## Multiphase formulation of plasma physics

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## Outline

The Vlasov-Poisson equation and the kinetic Euler equation

Known results concerning linear and non-linear instability

New results: the measure-valued setting and the multiphase formulation

An application to incompressible optimal transport

The Vlasov-Poisson case

## The Vlasov-Poisson equation and the kinetic Euler equation

## The Vlasov-Poisson equation

$$
(V P)\left\{\begin{array}{c}
\partial_{t} f+v \cdot \nabla_{x} f-\nabla_{x} U \cdot \nabla_{v} f=0, \\
-\Delta_{x} U=\int f \mathrm{~d} v-1, \\
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Global existence of classical solutions for $d=2$ or 3 [Ukai, Okabe 78; Lions, Perthame 91; Pfaffelmoser 92].

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\left(V P_{\varepsilon}\right)\left\{\begin{array}{c}
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The parameter $\varepsilon$ is the Debye length. It is typically very small w.r.t. the scale of observations ( $\sim 10^{-3} \mathrm{~m}$ in the ionosphere, $\sim 10^{-4} \mathrm{~m}$ in a tokamak).

## The kinetic Euler equation


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(k E u)\left\{\begin{array}{c}
\partial_{t} f+v \cdot \nabla_{x} f-\nabla_{x} p \cdot \nabla_{v} f=0 \\
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\left.f\right|_{t=0}=f_{0}
\end{array}\right.
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where again $f=f(t, x, v), p=p(t, x)$.
As in the case of the incompressible Euler equation, $p$ solves an elliptic equation:

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The pressure $p$ has the same number of spatial derivatives as $f$. (Same scaling as in the Vlasov-Benney equation where $p$ is replaced by the spatial density $\rho=\int f \mathrm{~d} v$ [Jabin, Nouri 11; Bardos, Nouri 12]).

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[Grenier 96]: (kEu) is well-posed in spaces of analytic regularity.

# Known results concerning linear and non-linear instability 

## Linearization of (VP) around homogeneous profiles

$$
(V P)\left\{\begin{array}{c}
\partial_{t} f(t, x, v)+v \cdot \nabla_{x} f(t, x, v)-\nabla_{x} U(t, x) \cdot \nabla_{v} f(t, x, v)=0, \\
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-\Delta_{x} U(t, x)=\int f(t, x, v) d v>1,  \tag{L}\\
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We look for exponential growing modes (EGM):

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f(t, x, v)=g(v) \exp (i n \cdot x) \exp (\lambda t),
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where $n \in \mathbb{Z}^{d}$ is the frequency, $\lambda \in \mathbb{C}$ with $\Re(\lambda)>0$ is the growing rate.

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If there exists an EGM, we say that $\mu$ is unstable.

## Penrose instability criterion

## Proposition (Penrose 1960)

Let $\mu$ be a smooth profile. Equation (L) admits an EGM of frequency $n$ and growing rate $\lambda$ iff the following Penrose condition (Pen) holds:

$$
\int \frac{i n \cdot \nabla_{v} \mu(v)}{\lambda+i n \cdot v} d v= \begin{cases}\varepsilon^{2}|n|^{2}, & \text { for }\left(V P_{\varepsilon}\right), \\ 0, & \text { for }(k E u) .\end{cases}
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In that case:

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g(v) \propto \frac{i n \cdot \nabla_{v} \mu(v)}{\lambda+i n \cdot v} .
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In dimension 1:

STABLE


UNSTABLE


## Toward non-linear instability

Take $(\lambda, n)$ satisfying (Pen) and set the ansatz:

$$
\left\{\begin{array}{c}
f(t, x, v)=\mu(v)+\delta \Re\left(\frac{i n \cdot \nabla_{v} \mu(v)}{\lambda+i n \cdot v} \exp (\lambda t+i n \cdot x)\right)+R^{\delta}(t, x, v), \\
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Main question: Up to which time $T_{\delta}$ and in which norm $\|\bullet\|$ can you justify:

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\forall t \in\left[0, T_{\delta}\right], \quad\left\|R^{\delta}(t)\right\| \ll \delta \exp (\Re(\lambda) t) ?
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(We say that we justify the linear approximation in $\|\bullet\|$ up to time $T_{\delta}$.)

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## Problem

$$
\mu(v)+\delta \Re\left(\frac{i n \cdot \nabla_{v} \mu(v)}{\lambda+i n \cdot v} \exp (i n \cdot x)\right)
$$

needs to be sufficiently regular and nonnegative. It is hence needed to add assumptions on $\mu$ (regularity + cancellation conditions).

## Lyapounov instability for (VP)

This question has been widely studied, see e.g. [Guo, Strauss 95; Han-Kwan, Hauray 15; Han-Kwan, Nguyen 16].

## Theorem (Han-Kwan, Nguyen 16)

Let $\mu$ be smooth, Penrose unstable and satisfying cancellation conditions. For all $s, m \in \mathbb{N}$, there exist solutions $f^{\delta}$ up to time $T_{\delta}>0$ of (VP) such that:

- Convergence at the initial time:

$$
\left\|\left(1+|v|^{2}\right)^{m / 2}\left\{f_{0}^{\delta}-\mu\right\}\right\|_{H^{s}\left(\mathbb{T}^{d} \times \mathbb{R}^{d}\right)}=\mathcal{O}(\delta),
$$

- No convergence at time $T_{\delta}=\mathcal{O}(|\log \delta|)$ :

$$
\liminf _{\delta \rightarrow 0}\left\|f^{\delta}\left(T_{\delta}\right)-\mu\right\|_{L^{2}\left(\mathbb{T}^{d} \times \mathbb{R}^{d}\right)}>0 .
$$

## III-posedness for (kEu)

## Proposition

If $\mu$ is unstable, if $(n, \lambda)$ satisfies (Pen) for ( $k E u$ ) and if $k \in \mathbb{N}^{*}$, then ( $k n, k \lambda$ ) also satisfies (Pen).

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$$
\frac{\left\|f^{\delta}-\mu\right\|_{L^{2}\left(\left[0, T_{\delta}\right) \times \mathbb{T}^{d}\right)}}{\left\|\left(1+|v|^{2}\right)^{m / 2}\left\{f_{0}^{\delta}-\mu\right\}\right\|_{H^{s}\left(\mathbb{T}^{d} \times \mathbb{R}^{d}\right)}^{\alpha}} \underset{\delta \rightarrow 0}{\longrightarrow}+\infty
$$

New results: the measure-valued setting and the multiphase formulation

## The measure-valued setting

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Do there exist unstable solutions in the neighbourhood of these unstable measures?

## III-posedness for ( $k E u$ ) around measures

Theorem (B. 2019)
Take $\mu$ an unstable measure, $\varphi_{1}, \ldots, \varphi_{N} \in C_{c}^{\infty}\left(\mathbb{R}^{d}\right), s \in \mathbb{N}$ and $\alpha \in(0,1]$.

## III-posedness for ( $k E u$ ) around measures

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Take $\mu$ an unstable measure, $\varphi_{1}, \ldots, \varphi_{N} \in C_{c}^{\infty}\left(\mathbb{R}^{d}\right), s \in \mathbb{N}$ and $\alpha \in(0,1]$. Then there exists, $\left(T_{\delta}\right)_{\delta>0}$ tending to 0 and $\left(f_{0}^{\delta}\right)_{\delta>0}$ a family of measure-valued initial data such that:

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- we have:

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\frac{\left\|p_{\delta}\right\|_{L^{1}\left(\left[0, T_{\delta}\right) \times \mathbb{T}^{d}\right)}}{\sum_{i=1}^{N}\left\|\left\langle f_{0}^{\delta}, \varphi_{i}\right\rangle-\left\langle\mu, \varphi_{i}\right\rangle\right\|_{W^{s, \infty}\left(\mathbb{T}^{d}\right)}^{\alpha}} \xrightarrow[\delta \rightarrow 0]{\longrightarrow}+\infty .
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## Multiphase formulation

We look for solutions of the form:

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The stationary solution $(1, w)_{w \in \mathbb{R}^{d}}$ is linearly unstable if and only if $\boldsymbol{\mu}$ is Penrose unstable.

## III-posedness in the multiphase formulation

Recap: 1. Each stationary profile is a multiphase solution;
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An application to
incompressible optimal
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## An application to incompressible optimal transport



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Motivation: For a given $P$, if all the trajectories follow the same smooth vector field $v$, then $P$ is a solution "iff" $v$ is a solution of the incompressible Euler equation [Arnol'd 66; Brenier 89].

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In general: An incompressible generalized flow $P$ is a solution "iff" all the trajectories are accelerated by the same scalar pressure field $p$.

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By our ill-posedness result: $\boldsymbol{p}$ is not a smooth function of $\gamma$ [B. 2019].

## The Vlasov-Poisson case

## Lyapounov instability in the Vlasov-Poisson case

Ongoing work with D. Han-Kwan.
This time, the multiphase system is:

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- If $d=1$ and $\mu$ is is a superposition of 2 Diracs, this is exactly the framework of [Cordier, Grenier, Guo 2000] in which they prove non-linear instability.
- A generalization of their proof in higher dimension and general $\mu$ would provide a proof of non-linear instability for (VP) in a measure-valued setting.


Pictures from Frans Ebersohn, PEPL, University of Michigan.

