Implicit kinetic schemes for the Saint-Venant system

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Numerical Methods for Hyperbolic Problems

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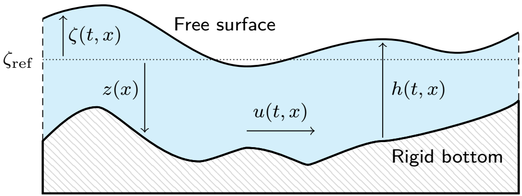
Saint-Venant equations: vertically averaged model (reduced complexity)

$$\begin{cases} \partial_t h + \partial_x hu = 0 \\ \partial_t hu + \partial_x (hu^2 + \frac{g}{2} h^2) = -gh\partial_x z \end{cases} \tag{SV}$$

Vector notation $\partial_t U + \partial_x F(U) = S(U, z)$ with $U = (h, hu)^T$.



Quantities of interest:

h	$\to$	water height
u	$\to$	horizontal velocity
hu	$\to$	horizontal discharge
z	$\to$	bathymetry

Important properties

Important properties at the continuous level:

- Positivity ($h \geq 0 \ \forall t$)
- Stationary state $h + z \equiv$ Cst, $u \equiv 0$
- Entropy inequality $\partial_t \eta(U,z) + \partial_x G(U,z) \leq 0$

$$\eta(U,z) = \frac{hu^2}{2} + \frac{gh^2}{2} + ghz, \quad G(U,z) = \Big(\eta(U,z) + \frac{gh^2}{2}\Big)u$$

Finite volume approximation

$$\begin{cases} \dfrac{U_i^{n+1} - U_i^n}{\Delta t} + \dfrac{1}{\Delta x}(F^n_{i+1/2} - F^n_{i-1/2}) = S_i^n \\ F^n_{i+1/2} = \mathcal{F}(U_i^n, z_i, U^n_{i+1}, z_{i+1}) \end{cases} \tag{1}$$

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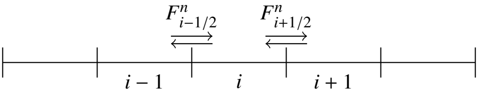
Finite volume approximation



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Finite volumes: numerical challenges

Problem n°1: if it exists, find $G^n_{i+1/2}$ numerical entropy flux such that

$$\text{Update (1)} \implies \begin{cases} \dfrac{\eta(U_i^{n+1}, z_i) - \eta(U_i^n, z_i)}{\Delta t} + \dfrac{1}{\Delta x}(G^n_{i+1/2} - G^n_{i-1/2}) \leq 0 \\ G^n_{i+1/2} = \mathcal{G}(U_i^n, z_i, U_{i+1}^n, z_{i+1}) \end{cases}$$

Problem n°2: preserve lakes at rest ($h + z = 0$, $u = 0$)

Steady state $\partial_t U = 0$ implies $\partial_x F(U) = S(U, z)$, whereas at discrete level:

$$\frac{1}{\Delta x}\left(F^n_{i+1/2} - F^n_{i-1/2}\right) = \begin{pmatrix} \dfrac{a}{2}\,\dfrac{z_{i+1} - 2z_i + z_{i-1}}{\Delta x} \\ \dfrac{g}{2\Delta x}((z_{i+1})^2 - (z_{i-1})^2) \end{pmatrix} \neq \begin{pmatrix} 0 \\ -g z_i \dfrac{z_{i+1} - z_{i-1}}{2\Delta x} \end{pmatrix},$$

and therefore $\dfrac{U_i^{n+1} - U_i^n}{\Delta t} \neq 0.$

Finite volumes: numerical challenges

Solution proposed by Audusse et. al (2016)

→ Explicit kinetic scheme preserving lakes at rest...

→ but satisfying a discrete entropy inequality with error term

$$\frac{\eta(U_i^{n+1}, z_i) - \eta(U_i^n, z_i)}{\Delta t} + \frac{1}{\Delta x}(G_{i+1/2}^n - G_{i-1/2}^n) \leq D_i^n, \quad D_i^n > 0$$

Our goal is to implicit this scheme to improve its stability

Outline of the talk:

1. Brief recall of the kinetic formalism
2. The case of a flat topography
3. The case of a varying topography

Kinetic representation of the Saint-Venant system

Kinetic equation with BGK collision operator

$$\partial_t f + \xi \partial_x f - g(\partial_x z)\partial_\xi f = \frac{1}{\epsilon}(M(U,\xi) - f) \tag{BGK}$$

- $f(t,x,\xi) \geq 0$ density of particles with velocity ξ
- Moment relations $\int (1,\xi,\xi^2)^T M(U,\xi)\,\mathrm{d}\xi = (h, hu, hu^2 + gh^2/2)^T$
- In the limit $\varepsilon \to 0$, we formally have $f \to M$

Choice proposed by Perthame and Simeoni 2001:

$$M(U,\xi) = \frac{1}{g\pi}\sqrt{(2gh - (\xi - u)^2)_+}$$

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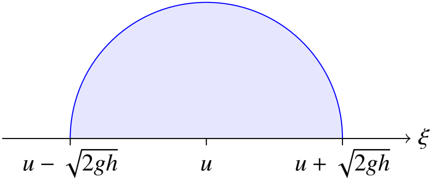

Definition 1 (Kinetic entropy)

The kinetic entropy $H(f,z,\xi) = \frac{\xi^2}{2} f + \frac{g^2\pi^2}{6} f^3 + gzf$ *is convex w.r.t.* $f \geq 0$ *and verifies*

$$\int_{\mathbb{R}} H(M(U,\xi),\xi)\,\mathrm{d}\xi = \eta(U), \qquad \int_{\mathbb{R}} H(M(U_f,\xi),\xi)\,\mathrm{d}\xi \leq \int_{\mathbb{R}} H(f,\xi)\,\mathrm{d}\xi \;\forall f$$

If flat bottom ($z \equiv$ Const), integrate (BGK) against $\partial_1 H(f,\xi)$ to get

$$\underbrace{\partial_t \int_{\mathbb{R}} H(f,\xi)\,\mathrm{d}\xi}_{\xrightarrow{\varepsilon\to 0}\ \partial_t\eta(U_f)} + \underbrace{\partial_x \int_{\mathbb{R}} \xi H(f,\xi)\,\mathrm{d}\xi}_{\xrightarrow{\varepsilon\to 0}\ \partial_x G(U_f)} = \frac{1}{\varepsilon} \underbrace{\int_{\mathbb{R}} \partial_1 H(f,\xi)(M(U_f,\xi) - f)\,\mathrm{d}\xi}_{\leq \int_{\mathbb{R}} H(M,\xi) - H(f,\xi)\,\mathrm{d}\xi \leq 0}$$

François Bouchut. "Construction of BGK Models with a Family of Kinetic Entropies for a Given System of Conservation Laws." (1999)

The case of a flat topography

Explicit time discretization involving BGK splitting

$$\begin{cases} \dfrac{f^{n+1/2} - f^n}{\Delta t} = \dfrac{1}{\varepsilon}(M(U_f^n, \xi) - f^{n+1/2}) & \text{collision step} \\ \dfrac{f^{n+1} - f^{n+1/2}}{\Delta t} + \xi \partial_x f^{n+1/2} = 0 & \text{transport step} \end{cases}$$

Explicit first order upwind scheme

$$\frac{f_i^{n+1} - M_i^n}{\Delta t} + \frac{\xi}{\Delta x}\Big(\mathbb{1}_{\xi<0}\big(M_{i+1}^n - M_i^n\big) + \mathbb{1}_{\xi>0}\big(M_i^n - M_{i-1}^n\big)\Big) = 0 \tag{2}$$

Macroscopic rewriting by integrating (2) against $(1, \xi)^T$

$$\frac{U_i^{n+1} - U_i^n}{\Delta t} + \frac{1}{\Delta x}\Big(F(U_i^n, U_{i+1}^n) - F(U_{i-1}^n, U_i^n)\Big) = 0$$

Kinetic numerical flux $F(U_L, U_R) = \int_{\xi<0} \xi \begin{pmatrix} 1 \\ \xi \end{pmatrix} M(U_R, \xi)\, \mathrm{d}\xi + \int_{\xi>0} \xi \begin{pmatrix} 1 \\ \xi \end{pmatrix} M(U_L, \xi)\, \mathrm{d}\xi.$

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The case of a flat topography

Do we satisfy a discrete counterpart to $\partial_t \eta + \partial_x G \leq 0$?

Proposition 1 (Audusse, Bouchut, Bristeau, and Sainte-Marie 2016)

If the CFL $\frac{\Delta t}{\Delta x}|\xi| \leq 1$ *holds for any* $\xi \in \operatorname{supp} M^n$*, then the explicit kinetic scheme* (2) *satisfies*

$$h_i^{n+1} \geq 0 \quad \textit{together with} \quad \frac{\eta(U_i^{n+1}) - \eta(U_i^n)}{\Delta t} + \frac{1}{\Delta x}(G_{i+1/2}^n - G_{i-1/2}^n) \leq 0$$

Proof: set $\sigma = \frac{\Delta t}{\Delta x}$ and rewrite (2) as

$$f_i^{n+1} = (1 - \sigma|\xi|)M_i^n + \sigma|\xi|M_{i\pm1}^n \geq 0$$

Also $\eta_i^{n+1} = \int_{\mathbb{R}} H(M_i^{n+1}, \xi)\,\mathrm{d}\xi \leq \int_{\mathbb{R}} H(f_i^{n+1}, \xi)\,\mathrm{d}\xi \leq \underbrace{\int_{\mathbb{R}} (1 - \sigma|\xi|)H_i^n + \sigma|\xi|H_{i\pm1}^n\,\mathrm{d}\xi}_{\eta_i^n - \sigma(G_{i+1/2}^n - G_{i-1/2}^n)}$

The case of a flat topography

We study the implicit version of the previous scheme.

$$\frac{f_i^{n+1} - M_i^n}{\Delta t} + \frac{\xi}{\Delta x}\Big(\mathbb{1}_{\xi<0}\big(f_{i+1}^{n+1} - f_i^{n+1}\big) + \mathbb{1}_{\xi>0}\big(f_i^{n+1} - f_{i-1}^{n+1}\big)\Big) = 0 \tag{3}$$

Solve the system $(\mathbf{I} + \sigma\mathbf{L})f^{n+1} = M^n + \sigma B^{n+1}$ with $\sigma = \Delta t/\Delta x$ and

$$\mathbf{L} = |\xi| \begin{pmatrix} 1 & -\mathbb{1}_{\xi<0} & & & 0 \\ -\mathbb{1}_{\xi>0} & 1 & -\mathbb{1}_{\xi<0} & & \\ & \ddots & \ddots & \ddots & \\ & & -\mathbb{1}_{\xi>0} & 1 & -\mathbb{1}_{\xi<0} \\ 0 & & & -\mathbb{1}_{\xi>0} & 1 \end{pmatrix}_{N\times N}, \quad B^{n+1} = |\xi| \begin{pmatrix} M_0^{n+1}\mathbb{1}_{\xi>0} \\ 0 \\ \vdots \\ 0 \\ M_{N+1}^{n+1}\mathbb{1}_{\xi<0} \end{pmatrix}_N$$

In practice, ghost cell contribution B^{n+1} unknown $\rightarrow$ substitute it by B^n.

Proposition 2 (El Hassanieh, R., Sainte-Marie)

The implicit kinetic scheme (3) is well defined, its update can be computed analytically and it enjoys the same properties as the explicit scheme $\forall \Delta t > 0$.

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The implicit kinetic scheme (3) *is well defined, its update can be computed analytically and it enjoys the same properties as the explicit scheme* $\forall \Delta t > 0$.

$$\frac{f_i^{n+1} - M_i^n}{\Delta t} + \frac{\xi}{\Delta x}\left(f_{i+1/2}^{n+1} - f_{i-1/2}^{n+1}\right) = 0 \quad \Longleftrightarrow \quad (\mathbf{I} + \sigma \mathbf{L}) f^{n+1} = M^n + \sigma B^n \tag{4}$$

Sketch of the proof:

Well-defined: The mass matrix has a strictly dominant diagonal ⇒ invertible

Positivity: The mass matrix is monotone and RHS is positive

Analytic expression: Decompose $\mathbf{L} = |\xi|\mathbf{I} - \mathbf{N}$ so that

$$(\mathbf{I} + \sigma \mathbf{L})^{-1} = \frac{1}{1 + \sigma|\xi|}\left(\mathbf{I} - \frac{\sigma}{1 + \sigma|\xi|}\mathbf{N}\right)^{-1} = \frac{1}{1 + \sigma|\xi|} \sum_{k=0}^{N} \left(\frac{\sigma}{1 + \sigma|\xi|}\mathbf{N}\right)^k$$

Entropy inequality: Multiply (4) by $\partial_1 H(f_i^{n+1}, \xi)$ and use

$$\partial_1 H(b, \xi)(b - a) = H(b, \xi) - H(a, \xi) + \frac{g^2 \pi^2}{6}(2b + a)(b - a)^2$$

to obtain

$$\frac{H(f_i^{n+1}) - H(M_i^n)}{\Delta t} + \frac{\xi}{\Delta x}(H_{i+1/2}^{n+1} - H_{i-1/2}^{n+1}) = \widetilde{D}_i(\xi) \leq 0$$

The case of a flat topography

In practice, cannot obtain explicit expression for $\int_{\mathbb{R}} \xi^p (\mathbf{I} + \sigma \mathbf{L})^{-1} M \, \mathrm{d}\xi$ with

$$M(U,\xi) = \frac{1}{g\pi} \sqrt{\left(2gh - (\xi - u)^2\right)_+}$$

Substitute M with a simpler Maxwellian satisfying the moment relations

$$\widetilde{M}(U,\xi) = \frac{h}{2\sqrt{3}c} \mathbb{1}_{|\xi - u| \leq \sqrt{3}c}, \quad c = \sqrt{\frac{gh}{2}}$$

- nonlinear implicit update **can be rewritten explicitly**
- counterpart: unlike M, $\widetilde{M}$ doesn't minimize $\int_{\mathbb{R}} H(\cdot,\xi) \, \mathrm{d}\xi$
- as a consequence, no proof of discrete entropy inequality...
- ... but in practice, it seems to dissipate energy (numerical validation)

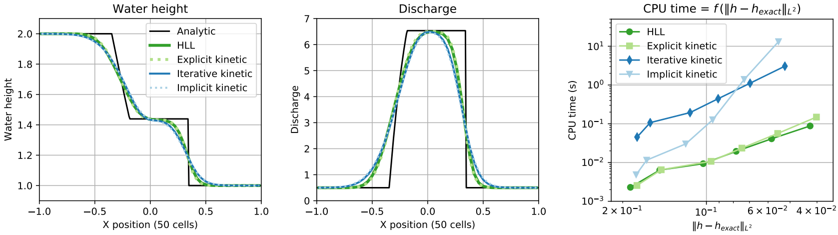
Computational cost of the implicit kinetic scheme

Neglecting the ghost cells, the implicit kinetic update writes

$$h^{n+1} = K((Ah) + (Bh))\sqrt{h^n}, \qquad hu^{n+1} = K'((Ahu) - (Bhu))\sqrt{h^n}$$

Matrices $(Ah), (Bh), (Ahu), (Bhu)$ have $N(N+1)/2$ nonzero coefficients

- matrix vector product has $\mathcal{O}(N^2)$ complexity (cannot do better)
- matrix assembly in $\mathcal{O}(N^2)$ steps possible
- fully vectorized implementation in Python



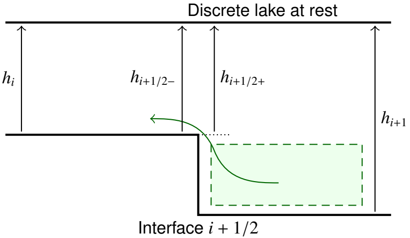
The case of a varying topography: hydrostatic reconstruction

Discretize source term in (SV) $\begin{cases} \partial_t h + \partial_x hu = & 0 \\ \partial_t hu + \partial_x(hu^2 + \frac{g}{2}h^2) = & -gh\partial_x z \end{cases}$

Problem: how to preserve lakes at rest $h + z \equiv$ Cst, $u \equiv 0$?

- Upwinding introduces diffusion on $h \Rightarrow h^{n+1} \neq h^n$
- Pressure variation should balance with source: $\partial_x\left(\frac{g}{2}h^2\right) = -gh\partial_x z$

Hydrostatic reconstruction



$$z_{i+1/2} = \max(z_i, z_{i+1})$$

$$h_{i+1/2-} = (h_i + z_i - z_{i+1/2})_+$$

$$h_{i+1/2+} = (h_{i+1} + z_{i+1} - z_{i+1/2})_+$$

Audusse, Bouchut, Bristeau, Klein, et al. 2004 “A fast and stable well-balanced scheme with hydrostatic reconstruction for shallow water flows.”

The case of a varying topography: explicit kinetic scheme

Explicit kinetic scheme with hydrostatic reconstruction:

$$\widetilde{F}_{i+1/2} = \int_{\mathbb{R}} \xi \begin{pmatrix} 1 \\ \xi \end{pmatrix} \Big(\mathbb{1}_{\xi>0} M(U_{i+1/2-}, \xi) + \mathbb{1}_{\xi<0} M(U_{i+1/2+}, \xi) \Big) \, \mathrm{d}\xi$$

$$\frac{U_i^{n+1} - U_i^n}{\Delta t} + \frac{1}{\Delta x}(\widetilde{F}^n_{i+1/2} - \widetilde{F}^n_{i-1/2}) = \widetilde{S}^n_i \tag{4}$$

Proposition 3 (Audusse, Bouchut, Bristeau, and Sainte-Marie 2016)

Under the CFL condition $\frac{\Delta t}{\Delta x}|\xi| < 1$ *the scheme* (4) *preserves the water height positivity, and admits the discrete entropy inequality*

$$\frac{\eta(U_i^{n+1}, z_i) - \eta(U_i^n, z_i)}{\Delta t} + \frac{1}{\Delta x}(G^n_{i+1/2} - G^n_{i-1/2}) \leq D_i, \quad D_i \geq 0$$

The quadratic error D_i *is Lipschitz in* $\sigma, \Delta x, \Delta z_i$*, and vanishes when* $u_i^n \to 0$.

$\Rightarrow$ We cannot ensure the dissipation of the total energy $\int_\Omega \eta(U(t,x)) \, \mathrm{d}x$

The case of a varying topography: iterative kinetic scheme

To solve this issue, implicit the previous scheme

$$\frac{U_i^{n+1} - U_i^n}{\Delta t} + \frac{1}{\Delta x}(\widetilde{F}_{i+1/2}^{n+1} - \widetilde{F}_{i-1/2}^{n+1}) = \widetilde{S}_i^{n+1}$$

Nonlinear system can't be solved directly → iterative approximation

$$(1+\alpha)U_i^{n+1,k+1} = U_i^n + \alpha U_i^{n+1,k} - \frac{\Delta t}{\Delta x}\Big(\widetilde{F}_{i+1/2}^{n+1,k} - \widetilde{F}_{i-1/2}^{n+1,k}\Big) + \widetilde{S}_i^{n+1,k}, \quad \alpha \geq 0 \tag{5}$$

Proposition 4 (El Hassanieh, R., Sainte-Marie)

- *We have $h_i^{n+1,k+1} \geq 0$ under the CFL*

$$\forall \xi \in \mathbb{R}, \ \Big(\frac{\Delta t}{\Delta x}|\xi| - \alpha\Big) M(U_i^{n+1,k}, \xi) \leq M(U_i^n, \xi)$$

- *The iterative process* (5) *satisfies the macroscopic entropy inequality*

$$\frac{\eta(U_i^{n+1,k+1}, z_i) - \eta(U_i^n, z_i)}{\Delta t} + \frac{1}{\Delta x}\Big(G_{i+1/2}^{n+1,k} - G_{i-1/2}^{n+1,k}\Big) \leq D_i^{n+1,k},$$

with $D_i^{n+1,k} \leq 0$ from some rank k assuming (5) *converges.*

Sketch of the proof: relies on the kinetic rewriting

$$(1+\alpha)f_i^{n+1,k+1} = M_i^n + \alpha M_i^{n+1,k} - \sigma\xi(M_{i+1/2}^{n+1,k} - M_{i-1/2}^{n+1,k}) + \sigma(\xi - u_i^{n+1,k})[M_{i+1/2-}^{n+1,k} - M_{i-1/2+}^{n+1,k}] \tag{6}$$

so that $U^{n+1,k} = \int_{\mathbb{R}}(1,\xi)^T f^{n+1,k}\,\mathrm{d}\xi$ for any $k \in \mathbb{N}$

Positivity: The quantity $(1+\alpha)h_i^{n+1,k}$ equals

$$\int_{\mathbb{R}} \Big(M_i^n + \alpha M_i^{n+1,k} - \sigma\xi(M_{i+1/2}^{n+1,k} - M_{i-1/2}^{n+1,k})\Big)\,\mathrm{d}\xi \geq \int_{\mathbb{R}} \Big(M_i^n + M_i^{n+1,k}\big(\alpha - \sigma|\xi|\big)\Big)\,\mathrm{d}\xi$$

Entropy inequality: Multiply (6) by $\partial_1 H(M_i^{n+1,k}, z_i, \xi)$ and use convexity of H

$$H(M_i^{n+1,k+1}, z_i) \leq H(M_i^n, z_i) - \sigma\Big(\widetilde{G}_{i+1/2}^{n+1,k} - \widetilde{G}_{i-1/2}^{n+1,k}\Big) + Q(\xi) + \widetilde{D}_i,$$

with $\int_{\mathbb{R}} Q(\xi)\,\mathrm{d}\xi = 0$ and

$$\widetilde{D}_i = \text{Strictly negative term } + \mathcal{O}(M_i^{n+1,k+1} - M_i^{n+1,k})$$

The case of a varying topography: iterative kinetic scheme

Proposition 5 (El Hassanieh, R., Sainte-Marie)

Assume the iterative scheme (6) keeps $U_i^{n+1,k}$ in $\left\{(h, hu)^T,\ \delta \le h \le K_1,\ |u| \le K_2\right\}$ for all k.
There exists $C(K_1, K_2, 1/\delta)$ such that $\Delta t \le C\Delta x$ implies the convergence of $(f_i^{n+1,k})_{k\in\mathbb{N}}$ to f_i^{n+1} solution of the implicit scheme.

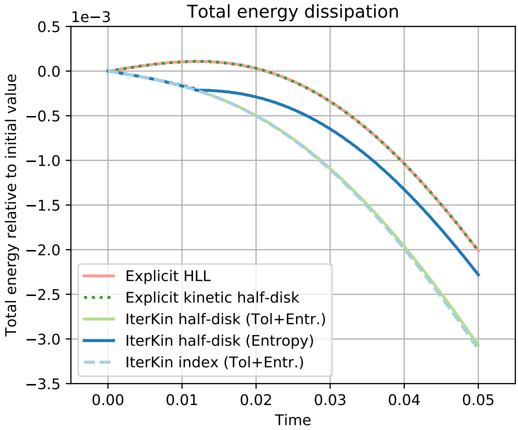
→ In practice, iterative process seems to converge without restriction

Stopping criteria: tolerance + total energy dissipation

$$\|U^{n+1,k+1} - U^{n+1,k}\| \le \tau \quad \& \quad \frac{1}{\Delta t}\sum_{1\le i\le N}\Big(\eta(U_i^{n+1,k+1}, z_i) - \eta(U_i^n, z_i)\Big) + \frac{1}{\Delta x}(G_{N+1/2}^{n+1,k} - G_{1/2}^{n+1,k}) \le 0$$

Numerical simulations

Total energy $\int_\Omega \eta \, \mathrm{d}x$ shoud decrease in time due to **entropy inequality**.

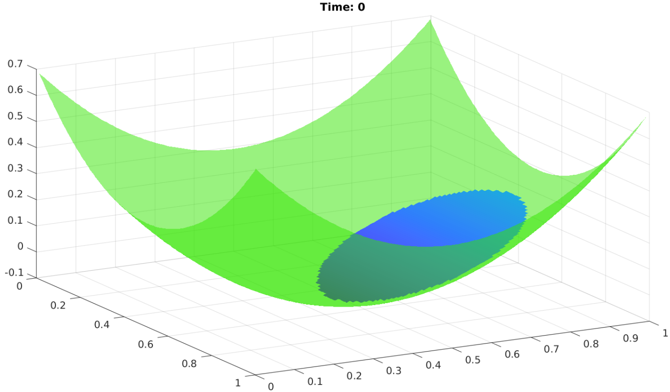


Numerical testcase:

$h + z = \text{Cst}$
$u = \text{Cst}' \neq 0$

→ Results still valid in 2D

→ Good approximation of the parabolic bowl (difficult numerical testcase)



For a flat topography

- Positivity and entropy inequality obtained unconditionally
- Obtained fully implicit scheme with explicit update for Saint-Venant
- Optimal setting: inversion by hand, no factorization/iterative method

With varying bathymetry

- Hydrostatic reconstruction requires iterative strategy
- Positivity and entropy inequality hold under CFL

Perspectives

- Increase order of accuracy (iterative only)
- Improve hydrostatic reconstruction by also reconstructing velocity u
- 2D version of implicit scheme

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- Optimal setting: inversion by hand, no factorization/iterative method

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- Hydrostatic reconstruction requires iterative strategy
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- Increase order of accuracy (iterative only)
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Conclusion and perspectives

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Thank you for your attention!

Explicit writing of the implicit kinetic scheme

Neglecting the ghost cells, the implicit kinetic update writes

$$h^{n+1} = K((Ah) + (Bh))\sqrt{h^n}, \qquad hu^{n+1} = K'((Bhu) - (Ahu))\sqrt{h^n}$$

For instance, matrix (Ah) is given by

$$\begin{pmatrix}
[z]_{-\min(0,b_1)\sigma}^{-\min(0,a_1)\sigma} & [z-y]_{-\min(0,b_2)\sigma}^{-\min(0,a_2)\sigma} & \dots & \dots & [z-\sum_{l=1}^{N-1} y^l/l]_{-\min(0,b_N)\sigma}^{-\min(0,a_N)\sigma} \\
0 & [z]_{-\min(0,b_2)\sigma}^{-\min(0,a_2)\sigma} & & & \vdots \\
\vdots & & \ddots & & \vdots \\
\vdots & & & \ddots & [z-y]_{-\min(0,b_N)\sigma}^{-\min(0,a_N)\sigma} \\
0 & \dots & \dots & 0 & [z]_{-\min(0,b_N)\sigma}^{-\min(0,a_N)\sigma}
\end{pmatrix}$$

where $y = x/(1+x)$, $z = \ln|1+x|$, $a_j = u_j^n - \sqrt{3}\,c_j^n$ and $b_j = u_j^n + \sqrt{3}\,c_j^n$

The case of a varying topography: hydrostatic reconstruction

Numerical flux and source term using reconstructed values

$$\begin{cases} \widetilde{F}_{i+1/2} = F(U_{i+1/2-}, U_{i+1/2+}) \\ \widetilde{F}_{i-1/2} = F(U_{i-1/2-}, U_{i-1/2+}) \end{cases}, \quad \widetilde{S}_i = \frac{g}{2\Delta x}(h^2_{i+1/2-} - h^2_{i-1/2+})\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

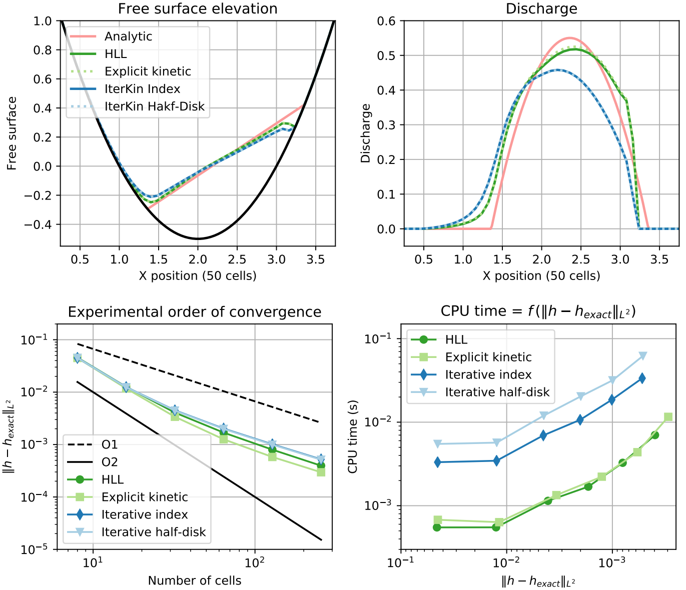
- $\widetilde{S}_i$ is indeed consistent with the source term

$$\frac{1}{2\Delta x}(h^2_{i+1/2-} - h^2_{i-1/2+}) = \underbrace{\frac{1}{2}(h_{i+1/2-} + h_{i-1/2+})}_{h_i + O(\Delta z_i)} \times \underbrace{\frac{1}{\Delta x}(h_{i+1/2-} - h_{i-1/2+})}_{-(z_{i+1/2} - z_{i-1/2})/\Delta x} = -h\partial_x z + O(\Delta x)$$

- If $F(U,U) = F(U)$ (consistency), then over lakes at rest one has

$$U_{i+1/2-} = U_{i+1/2+} \implies \frac{\widetilde{F}_{i+1/2} - \widetilde{F}_{i-1/2}}{\Delta x} = \frac{F(U_{i+1/2-}) - F(U_{i-1/2+})}{\Delta x} = \widetilde{S}_i$$

Numerical simulations



Numerical testcase: slowly moving shock