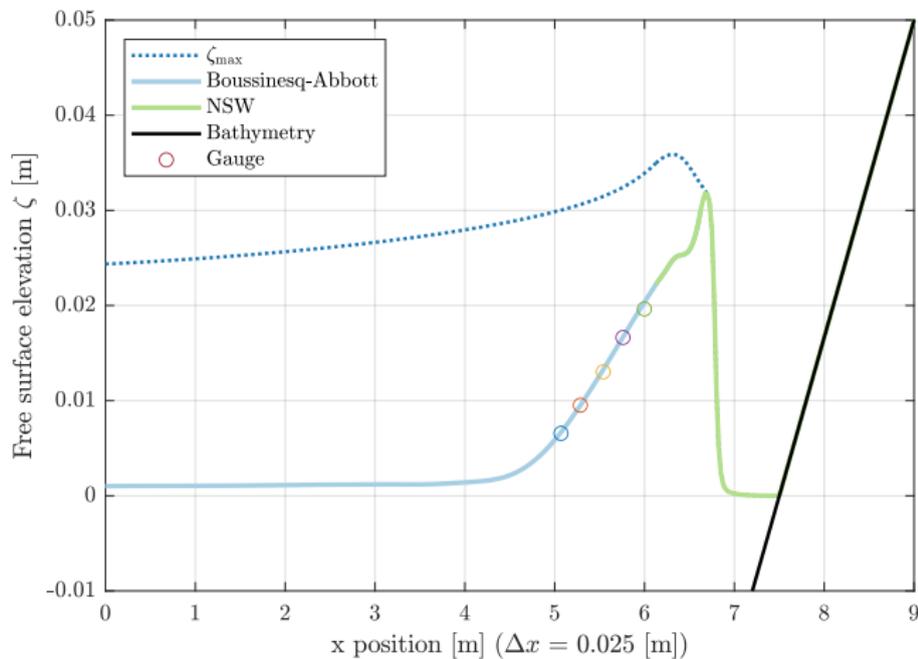


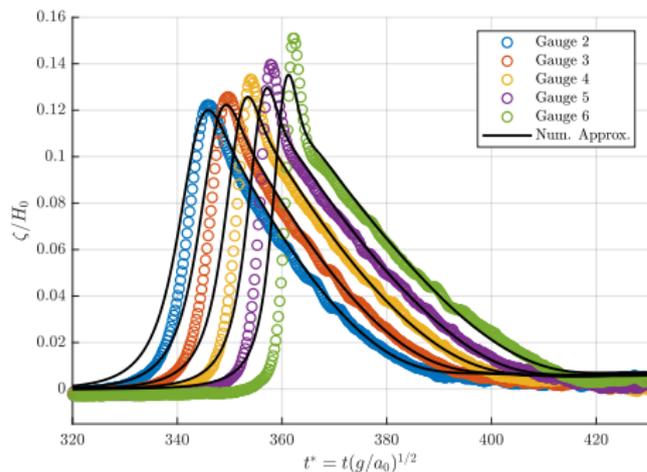
Figure: Time $t = 18.5$ [s]



Filippini, Bellec, Colin, Ricchiuto 2014

Boussinesq models can be written in (ζ, q) or (ζ, v) form

- in the 1st case, shoaling is **underestimated**;
- in the 2nd case, shoaling is **overestimated**;



Issue: risk of bias when predicting extreme waves

Possible fix: try mixing the (ζ, q) and (ζ, v) formulations

Figure: Predicted elevation for LEGI experiment

Over a flat bottom:

- Reformulation of Boussinesq-Abbott in bounded domain
- Generalized boundary conditions
- Efficient 1st and 2nd order schemes

Over a varying bottom:

- Similar reformulation
- Numerical validation & asymptotic stability

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Perspectives:

- Coupling with shallow water model
- Improve shoaling description
- Statistics of extreme waves: impact of bathymetry

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Thank you for your attention!

Constructing nonlocal operator R_b^1

Write dispersive operator $(1 + h_b \mathcal{T}_b)$ as $\alpha_b + h_b \mathcal{S}^*(h_b \mathcal{S}(\cdot))$, where

$$\alpha_b = 1 + \frac{1}{4}(\partial_x b)^2, \quad \mathcal{S}(\cdot) = -\frac{h_b}{\sqrt{3}} \partial_x \left(\frac{\cdot}{h_b} \right) + \frac{\sqrt{3}}{2} \frac{\partial_x b}{h_b}$$

Definition 2

$$R_b^1 : f \in L^2(0, \ell) \mapsto u \in H^2(0, \ell) \text{ s.t. } \begin{cases} \left[1 + \mathcal{S} \left(\frac{h_b}{\alpha_b} (h_b \mathcal{S})^* \right) \right] u = f \\ (h_b \mathcal{S})^* u(0) = (h_b \mathcal{S})^* u(\ell) = 0 \end{cases}$$

Lemma 3 (Commutation)

$$\forall f \in L^2(0, \ell), R_b^0(h_b \mathcal{S}^* f) = \frac{h_b}{\alpha_b} (h_b \mathcal{S})^* \left(R_b^1 \left(\frac{f}{h_b} \right) \right)$$

Approximate transparent boundary conditions

Use coupling as a sponge layer to evacuate waves.

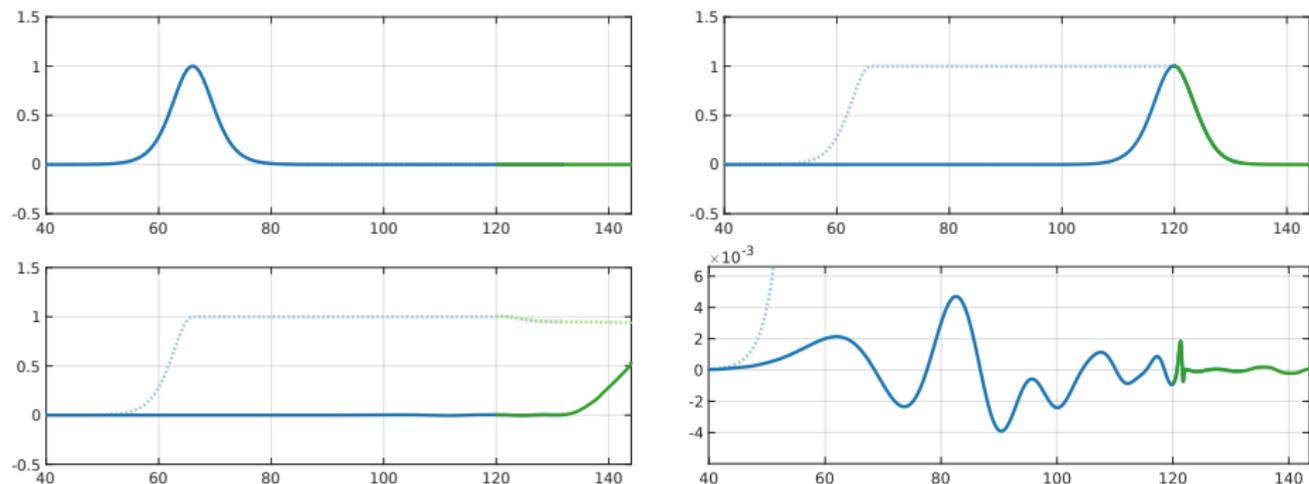


Figure: Outgoing soliton at times $t = 0, 9.46, 14.19$, and 23.16 [s]. Green domain corresponds to NSW.

Goal: study impact of bathymetry on extreme waves formation.

- Complex waves: different scales (swell/infragravity waves), two-ways propagation
- Need to randomly generate input data (ξ_0^+, ξ_ℓ^-)
- Probability distribution for incoming waves: [Fuhrman, Klahn and Zhai 2023](#)

$$p(\zeta) = \frac{1}{\sqrt{2\pi}} e^{-\zeta^2/2} \left(1 + \frac{1}{6} S(\zeta^3 - 3\zeta) \right) + O(\epsilon^2), \quad \begin{cases} S = \text{skewness parameter} \\ \epsilon = \text{wave steepness} \end{cases}$$

- Efficient code required: implement new methods in UHAINA