MULTIRESOLUTION ANALYSIS FOR 2D TURBULENCE.
PART 2: A PHYSICAL INTERPRETATION

PATRICK FISCHER, CHARLES-HENRI BRUNEAU
Université Bordeaux 1, IMB, CNRS UMR 5466, INRIA projet MC2,
351, Cours de la Libération, 33405 Talence Cedex, France

HAMID KELLAY
Université Bordeaux1, CPMOH, CNRS UMR 5798,
351, Cours de la Libération, 33405 Talence Cedex, France
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ABSTRACT. Multiresolution methods such as the wavelet packets or the cosine packets are more and more used in physical applications and in particular in two-dimensional turbulence. The numerical results of the first part of this paper have shown that the wavelet packets decomposition is well suited for studying this kind of problem: the visualization of the vorticity field is better, without any artefacts, than the visualization with the cosine packets filtering.
The current second part of the paper is devoted to the physical interpretation of the filtered fields obtained in the first part. Energy and enstrophy spectra as well as energy and enstrophy fluxes are computed to determine the role of each filtered field with respect to the cascades.

1. Introduction. It has been shown in the first part of this paper [3] that the wavelet packets filtering can be successfully used for analyzing two-dimensional turbulence. This technique allows the separation of two structures: the solid rotation part of the vortices and the remaining mainly composed of vorticity filaments. The wavelet packets filtering leads to continuous filtered fields and avoids the discontinuities that would be created by a direct cut-off filtering. The spurious effects due to this kind of discontinuities created by a direct filtering have been discussed in [4]. It has been shown in particular in that paper that the discontinuities are responsible for the creation of spurious coefficients in Fourier space that alter the corresponding energy and enstrophy spectra.

In the present paper we will refine the explanations given in the first part and detail the physical interpretation of the filtered fields given in [1]. The energy and enstrophy fluxes will be computed and they will allow a better understanding of the energy and enstrophy transfer processes through the scales. A few results about the pressure field and its correlation to the solid rotations field will be also given in the paper.

The paper is organized as follows. The theoretical background is recalled in section 2 where we make some remarks about the Danilov inequality. The experimental setup and the filtering process are described in section 3. Direct numerical simulations are used to obtain a two-dimensional turbulent flow at relatively high Reynolds

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numbers. The filtering algorithm leading to continuous filtered fields is described but the theory of wavelet packets is not recalled here. The results about the energy and enstrophy fluxes are given in section 4. It is shown that two-dimensional turbulence admits two distinct structures: vortical structures and filamentary structures. The first ones are responsible for the inverse transfers of energy while the second ones are responsible for the forward transfer of enstrophy. The decomposition of the nonlinear term in the Navier-Stokes equation is described in section 5. This decomposition permits the separation of the energy or enstrophy transport due to the solid rotations from the transport due to the filaments. Conclusions and remarks are given in section 6.

2. Theoretical background. Two-dimensional turbulence, in a finite but periodic domain, is governed by two invariants, the energy and the enstrophy. The mean energy per unit mass $E$ is defined by,

$$E \equiv \left\langle \frac{1}{2} |v|^2 \right\rangle = \frac{1}{2} \int_{B_L} |v(x)|^2 dx$$

(1)

where $B_L$ denotes the physical domain and $S(B_L)$ its corresponding surface. If one considers now the velocity $v$ as a $L$-periodic function, it can be decomposed as a Fourier series:

$$v(x) = \sum_k \hat{v}(k)e^{\frac{2\pi i}{L} k \cdot x}, \quad k \in \mathbb{Z}^2.$$  

(2)

The low-pass filtered velocity function is then defined as,

$$v^K_L(x) = \sum_{|k| \leq K} \hat{v}(k)e^{\frac{2\pi i}{L} k \cdot x}$$

(3)

and the high-pass filtered velocity function as:

$$v^K_H(x) = \sum_{|k| > K} \hat{v}(k)e^{\frac{2\pi i}{L} k \cdot x}.$$  

(4)

This decomposition of the velocity,

$$v(x) = v^K_L(x) + v^K_H(x),$$

(5)

was used for the first time by Obukhov [11, 12]. Introducing this splitting in the Navier-Stokes equations, one obtain a scale-by-scale energy budget equation described by Frisch [5]:

$$\partial_t E(K) + \Pi_E(K) = D_E(K) + F_E(K).$$

(6)

where

$$E(K) = \left\langle \frac{1}{2} |v^K_L|^2 \right\rangle = \frac{1}{2} \sum_{|k| \leq K} |\hat{v}(k)|^2,$$

(7)

denotes the cumulative energy, $\Pi_E(K)$ the energy flux due to the nonlinear terms through the wavenumber $K$, $D_E(K)$ the energy dissipation, and $F_E(K)$ the energy injection. The energy spectrum is then defined by,

$$E(k) \equiv \frac{dE(k)}{dk},$$

(8)

and the total energy can be rewritten as,

$$E = \int_{0}^{\infty} E(k) dk.$$  

(9)
The same splitting can be used in the Navier-Stokes equation written for the vorticity and a scale-by-scale enstrophy budget equation can be obtained:

\[ \partial_t Z(K) + \Pi_Z(K) = D_Z(K) + \mathcal{F}_Z(K), \]

where \( Z(K) \) denotes the cumulative enstrophy, \( \Pi_Z(K) \) the enstrophy flux, \( D_Z(K) \) the enstrophy dissipation, and \( \mathcal{F}_Z(K) \) the enstrophy injection. The enstrophy \( Z \) can be defined in the same way as the energy,

\[ Z \equiv \left\langle \frac{1}{2} |\omega|^2 \right\rangle = \frac{1}{2} \frac{1}{S(B_L)} \int_{B_L} |\omega(x)|^2 dx, \]

where \( \omega = \nabla \times v \) is the vorticity field. The relation between the enstrophy and the enstrophy spectrum is then given by:

\[ Z = \int_{0}^{\infty} Z(k) dk \]

where \( Z(k) \) stands for the enstrophy spectrum. The energy and enstrophy spectra are linked to each other in Fourier space by the following relation:

\[ Z(k) = \left( \frac{2\pi k}{L} \right)^2 E(k) \]

which reduces to

\[ Z(k) = k^2 E(k) \]

in a \( 2\pi \)-periodic bounded domain. Using the same notation as Tung and Gkioulekas in [16], this relation can be written in a more general form:

\[ Z(k) = \Lambda(k) E(k). \]

The fluxes are also related to each other by the same kind of relation:

\[ \frac{\partial \Pi_Z(k)}{\partial k} = \Lambda(k) \frac{\partial \Pi_E(k)}{\partial k}. \]

Outside the forcing range, the fluxes should verify the following Danilov inequality:

\[ \Lambda(k) \Pi_E(k) < \Pi_Z(k). \]
imposed on the entrance section of the channel, and a non reflecting condition is imposed on the exit section. The numerical experiments give a realistic picture of a fluid entering in a channel, pertubated by cylindrical obstacles and exiting the channel. These simulations describe the behavior of a shallow river or a real soap film experiment like in [9, 10, 14, 13]. The spectra are computed in a selected square located at the end of the channel. Thus we do not have any periodic condition in any case, and the relations described above between the energy and the enstrophy spectra do not hold anymore. It has been shown in [4] that the energy-enstrophy relation numerically diverges in our particular case. This relation is verified only for a short range of frequencies in the middle part of the spectra, approximately between $k \approx 3$ and $k \approx 20$. A detailed study has been performed, and the results have shown that a Windowed Fourier Transform has to be used for the spectra computations in order to remove the discontinuities created by the boundary conditions.

3. The experimental setup and the filtering process.

3.1. Experimental setup. In the first part [3], two numerical experiments, called simulation I and II, had been performed. Slightly different versions of simulation II are considered in this paper. The additional cylinders along the channel are used to increase the number of merging events, and thus to enhance the inverse energy cascade phenomenon. In the first part, the energy injection scale $k_{inj}$ had been considered to be equal to the diameter of the five big cylinders ($k_{inj} \approx 10$). But it is a matter of fact that the small cylinders along the sides of the channel induce a second small energy injection around $k = 20$. So the energy injection should be considered to lie between 10 and 20. In order to get a better localized energy injection, the five big cylinders have been replaced by ten small cylinders. From now, all the obstacles have the same diameter and induce the same energy injection scale. The Reynolds number based on the cylinders diameter is $Re = 50000$ that is large enough to get a fully developed turbulent flow. This is about the same value as those used in soap film experiments [2, 9, 10]. A snapshot of the vorticity field from the upstream cylinders to the end of the channel is given in Figure 1.

The simulations have been performed on a $640 \times 2560$ grid and the averages have been computed with 25 snapshots. A Tukey window with the parameter equal to 0.1 has been used in all the computations in order to remove the discontinuities created by the boundary conditions.

3.2. The filtering process. The theory concerning the wavelet packets has been detailed in [3] and will not be repeated here. The same Daubechies type wavelets are used in the current paper to build the packets array, and the entropy criterion is used in the best basis selection process. In [3], a few tests were performed in order to get the best wavelet mother, and to determine the number of scales necessary for an efficient representation of the flow. The criterion was then the minimization of the entropy. It had been shown that it was not necessary to perform the wavelet packets decomposition over more than 3 scales when the finest scale corresponds to a $320 \times 1280$ grid. It has to be reminded that the scale sequence goes from finest scales to coarsest scales. It leads to the most efficient representation according to the entropy criterion but not to the smoothest fields after filtering. It has been shown in [3] that, as long as one is concerned with smoothing the discontinuities, it is necessary to go over at least 4 scales (for a finest scale corresponding to a $320 \times 1280$ grid). That means that in [3], where only 3 scales were considered,
some spurious coefficients due to the discontinuities remained in the spectra, and
the slopes detected in the figures were partly altered. So in the results presented
in this second part of the paper, all the decompositions have been performed over
5 scales for a $640 \times 2560$ grid. The overall filtering process can be summarized as
follows:

1. Computation of the wavelet packets decomposition of the two components of
the velocity $v = (u, v)$ over 5 scales.
2. Separation of the velocity fields into two subfields: one subfield, $v_s = (u_s, v_s)$,
where the wavelet packet coefficients have their modulus larger than a given
threshold $\epsilon$ and another one, $v_f = (u_f, v_f)$ where the wavelet packet coeffi-
cients are smaller than $\epsilon$.
3. Construction of the corresponding vorticity fields, $\omega_s$ and $\omega_f$. The filtered
field $\omega_s$ is then essentially composed by the solid rotation part of the vortices,
and the filtered field $\omega_f$ by the vorticity filaments in between that roll up
in spirals inside the vortices. The first subfield corresponds to more than
95% of the total energy and around 70% of the enstrophy while the second
one corresponds to less then 5% of the total energy and around 30% of the
enstrophy.
4. Computations of the physical data: energy and enstrophy spectra and fluxes.
The velocity decomposition $v = v_s + v_f$ is orthogonal and leads to the energy
spectrum decomposition:

$$E(k) = E_s(k) + E_f(k),$$ (18)

as can be verified in Figure 2.

First of all, we have to remark that because of the use of the windowing the slopes
in the original spectrum are steeper than the ones shown in Figure 1b. Here we observe
a first slope around $k^{-2}$ and a second slope around $k^{-5.5}$. This is due to the fact
that all the spurious coefficients due to the discontinuities have been removed. One
then notice that both components are multiscale, although the part with the
vortices dominates at low wavenumbers and the part mainly composed by filaments
dominate at high wavenumbers. The first slope is not really clear but the second
one is evident. These slopes and this decomposition can be also observed on the
enstrophy spectra given in Figure 3.

It has been shown in [4] that the relation (15) with \( \Lambda(k) = 4\pi^2k^2 \)
between the
energy and the enstrophy spectra is verified only in the middle part of the spectra
(which is the significant part for \( k \) in the range 4 to 120 on both sides of the injection
scale \( k_{inj} \)) due to the boundary conditions.

**Remark:** The pressure field is rarely studied in papers on two-dimensional turbu-
lence but nevertheless can bring interesting information about the fluid. A snap-
shot of the end of the pressure field is given in Figure 4.

The pressure field can be compared to the corresponding vorticity field. The
decomposition into the two subfields obtained by the filtering process is also given
in Figure 4.

As can be easily observed, the peaks of the pressure correspond exactly to vorti-
icity peaks. They correspond obviously to the solid rotation structures, and it can
be expected that the pressure spectrum should present the same behavior as the
solid rotations spectrum. Both spectra are given in Figure 5 and the similarity
between the shape of the pressure spectrum and the shape of the solid rotations
energy spectrum is clear.
4. Energy and enstrophy fluxes. We recall that the energy flux is computed from the nonlinear term in the Navier-Stokes equation written in Fourier space:

$$\Pi_E(k) = \int_{k}^{+\infty} T_E(k')dk'$$

(19)

where $T_E(k)$ is the nonlinear energy transfer function and is obtained by angular integration of $\hat{v}^\ast(k) (v \cdot \nabla \hat{v}(k))$. The enstrophy flux is obtained in the same way:

$$\Pi_Z(k) = \int_{k}^{+\infty} T_Z(k')dk'$$

(20)

where $T_Z(k)$ is the enstrophy transfer function and is obtained by angular integration of $\hat{\omega}^\ast(k) (v \cdot \nabla \hat{\omega}(k))$.

The inequality in equation (17) brought to the attention of Tung and Gkioulekas by Danilov has been discussed in [16]. According to Tung and Gkioulekas, if an inertial range exists, then this inequality describes the process of the transition from
Figure 5. Pressure and solid rotations spectra ($k_{inj} \approx 20$).

Figure 6. $\Pi Z - \Delta \Pi E$ allowing to verify the Danilov inequality.
the leading cascade to the subleading cascade observed in the energy spectrum. As can be noticed in Figure 6, this inequality is verified almost everywhere except in a small range at large scales. It is not surprising since the inertial range does not stretch out on large scales. It has been mentioned by Tran in [15] that the behavior at large scales of a fluid in an elongated and doubly periodic domain is far from understood. He describes in that paper how the inverse energy cascade can be partially stopped. Furthermore in our case, the boundary conditions are different and the fluid dynamics at large scale is very hard to predict. However, it can be noticed that the inequality is verified around $k = 20$ which is supposed to be the injection scale.

![Figure 7](image_url)

**Figure 7.** Energy fluxes of the whole flow and of the separate structures ($k_{inj} \approx 20$).

Let us now study the energy and enstrophy fluxes themselves. The energy and enstrophy fluxes corresponding to those experiments are respectively given in Figure 7 and 8. The energy flux is negative for wavenumbers $k$ below the injection scale 20 and slightly positive but almost zero above. The enstrophy flux is on the other hand positive above the injection scale, and negative below. The zero crossing corresponds approximately to the injection scale. These results show the existence of leading cascades, upscales for the inverse energy cascade and downscales for the direct enstrophy cascade but also the existence of subleading cascades as theoretically shown by Tung and Gkioulekas in [6, 7] and [16]. It can also be noticed that the injection scale being relatively large, the energy cascade cannot be developed completely. A priori and if the turbulence is inertial, the energy flux should present a plateau in the small wavenumber range. Our simulations do not produce a large plateau but an explanation for this is the limitation of the range of scales probed.
and the presence of the boundaries. In our mathematical model, we did not use any artificial dissipation term like an hyper or hypoviscosity terms, and the two cascades could certainly be improved by using artificial dissipation terms at large and small scales.

Finally, even if our experiment does not verify the usual boundary conditions of the 2D turbulence theory, both the energy flux and the enstrophy flux show that the classical picture of 2D turbulence, i.e. coexistence of two cascades, is valid for the flow considered here regardless of whether a plateau for the energy flux or enstrophy flux is achieved.

4.1. Fluxes for the filtered fields. In order to study, in detail, the energy transfer, we focus now on the nonlinear energy transfer function which, due to the orthogonal decomposition, can be written as:

\[
T_E(k) = \mathbf{v}^*(k) \cdot (\nabla \mathbf{v}) = \mathbf{v}_s^*(k) \cdot (\nabla \mathbf{v}_s(k)) + \mathbf{v}_f^*(k) \cdot (\nabla \mathbf{v}_f(k))
\]

(21)

The global energy transfer can be split into four parts corresponding to the multiscale transfers from one subfield to itself or to the other one. For instance, \(\mathbf{v}_s^*(k) \cdot (\nabla \mathbf{v}_f(k))\) is the energy transfer from the vorticity filaments subfield to the solid rotation subfield. The fluxes corresponding to each term in the expression for the total energy transfer function will be denoted as for example \(\Pi_{E}^{f \rightarrow s}\) which is the flux corresponding to the transfer term previously described. In the same way, the nonlinear enstrophy transfer term is also split into four parts:

\[
T_Z(k) = \mathbf{\omega}^*(k) \cdot (\nabla \mathbf{\omega}) = \mathbf{\omega}_s^*(k) \cdot (\nabla \mathbf{\omega}_s(k)) + \mathbf{\omega}_f^*(k) \cdot (\nabla \mathbf{\omega}_f(k))
\]

(22)

Using these decompositions, the fluxes associated with each structure as well as the fluxes associated with the interactions of the two structures can be obtained. Let us first consider the energy fluxes of the whole flow and of the separate structures in Figure 7.

The energy flux for the vortices shows a large negative part at small \(k\) which is similar to the total flux and becomes very small and close to zero beyond the injection scale. The energy flux associated with the filaments is almost zero everywhere; it is negative but small at small \(k\) and becomes slightly positive near the injection scale before becoming zero at the high \(k\) end.

The enstrophy flux for the vortices is negative at small \(k\) and becomes close to zero beyond the injection scale as shown in Figure 8. The enstrophy flux for the filaments is on the other hand large and positive for the high \(k\) after the injection scale and is very close to the value of the total flux in this region of wavenumbers. This preliminary examination of the fluxes indicates that the main part of the energy flux comes from the solid rotations while the main part of the enstrophy flux comes from the filamentary structures.
Figure 8. Enstrophy fluxes of the whole flow and of the separate structures ($k_{inj} \approx 20$).

Figure 9. Cross fluxes of enstrophy ($k_{inj} \approx 20$).
It is however possible to give a more detailed analysis of the energy and enstrophy transfers. When computing the nonlinear terms, we are comparing in fact the Fourier spectrum of a two-dimensional field, \( \hat{\omega}_s(k) \) for instance, to the Fourier spectrum of a transported field, \( (v \nabla) \omega_f(k) \) on the other hand. The energy flux from the vortices to the filaments and vice versa are an order of magnitude smaller than the flux due to the filaments or the flux due to the vortices. However, the cross fluxes of enstrophy show an interesting feature in Figure 9.

\[ \Pi_{f \rightarrow s} + \Pi_{s \rightarrow f} \approx 0 \]

Although both fluxes compensate each other, there is a clear interaction between the two different structures. The vortices transfer enstrophy to the filaments from the small scales to the large scales while the filaments transfer enstrophy to the vortices from large scales to the small scales.

4.2. The inverse energy cascade. In order to improve the generation of each cascade separately, one can try to move the injection scale from one side of the spectrum to the other one. However, the possible shifts are very limited due to numerical constraints. The penalization method used to take into account the obstacles in the equations and the discretization step size do not allow the use of very small cylinders. One can however define obstacles of size corresponding to an injection scale of \( k_{\text{inj}} \approx 40 \). The Reynolds number is still kept equal to 50000 in these new numerical computations. The computations have been performed on a grid of size \( 1024 \times 4096 \). A snapshot corresponding to this new geometry is given in Figure 10. The statistics to compute the fluxes have been performed only on 20 snapshots in order to limit the size of the data. Consequently the fluxes are less smooth than in the previous case.

As can be expected, the inverse energy cascade has more room to take place and the energy flux tends to go to zero at the largest scales (Figure 11) and goes back to zero close to the injection scale (\( k \approx 40 \)). The direct enstrophy cascade still exists at scales larger than the injection scale (Figure 12) and can be observed until \( k \approx 100 \). One can also notice that the enstrophy flux crosses the zero axis around the injection scale (\( k \approx 40 \)).
Figure 11. Energy fluxes of the whole flow and of the separate structures ($k_{inj} \approx 40$).

Figure 12. Enstrophy fluxes of the whole flow and of the separate structures ($k_{inj} \approx 40$).
4.3. The direct enstrophy cascade. In order to study the direct enstrophy cascade, the geometry of the numerical experiment has been modified again. The turbulence is now created by three arrays of big cylinders. This setup produces an injection scale $k_{\text{inj}}$ located around $k = 9$ ($Re = 50000$). The computations have been performed on a grid of size $512 \times 2048$. A snapshot of the vorticity field corresponding to this setup is given in Figure 13.

As can be verified on the corresponding energy flux given in Figure 14, the injection scale is too large to allow the development of a full inverse energy cascade.

The enstrophy flux is given in Figure 15 and it can be observed on the graph that the direct enstrophy cascade beyond the injection scale does exist. But it can also be observed a strong enstrophy transfer from the injection scale toward the largest scales. One notice again that the enstrophy flux crosses the zero axis around the injection scale ($k \approx 9$).

Finally, the shifting of the injection scale from $k_{\text{inj}} \approx 9$ to $k \approx 40$ essentially influences what is going on before the injection scale but modify only slightly the
Figure 15. Enstrophy fluxes of the whole flow and of the separate structures ($k_{inj} \approx 9$).

Figure 16. Decomposition of the main term responsible for the energy cascade ($k_{inj} \approx 20$).

fluxes beyond it. However, if a much larger injection scale could be set then the enstrophy cascade would be certainly altered. In addition, one can observe that the amplitude of the enstrophy flux increases with the injection scale. This is due to the fact that the number of vortices also increases with the injection scale.
5. **Decomposition of the transport operator.** We have studied in the previous paragraphs the roles played by the various structures in the global energy and enstrophy transfers and the interactions occurring between them. It is however possible to specify how these interactions take place or more exactly what are the media allowing those transfers. Indeed, thanks to the decomposition of the transport operator itself, it will be shown in this part that the solid rotations of the vortices are the means of transport of the energy and enstrophy transfers.

Thus the transport operator can be decomposed into two parts:

\[
(v \cdot \nabla) = (v_s \cdot \nabla) + (v_f \cdot \nabla).
\] (23)

By performing this decomposition one can separate the energy or enstrophy transport due to the solid rotations from the transport due to the filaments. Finally each term of the equations (21) and (22) can be also split into two parts leading to the following complete decompositions:

\[
T_E(k) = \widehat{v_s^*}(k).\widehat{(v_s \cdot \nabla)v_s(k)} + \widehat{v_s^*}(k).\widehat{(v_f \cdot \nabla)v_s(k)}
\]

\[
+ \widehat{v_s^*}(k).\widehat{(v_s \cdot \nabla)v_f(k)} + \widehat{v_s^*}(k).\widehat{(v_f \cdot \nabla)v_f(k)}
\]

\[
+ \widehat{v_f^*}(k).\widehat{(v_s \cdot \nabla)v_s(k)} + \widehat{v_f^*}(k).\widehat{(v_f \cdot \nabla)v_s(k)}
\]

\[
+ \widehat{v_f^*}(k).\widehat{(v_s \cdot \nabla)v_f(k)} + \widehat{v_f^*}(k).\widehat{(v_f \cdot \nabla)v_f(k)},
\] (24)

and

\[
T_Z(k) = \widehat{v_s^*}(k).\widehat{(v_s \cdot \nabla)v_s(k)} + \widehat{v_s^*}(k).\widehat{(v_f \cdot \nabla)v_s(k)}
\]

\[
+ \widehat{v_s^*}(k).\widehat{(v_s \cdot \nabla)v_f(k)} + \widehat{v_s^*}(k).\widehat{(v_f \cdot \nabla)v_f(k)}
\]

\[
+ \widehat{v_f^*}(k).\widehat{(v_s \cdot \nabla)v_s(k)} + \widehat{v_f^*}(k).\widehat{(v_f \cdot \nabla)v_s(k)}
\]

\[
+ \widehat{v_f^*}(k).\widehat{(v_s \cdot \nabla)v_f(k)} + \widehat{v_f^*}(k).\widehat{(v_f \cdot \nabla)v_f(k)},
\] (25)

and

\[
T_f(k) = \widehat{v_s^*}(k).\widehat{(v_s \cdot \nabla)v_s(k)} + \widehat{v_s^*}(k).\widehat{(v_f \cdot \nabla)v_s(k)}
\]

\[
+ \widehat{v_s^*}(k).\widehat{(v_s \cdot \nabla)v_f(k)} + \widehat{v_s^*}(k).\widehat{(v_f \cdot \nabla)v_f(k)}
\]

\[
+ \widehat{v_f^*}(k).\widehat{(v_s \cdot \nabla)v_s(k)} + \widehat{v_f^*}(k).\widehat{(v_f \cdot \nabla)v_s(k)}
\]

\[
+ \widehat{v_f^*}(k).\widehat{(v_s \cdot \nabla)v_f(k)} + \widehat{v_f^*}(k).\widehat{(v_f \cdot \nabla)v_f(k)},
\] (26)
\[ T_\omega(k) = \hat{\omega}_s(k) \cdot (v_s \cdot \nabla) \omega_s(k) + \hat{\omega}_f(k) \cdot (v_f \cdot \nabla) \omega_f(k) \]  
\[ + \hat{\omega}_f(k) \cdot (v_s \cdot \nabla) \omega_f(k) + \hat{\omega}_s(k) \cdot (v_f \cdot \nabla) \omega_s(k) \]  
\[ + \hat{\omega}_s(k) \cdot (v_s \cdot \nabla) \omega_s(k) + \hat{\omega}_s(k) \cdot (v_f \cdot \nabla) \omega_f(k) \]  
\[ + \hat{\omega}_f(k) \cdot (v_s \cdot \nabla) \omega_f(k) + \hat{\omega}_f(k) \cdot (v_f \cdot \nabla) \omega_f(k). \]  

For instance, the second term in the right hand side of (25) describes the enstrophy transfer from the solid rotations to themselves by the filamentary structures. One can thus detail the main terms responsible for the fluxes:

\[ \Pi_{E}^{s-s} = \Pi_{E}^{s-s} + \Pi_{E}^{s-f} \]  
\[ \Pi_{Z}^{f-f} = \Pi_{Z}^{f-f} + \Pi_{Z}^{f-f}, \]  

for the energy transfer and,

for the enstrophy transfer. The various terms corresponding to these decompositions have been computed for the first numerical experiment with the injection scale \( k_{inj} \) equal to 20 described in the beginning of the paper. The decompositions are given in Figures 16 and 17. The outstanding result of these decompositions is that in both cases the solid rotations are the media responsible for the two transfers. Thus the vortices transport the energy from vortices to vortices and the enstrophy from filaments to filaments. The filamentary structures are responsible for the direct enstrophy cascades thanks to the solid rotations dynamics. On the other hand, the inverse energy cascade is completely due to the vortices.

6. Conclusions. All the results presented in this paper were obtained with a forcing naturally created by the obstacles. No artificial force has been introduced and the dissipation is only due to the classical term without any hyper or hypo viscosity. The boundary conditions are quite realistic and close to the conditions that can be found in a river with a two-dimensional turbulence created by the pillars of a bridge for instance. The theory for this realistic setup does not yet exist, and the comparison to the classical Kraichnan-Leith-Bachelor theory is limited. Tran in [15] studied the case of a large-scale transverse flows of incompressible fluid in an elongated doubly periodic domain. He concluded that many questions are still open and should be addressed by numerical methods. Our numerical experiments shed some light on this particular problem.

Concerning our specific numerical experiments, we can conclude that an inverse energy cascade and a direct enstrophy cascade coexist. An inverse enstrophy cascade also exists. Because of the inverse cascade in two-dimensional turbulence, energy usually piles up at the scales of the domain and a large-scale energy sink is generally used in numerical simulations. Here, we don’t need this kind of large-scale dissipation in our experiments because of our boundary conditions (an open channel with a Poiseuille flow at the entrance and a non-reflecting condition on the exit section) which allow the inverse energy cascade to take place.

Due to numerical limitations, the importance of these cascades is linked to the size of the injection scale. Furthermore, the energy spectra do not present the classical \( k^{-5/3} \) and \( k^{-3} \) slopes. We found a scaling law in \( k^{-2} \) for the inverse energy transfer and in \( k^{-5.5} \) for the direct enstrophy transfer. The energy cascade is due to an
energy transfer inside the solid rotation parts of the vortices and the enstrophy cascade is due to an enstrophy transfer from filaments to themselves. The structures allowing the two transfers are the solid rotation parts of the vortices.

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E-mail address: Patrick.Fischer@math.u-bordeaux1.fr