Designing accurate and efficient schemes for the low Froude regime

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The 2D Shallow Water system



Low Froude regime: $Fr \stackrel{\text{def}}{=} \frac{\text{particles velocity}}{\text{surface waves velocity}} \ll 1$

Shallow Water system: $\partial_t U + \nabla \cdot F(U) = S(U, z)$ (SW)

$$U(t, x, y) = \begin{pmatrix} h \\ hV \end{pmatrix}_{3 \times 1} \quad F(U) = \begin{pmatrix} hV^T \\ hV \otimes V + \frac{h^2}{2Fr^2} I \end{pmatrix}_{3 \times 3} \quad S(U, z) = \begin{pmatrix} 0 \\ -\frac{h}{Fr^2} \nabla z \end{pmatrix}_{3 \times 1}$$

Wave splitting and time integration

Explicit FV schemes: stability ⇒ prohibitively small timesteps

$$\Delta t \leq \frac{\operatorname{Fr}}{2} \min\left(\frac{\operatorname{mes}(\Gamma)}{\operatorname{Fr}|V \cdot n| + \sqrt{h}}\right) = O(\operatorname{Fr}\Delta x, \operatorname{Fr}\Delta y)$$

Instead: try to split the system in two spatial operators:

$$\nabla \cdot F(U) - S(U, z) = \nabla \cdot K(U, z) + \mathcal{G}(U, z)$$

 $K(U, z) \rightarrow$ convective flux (slow dynamics)

- its eigenvalues must remain bounded as $Fr \rightarrow 0$;
- it can be nonlinear;

 $\mathcal{G}(U, z) \rightarrow$ gravity waves diff. operator (fast dynamics)

- its eigenvalues can be unbounded as $Fr \rightarrow 0$;
- it must be linear;

Wave splitting and time integration

We will consider IMplicit-EXplicit time integrators:

$$\frac{U^{n+1}-U^n}{\Delta t}+\nabla\cdot K(U^n,z)+\mathcal{G}(U^{n+1},z)=0$$

Space discretization on a cartesian mesh:

- $\nabla \cdot K(U, z)$ discretized using Godunov-type fluxes;
- $\mathcal{G}(U, z)$ discretized using centered differences;

Define scheme S_{Fr}^1 with properties:

- Second order accuracy;
- Stable for a scale-independent timestep $(\Delta t = O(\Delta x, \Delta y));$
- Well balanced (lakes at rest are preserved);
- Asymptotic preserving (S_0^1 consistent with limiting eq.);

A first IMEX scheme



A first IMEX scheme



Preserving nearly incompressible states

How should solutions behave when $Fr \ll 1$?

Limiting system:

$$\left\{ \begin{array}{l} \overline{U}(t > 0, \cdot) \in \ker \mathcal{G}(\cdot, z) \stackrel{\text{def}}{=} \left\{ \begin{pmatrix} h \\ hV \end{pmatrix}, \ \nabla(h + z) = 0, \ \nabla \cdot (hV) = 0 \right\} \\ \partial_t \overline{V} + (\overline{V} \cdot \nabla) \overline{V} + \nabla \Pi = 0 \end{array} \right\}$$
(SW₀)

From now on, take $z \equiv Cst \Rightarrow ker \mathcal{G}$ is the set of incompressible states

Theorem 1 (Schochet, 1994)

Solutions of (SW) remain "close" to ker \mathcal{G} if the initial condition is "close".

Study modified equation associated with $S_{Fr}^1(K = 0)$: $\partial_t U + \mathcal{F}U = 0$

 \rightarrow Does it preserve nearly incompressible states?

Theorem 2 (Dellacherie)

Assume $(\partial_t + \mathcal{F})U = 0$ leaves ker \mathcal{G} invariant. Sol. U of this eq. satisfy

$$\inf_{\mathsf{V} \in \ker \mathcal{G}} ||U(t = 0, \cdot) - W|| = O(\mathsf{Fr}) \Rightarrow \inf_{\mathsf{W} \in \ker \mathcal{G}} ||U(t > 0, \cdot) - W|| = O(\mathsf{Fr})$$

Proposition 1

The modified equation of $S_{Fr}^1(K = 0)$ doesn't leave ker G invariant.

Intuition: Neglecting *K*, the modified equation of $S_{Fr}^1(K = 0)$ reads

$$\left(\frac{\partial}{\partial t}+\mathcal{G}\right)U=[\mathcal{R}_{\Delta t}-\mathcal{R}_{\Delta x}]U$$

We have ker $\mathcal{G} \subset \ker \mathcal{R}_{\Delta t}$, but ker $\mathcal{G} \not\subset \ker \mathcal{R}_{\Delta x}$

Preserving nearly incompressible states

Solution: introduce $\widetilde{\mathcal{R}}_{\Delta x}$ such that ker $\widetilde{\mathcal{R}}_{\Delta x} \supset \ker \mathcal{G}$

Proposition 2

Define S_{Fr}^2 by substituting G with $G + \tilde{\mathcal{R}}_{\Delta x} - \mathcal{R}_{\Delta x}$ in S_{Fr}^1 . Its modified eq. reads

$$\left(\frac{\partial}{\partial t}+\mathcal{G}\right)U=[\mathcal{R}_{\Delta t}-\widetilde{\mathcal{R}}_{\Delta x}]U,$$

hence it leaves ker G invariant.

Modified scheme S_{Fr}^2



Experimental order of convergence and efficiency

