

# Around BGK models: numerical methods for conservation laws and more

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# Goal of the talk

Use the kinetic viewpoint to construct numerical approximations of systems of PDEs arising in fluid dynamics, plasmas, and more.

**The fundamental example** Finite volumes for Euler equations:

- ▶ Godunov method  
Riemann solver with resolution of algebraic equations at each cell interface
- ▶ Kinetic method

*Euler* = limit of BGK

*discretized Euler* = limit of *discretized BGK*

Resolution of transport equations

First paper in that direction: R.H. Sanders and K.H. Prendergast, On the origin of the 3 kiloparsec arm, *Astrophys. J.* (1974)

# BGK (Bhatnagar-Gross-Krook) model for Euler equations - 1954

It is a simplification of the Boltzmann equation governing the distribution function  $f(x, t, \xi)$  of an homogeneous gas:

$$\partial_t f^\varepsilon + \xi \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon} (M(Pf^\varepsilon, \xi) - f^\varepsilon), \quad Pf^\varepsilon = \int_{\mathbb{R}^3} \begin{pmatrix} 1 \\ \xi \\ \frac{1}{2}|\xi|^2 \end{pmatrix} f^\varepsilon d\xi.$$

**linear transport equation** with source-term.

$\varepsilon$ : proportionnal to the Knudsen number.

$M(U, \xi)$ : maxwellian function satisfying

$$\forall U = (\rho, \rho u, \mathcal{E}), \quad PM(U, \xi) = U, \quad P(\xi M(U, \xi)) = F(U)$$

and **entropy properties**.  $F$ : flux of Euler equations.

Macroscopic limit:  $\varepsilon \rightarrow 0$

$$f^\varepsilon \rightarrow f = M(U), \quad U = Pf$$

and  $U$  is an **entropy solution of Euler equations**.

The idea is to discretize the BGK equation in such a way that when  $\varepsilon \rightarrow 0$  we obtain a consistent and stable discretization of Euler equations, ie to construct an **Asymptotic Preserving (AP) scheme**

# Finite Volume method for hyperbolic systems of conservation laws

$$\partial_t U + \partial_x F(U) = 0, \quad (x, t) \in \mathbb{R} \times [0, T]$$

with  $U(x, t) \in \mathcal{V} \subset \mathbb{R}^K$ .

$$C_j = ]x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}[, \quad x_{j+\frac{1}{2}} - x_{j-\frac{1}{2}} = \Delta x, \quad t_0 = 0, \quad t_{n+1} = t_n + \Delta t.$$

$$\int_{t_n}^{t_{n+1}} \int_{C_j} \partial_t U + \partial_x F(U) dx dt = 0$$

$$\begin{aligned} \int_{C_j} U(x, t_{n+1}) dx &= \int_{C_j} U(x, t_n) dx \\ &\quad - \int_{t_n}^{t_{n+1}} F(U(x_{j+\frac{1}{2}}, t)) dt + \int_{t_n}^{t_{n+1}} F(U(x_{j-\frac{1}{2}}, t)) dt \end{aligned}$$

## Finite Volume method for hyperbolic systems of conservation laws

$$U_j^n \sim \frac{1}{\Delta x} \int_{C_j} U(x, t_n) dx, \quad F_{j+\frac{1}{2}}^n \sim \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} F(U(x_{j+\frac{1}{2}}, t)) dt$$

Approximate formula:

$$U_j^{n+1} = U_j^n - \frac{\Delta t}{\Delta x} \left( F_{j+\frac{1}{2}}^n - F_{j-\frac{1}{2}}^n \right).$$

The numerical approximation is determined by the choice of  $F_{j+\frac{1}{2}}^n$ .

$$F_{j+\frac{1}{2}}^n = \mathcal{F}(U_j^n, U_{j+1}^n), \quad \mathcal{F}(U, U) = F(U) \quad (\text{conservativity}).$$

Simple choices as centred formula  $\mathcal{F}(U, V) = \frac{1}{2}(F(U) + F(V))$  are not stable even in the linear case.

# Finite Volume method for conservation laws

In order to compute physically relevant solutions, the scheme must satisfy some discrete **discrete entropy inequality**: if  $\eta$  is an entropy for the system:

$$\frac{\eta(U_j^{n+1}) - \eta(U_j^n)}{\Delta t} + \frac{\mathcal{G}_{j+\frac{1}{2}}^n - \mathcal{G}_{j-\frac{1}{2}}^n}{\Delta x} \leq 0.$$

$\mathcal{G}_{j+\frac{1}{2}}^n$ : numerical entropy flux.

## Finite Volume method for conservation laws

**Godunov method:** solve the **Riemann problem** at interface exactly,  
i.e. :  $\forall x_{j+\frac{1}{2}}$ , find the exact solution  $U_{j+\frac{1}{2}}$  of the system with

$$U_{j+\frac{1}{2}}(x, t_n) = U_j^n \quad \text{if } x < x_{j+\frac{1}{2}}, \quad U_{j+\frac{1}{2}}(x, t_n) = U_{j+1}^n \quad \text{if } x > x_{j+\frac{1}{2}}.$$

Then set as numerical flux

$$F_{j+\frac{1}{2}}^n = \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} F(U_{j+\frac{1}{2}}(x_{j+\frac{1}{2}}, t)) dt.$$

May be difficult and expensive.

Under CFL condition, this is equivalent to set  $U_j^{n+1}$  as the average of the exact solution at  $t = t_{n+1}$  when  $U(x, t_n) = \sum_j U_j^n \mathbb{1}_{C_j}(x)$ .

## Alternatives to Godunov method

In order to avoid the exact resolution of the Riemann problem at each interface: approximate solvers and Lax-Friedrichs type schemes. Among them:

- ▶ HLL solver
- ▶ kinetic solvers
- ▶ relaxation solvers

These methods are closely linked.

In what follows we give a brief overview of the history of kinetic approach of conservation laws.

# HLL solver

A. Harten, P.D. Lax, B. Van Leer, On upstream differencing and Godunov-type schemes for hyperbolic conservation laws, SIAM Rev. (1983)

Exact solution of the Riemann problem

$$U_{j+\frac{1}{2}}(x, t) = W \left( \frac{x - x_{j+\frac{1}{2}}}{t - t_n}; U_j^n, U_{j+1}^n \right)$$

and  $W$  is a superposition of simple waves (shocks, rarefactions, contact discontinuities).

Denoting  $a_i(U)$  the eigenvalues of  $F'(U)$ :

$$\lambda^- = \min_i \{a_i(U), a_i(V)\}, \quad \lambda^+ = \max_i \{a_i(U), a_i(V)\}.$$

For  $y < \lambda^-$ :  $W(y, U, V) = U$ .

For  $y > \lambda^+$ :  $W(y, U, V) = V$ .

# HLL solver

HLL scheme :  $W(y, U, V)$  is replaced by the superposition of three constant states  $U, Z, V$ :

$$w(y, U, V) = \begin{cases} U & \text{if } y < \lambda^-, \\ Z & \text{if } \lambda^- < y < \lambda^+, \\ V & \text{else.} \end{cases}$$

# HLL solver: the numerical flux

Some more considerations lead to

$$\mathcal{F}(U, V) = \begin{cases} F(U) & \text{if } \lambda^- > 0, \\ F(V) & \text{if } \lambda^+ < 0, \\ \frac{-\lambda^- F(V) + \lambda^+ F(U)}{\lambda^+ - \lambda^-} + \frac{\lambda^+ \lambda^-}{\lambda^+ - \lambda^-} (V - U) & \text{else.} \end{cases}$$

Explicit, easy to implement.

# Kinetic interpretation of flux splitting methods

Euler equations:

$$F'(U) = A(U) = R(U)\Lambda(U)R(U)^{-1}, \quad \Lambda(U) = \text{diag}(a_i(U)).$$

By homogeneity of  $F$  the **Euler identity** holds:

$$F(U) = A(U)U.$$

Denoting  $\Lambda^\pm = \text{diag}(a_i^\pm)$  and  $A^\pm = R\Lambda^\pm R^{-1}$ :

$$F(U) = F^+(U) - F^-(U), \quad F^\pm(U) = A^\pm(U)U.$$

# Kinetic interpretation of flux splitting methods

Steger-Warming scheme:

$$F_{j+\frac{1}{2}}^n = F^+(U_j^n) - F^-(U_{j+1}^n)$$

Harten, Lax and Van Leer give a kinetic interpretation of this scheme with a Maxwellian function supported by the characteristic velocities  $a_i(U)$ .

A. Harten, P.D. Lax, B. Van Leer, On upstream differencing and Godunov-type schemes for hyperbolic conservation laws, SIAM Rev. (1983)

# Kinetic numerical methods

Y. Brenier, Résolution d'équations d'évolution quasilineaires en dimension  $N$  d'espace à l'aide d'équations linéaires en dimension  $N+1$ . JDE (1983).

Scalar conservation law

$$\partial_t U + \sum_{n=1}^N \partial_{x_n} F_n(U) = 0, \quad (x, t) \in \mathbb{R}^N \times [0, T]$$

with  $U(x, t) \in \mathcal{V} \subset \mathbb{R}$ .

Kinetic equation (**linear related equation**):

$$\partial_t s + \sum_{n=1}^N F'_n(\xi) \partial_{x_n} s = 0.$$

Maxwellian function:

$$\chi(u, \xi) = \begin{cases} 1 & \text{if } 0 < \xi < u \\ -1 & \text{if } u < \xi < 0 \\ 0 & \text{else.} \end{cases}$$

Moment operator:

$$\forall g \in L^1(\mathbb{R}), \quad Pg = \int_{\mathbb{R}} g(\xi) d\xi.$$

The following time-splitting procedure converges in  $L^1$  when  $\Delta t \rightarrow 0$ :

- ▶ Projection on the Maxwellian state:

$$s^n(x, \xi) = \chi(u^n(x), \xi).$$

- ▶ Transport:

$$\forall (x, \xi) \in \mathbb{R}^N \times \mathbb{R}, \quad s^{n+1}(x, \xi) = s^n(x - tF'(\xi)).$$

- ▶ Moment operator:

$$\forall x \in \mathbb{R}^N, \quad u^{n+1}(x) = P(s^{n+1}(x, \cdot)).$$

## Related BGK model

$$\partial_t f + \sum_{n=1}^N F'_n(\xi) \partial_{x_n} f = \frac{1}{\varepsilon} (\chi(Pf, \xi) - f). \quad (1)$$

One has

$$\int_{\mathbb{R}} \chi(U, \xi) d\xi = U, \quad \int_{\mathbb{R}} F'(\xi) \chi(U, \xi) d\xi = F(U) - F(0).$$

The same model appears in Y. Giga and T. Miyakawa, A kinetic construction of global solutions of first order quasilinear equations, *Duke Math. J.* (1983).

Convergence of (1) to weak entropy solutions of the scalar conservation law:

B. Perthame and E. Tadmor, A kinetic equation with kinetic entropy functions for scalar conservation laws, *Commun. Math. Phys.* (1991).

## Kinetic interpretation of Engquist-Osher scheme

Consider the 1D **scalar** conservation law with  $F$  strictly convex,  $UF'(U) \geq 0$ ,  $F(0) = 0$ :

$$\partial_t U + \partial_x F(U) = 0.$$

$$F^-(U) = -F(U) \quad \text{if } U < 0, \quad 0 \quad \text{else}$$
$$F^+(U) = F(U) \quad \text{if } U > 0, \quad 0 \quad \text{else.}$$

$F^+$  and  $F^-$  are increasing functions. Numerical flux of Engquist-Osher:

$$F_{j+\frac{1}{2}}^n = F^+(U_j^n) - F^-(U_{j+1}^n)$$

This scheme can be obtained as follows: for all  $n \geq 0$

- ▶ Maxwellian projection:  $f_j^n(\xi) = \chi(U_j^n, \xi)$ ,
- ▶ Upwind scheme on the transport equation:

$$f_j^{n+\frac{1}{2}}(\xi) = f_j^n(\xi) - F^{+'}(\xi) \frac{\Delta t}{\Delta x} (f_j^n(\xi) - f_{j-1}^n(\xi)) \\ + F^{-'}(\xi) \frac{\Delta t}{\Delta x} (f_{j+1}^n(\xi) - f_j^n(\xi))$$

- ▶ Moment operator:

$$U_j^{n+1} = \int_{\mathbb{R}} f_j^{n+\frac{1}{2}}(\xi) d\xi.$$

# Kinetic schemes for hyperbolic systems

Models for gas dynamics:

B. Perthame, Boltzmann type schemes for gas dynamics and the entropy property, *SINUM* (1990).

See the book B. Perthame, *Kinetic formulation of conservation laws*. Oxford lecture series in mathematics and its applications, 21 (2002) and ref. therein.

## Jin and Xin's relaxation scheme

S. Jin and Z. Xin, The relaxation schemes for systems of conservation laws in arbitrary space dimensions. CPAM (1995). 1D simplified version : consider a hyperbolic system

$$(1) \quad \partial_t U + \partial_x F(U) = 0, \quad U(x, t) \in \mathcal{V} \subset \mathbb{R}^K.$$

Relaxation approximation by a **semilinear hyperbolic system** of  $2K$  equations

$$\begin{cases} \partial_t U^\varepsilon + \partial_x V^\varepsilon = 0 \\ \partial_t V^\varepsilon + a^2 \partial_x U^\varepsilon = \frac{1}{\varepsilon} (F(U^\varepsilon) - V^\varepsilon), \quad a > 0. \end{cases}$$

Formally when  $\varepsilon \rightarrow 0$ ,  $(U^\varepsilon, V^\varepsilon) \rightarrow (U, F(U))$  and  $U$  is a solution of (1).

# Stability condition

Chapman-Enskog expansion:

$$V^\varepsilon = F(U^\varepsilon) - \varepsilon V^{(1)}.$$

$$\begin{aligned}V^{(1)} &= \partial_t V^\varepsilon + a^2 \partial_x U^\varepsilon \\&= \partial_t F(U^\varepsilon) + a^2 \partial_x U^\varepsilon + O(\varepsilon) \\&= F'(U^\varepsilon) \partial_t U^\varepsilon + a^2 \partial_x U^\varepsilon + O(\varepsilon) \\&= -F'(U^\varepsilon) \partial_x V^\varepsilon + a^2 \partial_x U^\varepsilon + O(\varepsilon)\end{aligned}$$

Hence:

$$\partial_t U^\varepsilon + \partial_x F(U^\varepsilon) = \varepsilon \partial_x \left( (a^2 I - F'(U^\varepsilon)^2) \partial_x U^\varepsilon \right).$$

A **subcharacteristic condition (TP Liu)** is necessary:  $a$  has to be large enough w.r.t.  $F'$ .

## Relaxing and relaxed schemes

**Relaxing scheme:** for  $\varepsilon > 0$  fixed, fractional step method:

- 1) Upwind scheme on the homogeneous part.
- 2) Exact resolution of the source-term on  $[t_n, t_{n+1}]$ :

$$\begin{cases} \partial_t U^\varepsilon = 0 \\ \partial_t V^\varepsilon = \frac{1}{\varepsilon} (F(U^\varepsilon) - V^\varepsilon). \end{cases}$$

Obtention of the **relaxed scheme** by making  $\varepsilon \rightarrow 0$  in the relaxed scheme. A **Lax-Friedrichs** type scheme is obtained:

$$U_j^{n+1} = U_j^n - \frac{\Delta t}{2\Delta x} (F(U_{j+1}^n) - F(U_{j-1}^n)) + a \frac{\Delta t}{2\Delta x} (U_{j+1}^n - 2U_j^n + U_{j-1}^n).$$

Higher order in space and time is possible and easy.

Convergence in the 1D scalar case for relaxing and relaxed schemes: D. A.-D. and R. Natalini, *Convergence of relaxation schemes for conservation laws*, App Anal. (1996).

Convergence of the model: R. Natalini, CPAM (1996).

## BGK interpretation of Jin and Xin's model

$$\begin{cases} \partial_t U^\varepsilon + \partial_x V^\varepsilon = 0 \\ \partial_t V^\varepsilon + a^2 \partial_x U^\varepsilon = \frac{1}{\varepsilon} (F(U^\varepsilon) - V^\varepsilon), \quad a > 0. \end{cases}$$

Diagonalization:

$$f^- = \frac{1}{2} \left( U - \frac{V}{a} \right), \quad f^+ = \frac{1}{2} \left( U + \frac{V}{a} \right).$$

Denoting  $M^\pm(U) = \frac{\pm F(U) + aU}{2a}$ :

$$\begin{cases} \partial_t f^- - a \partial_x f^- = \frac{1}{\varepsilon} (M^-(f^- + f^+) - f^-) \\ \partial_t f^+ + a \partial_x f^+ = \frac{1}{\varepsilon} (M^+(f^- + f^+) - f^+) \end{cases}$$

This is formally a discrete **vectorial** BGK model:

$$f = \begin{pmatrix} f^- \\ f^+ \end{pmatrix} \in \mathbb{R}^{2K}, \quad Pf = f^- + f^+, \quad M = \begin{pmatrix} M^- \\ M^+ \end{pmatrix}$$

The moment operator  $P$  is an integration with the counting measure satisfying

$$PM(U) = U, \quad P\Lambda M(U) = F(U)$$

with  $\Lambda = \text{diag}(-aI_K, aI_K)$ . Discrete analogue of

$$\int_{\mathbb{R}} M(U, \xi) d\xi = U, \quad \int_{\mathbb{R}^3} \begin{pmatrix} 1 \\ \xi \\ \frac{1}{2}|\xi|^2 \end{pmatrix} \xi M(U, \xi) d\xi = F(U)$$

for Euler equations.

# Generalization

Multidimensional hyperbolic system

$$\partial_t U + \sum_{d=1}^D \partial_{x_d} F_d(U) = 0, \quad U(x, t) \in \mathcal{V} \subset \mathbb{R}^K.$$

BGK model:

$$\partial_t f^\varepsilon + \sum_{d=1}^D \Lambda_d \partial_{x_d} f^\varepsilon = \frac{1}{\varepsilon} (M(Pf^\varepsilon) - f^\varepsilon), \quad f^\varepsilon(x, t) \in (\mathbb{R}^K)^L.$$

$$\Lambda_d = \text{diag}(v_{d,1} \mathbf{1}_K, \dots, v_{d,L} \mathbf{1}_K), \quad v_{d,l} \in \mathbb{R},$$

$$P \in \mathcal{L}((\mathbb{R}^K)^L, \mathbb{R}^K), \text{ and } M = (M_1, \dots, M_L): \mathcal{V} \rightarrow (\mathbb{R}^K)^L.$$

## Compatibility conditions

$$\forall U \in \mathcal{V}, \quad PM(U) = U, \quad P\Lambda_d M(U) = F_d(U), \quad d = 1, \dots, D.$$

Often  $Pf = \sum_l f_l$ .

Chapman-Enskog expansion can be generalized:

$$U^\varepsilon = Pf^\varepsilon$$

$$\partial_t U^\varepsilon + \sum_d \partial_{x_d} F_d(U^\varepsilon) = \varepsilon \sum_d \left( \partial_{x_d} \sum_j B_{dj}(U^\varepsilon) \partial_{x_d} U^\varepsilon \right)$$

with

$$B_{dj}(U) = P\Lambda_d \Lambda_j M'(U) - F'_d(U) F'_j(U).$$

# Stability

Convergence of  $U^\varepsilon = Pf^\varepsilon$  towards an entropy solution of the system of conservation laws?

**Scalar case:**  $U_0$ : initial condition. We suppose that the Maxwellian functions are **monotone nondecreasing** functions:

$$\forall U \in [-\|U_0\|_\infty, \|U_0\|_\infty], \quad M'_l(U) \geq 0, \quad l = 1, \dots, L.$$

Example: Jin and Xin's model:  $L = 2$ ,

$$M^-(U) = \frac{-F(U) + aU}{2a}, \quad M^+(U) = \frac{F(U) + aU}{2a}.$$

$M^-$  and  $M^+$  are increasing functions if and only if the **subcharacteristic condition** is satisfied:

$$\forall U \in [-\|U_0\|_\infty, \|U_0\|_\infty], \quad -a \leq F'(U) \leq a.$$

## Scalar case

**Theorem 1** R. Natalini, JDE 1998.  $U_0 \in L^\infty(\mathbb{R}^D)$  and  $f_0 = M(U_0)$ . For all  $l$ ,  $M_l$  is nondecreasing on  $[-\|U_0\|_\infty, \|U_0\|_\infty]$ . For  $\varepsilon > 0$  fixed the BGK system has a unique solution  $f^\varepsilon \in C([0, \infty[, L^1_{loc} \cap L^\infty)$ . Moreover

$$M_l(-\|U_0\|_\infty) \leq f_l^\varepsilon \leq M_l(\|U_0\|_\infty), \quad l = 1, \dots, L.$$

Main argument: The BGK system is quasimonotone (B. Hanouzet and R. Natalini, Diff. Int. Eq. 1996).

**Theorem 2** R. Natalini, JDE 1998. Same assumptions.  $U^\varepsilon = Pf^\varepsilon$  converges to the unique entropy solution of the Cauchy problem for the conservation law.

Boundary conditions: V. Milisic, Proc. Amer. Math. Soc. 2003.

# Systems

F. Bouchut, J. Stat. Phys. 1999: let  $E$  be a set of entropies for the system of conservation laws. For  $\eta \in E$  a related kinetic entropy  $H_\eta$  is a convex function s.t.  $G_{l,\eta} = H_\eta \circ M_l$  satisfies:

- ▶  $PG_\eta(U) = \eta(U)$ ,
- ▶  $\forall U_f$  s.t.  $f = M(U_f)$ ,  $PG_\eta(U_f) \leq PH_\eta(f)$ .

The existence of  $H_\eta$  for all  $\eta \in E$  is equivalent to the fact that  $\eta \in E$   $(M'_l)^t \eta''$  is symmetric and

$$\forall U \in \mathcal{V}, \quad \sigma(M'_l(U)) \subset [0, +\infty[; \quad l = 1, \dots, L.$$

In this case the Chapman-Enskog expansion is  $\eta$ -dissipative.

see also D. Serre, Ann. Inst. H. Poincaré 2000 for 2x2 1D systems.  
S. Bianchini, CPAM 2006 for 1D strictly hyperbolic systems (data small in BV).

## Examples of BGK vectorial models

1D, L=2.  $Pf = \sum_l f_l$ .

$$\begin{cases} \partial_t f_1 + \lambda^- \partial_x f_1 = \frac{1}{\varepsilon} (M_1(f_1 + f_2) - f_1) \\ \partial_t f_2 + \lambda^+ \partial_x f_2 = \frac{1}{\varepsilon} (M_2(f_1 + f_2) - f_2) \end{cases}$$

with

$$M_1(U) = \frac{\lambda^+ U - F(U)}{\lambda^+ - \lambda^-}, \quad M_2(U) = \frac{-\lambda^- U + F(U)}{\lambda^+ - \lambda^-},$$

Stability conditions:  $(M_l')^t \eta''$  is symmetric for all entropy  $\eta$ .

$$\lambda^- \leq F'(U) \leq \lambda^+.$$

## 2D version

$$L=4. Pf = \sum_l f_l.$$

$$\Lambda_1 = \begin{pmatrix} \lambda_1^- / \kappa & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \lambda_1^+ / \kappa & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad \Lambda_2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & \lambda_2^- / \kappa & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \lambda_2^+ / \kappa \end{pmatrix}.$$

Stability conditions:  $(M_l')^t \eta''$  is symmetric for all entropy  $\eta$ .

$$\frac{1}{2} \lambda_d^- \leq F_d'(U) \leq \frac{1}{2} \lambda_d^+.$$

see [D. A-D. and R. Natalini, SINUM 2000](#) for more examples with linear combinations of  $U$  and  $F_d(U)$ .

## Flux decomposition in 1D

As for Engquist-Osher or Steger-Warming, suppose that  $F(U) = F^+(U) - F^-(U)$  with  $\sigma(F^{\pm'}(U)) \subset [0, \infty[$ . BGK system:  
 $\lambda > 0$ ,  $U = \sum_l f_l$ .

$$\partial_t f_1 - \lambda \partial_x f_1 = \frac{1}{\varepsilon} \left( \frac{F^-(U)}{\lambda} - f_1 \right)$$

$$\partial_t f_2 = \frac{1}{\varepsilon} \left( U - \frac{F^+(U) + F^-(U)}{\lambda} - f_2 \right)$$

$$\partial_t f_3 + \lambda \partial_x f_3 = \frac{1}{\varepsilon} \left( \frac{F^+(U)}{\lambda} - f_3 \right)$$

see also F. Bouchut, Entropy satisfying flux vector splitting and kinetic BGK models, Numer. Math. 2003

# Numerical methods

D. A-D. and R. Natalini, SINUM 2000

Each BGK model provides a numerical method by the same procedure as above:

1) Numerical approximation of the BGK model by fractional step method:

- ▶ Upwind method on the free transport equations: obtention of  $f_j^{\varepsilon, n+1/2}$
- ▶ Exact resolution of the source-term:

$$f_j^{\varepsilon'} = \frac{1}{\varepsilon} (M(Pf_j^\varepsilon) - f_j^\varepsilon)$$

We have  $Pf^{\varepsilon'} = 0$  so

$$U_j^{\varepsilon, n+1} = Pf_j^{\varepsilon, n+1/2},$$

$$f_j^{\varepsilon, n+1} = M(U_j^{\varepsilon, n+1}) + e^{-\Delta t/\varepsilon} \left( f_j^{\varepsilon, n+1/2} - M(U_j^{\varepsilon, n+1}) \right).$$

2) Relaxed limit of the scheme:  $\varepsilon \rightarrow 0$

- ▶ Projection onto equilibrium:

$$f_j^n = M(U_j^n)$$

- ▶ Transport (upwind). In 1D

$$f_j^{n+\frac{1}{2}} = f_j^n - \frac{\Delta t}{\Delta x} \Lambda(f_{j+\frac{1}{2}}^n - f_{j-\frac{1}{2}}^n)$$

$$U_j^{n+1} = P f_j^{n+\frac{1}{2}}.$$

Same procedure as Brenier (1983): transport-collapse.

## First order relaxed numerical flux

If  $f_{j+\frac{1}{2}}^n = \Phi(f_j^n, f_{j+1}^n)$  then

$$U_j^{n+1} = U_j^n - \frac{\Delta t}{\Delta x} (F_{j+\frac{1}{2}}^n - F_{j-\frac{1}{2}}^n)$$

with

$$F_{j+\frac{1}{2}}^n = \mathcal{F}(U_j^n, U_{j+1}^n) = P\Lambda\Phi(M(U_j^n), M(U_{j+1}^n))$$

Consistence:

$$\mathcal{F}(U, U) = P\Lambda\Phi((MU), M(U)) = F(U).$$

**Scalar case:** convergence to the unique entropy solution of Cauchy Problem (monotony).

Boundary conditions: [D. A-D. and V. Milisic, Numer. Math. 2004.](#)

# Application to the presented BGK models

Application to model 2: HLL method.

Application to FDM: flux vector splitting.

## Higher order schemes

In **time**: RK2 Heun. In **space**, there are 2 viewpoints:

I. Replace the upwind scheme by a second order MUSCL type scheme:  $f_j^{n+\frac{1}{2}}$  is obtained by affine reconstruction, exact transport and exact average on  $C_j$ .

Works well, good stability properties, at least in the scalar case (TVD,  $L^\infty$ ).

Problems:

Computation of  $K \times L$  slopes  $\forall j, n$ .

For systems: positivity is not necessarily preserved.

II. Forget BGK and apply the second order procedure on the relaxed numerical flux :

1) Affine reconstruction of  $U_j^n$ :

$$\overline{U}_j^n(x) = U_j^n + \sigma_j^n(x - x_j).$$

2) Modified numerical flux:

$$\overline{F}_{j+\frac{1}{2}}^n = \mathcal{F} \left( \overline{U}_j^n(x + \Delta x/2), \overline{U}_{j+1}^n(x - \Delta x/2) \right).$$

## Interest and drawbacks of such methods

- ▶ BGK models provide flexible, easy to implement finite volume schemes.
- ▶ Great stability
- ▶ Drawback: contact discontinuities are not accurate

## Other numerical techniques

- ▶ Finite elements (T. Katsaounis and C. Makridakis, *Math of Comp.* 2001).
- ▶ Discontinuous Galerkin method, lattice Boltzmann method: B. Graille, *JCP* 1994, Coulette et al, *Computers and Fluids* 2019
- ▶ Residual distribution schemes: D. Torlo, PhD thesis with R. Abgrall, 2020.

## Other problems

- ▶ Parabolic problems: kinetic models with diffusive scaling: F. Bouchut, F. Guarguaglini, R. Natalini, *Indiana Univ. Math. J.* 2000.  
D. A-D., R. Natalini, S. Tang, *Math. of Comp.* 2003.
- ▶ Incompressible Navier-Stokes equations: M.F. Carfora, R. Natalini, *M2ANB* 2008,  
Bouchut et al, *SIAM J. Comput. Math.* 2018.
- ▶ A non conservative hyperbolic system : the Euler bitemperature model for plasma out of thermic equilibrium: will be the topic of the second talk.