

The hyperbolic dead water phenomenon

Virtual Summer school on Kinetic and fluid equations for collective dynamics

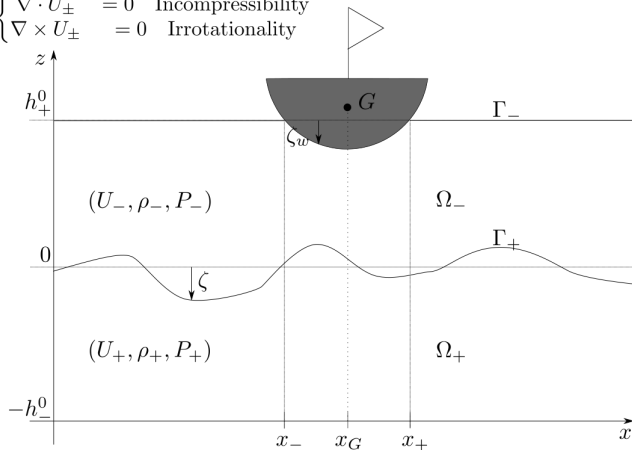
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Notations

$$\begin{cases} \nabla \cdot U_{\pm} = 0 & \text{Incompressibility} \\ \nabla \times U_{\pm} = 0 & \text{Irrotationality} \end{cases}$$



Outline of the talk

- 1 Notations and figure
- 2 The non-conservative hyperbolic system
- 3 The dead water phenomenon
- 4 Conclusion

Definition of the unknowns (h_{\pm}, Q_{\pm}) and equations

$$\begin{cases} h_+ = h_+^0 + \zeta, & h_- = h_-^0 + \zeta_w - \zeta, & \zeta_w(t, x) = \zeta_e(x - x_G(t)), \\ Q_+ = \int_{-h_+^0}^{\zeta} U_+ \cdot e_x dx, & Q_- = \int_{\zeta}^{h_-^0 + \zeta_w} U_- \cdot e_x dx. \end{cases} \quad (1)$$

Theorem (Nonconservative hyperbolic system in (h_{\pm}, Q_{\pm}))

$$\begin{cases} \partial_t h_{\pm} + \partial_x Q_{\pm} = 0, \\ \partial_t Q_+ + gh_+ \partial_x h_+ + \partial_x \left(\frac{Q_+^2}{h_+} \right) = -\frac{h_+ \partial_x(P)}{\rho_+} \\ \partial_t Q_- - gh_- \partial_x h_- + \partial_x \left(\frac{Q_-^2}{h_-} \right) = -\frac{h_- \partial_x(P)}{\rho_-} - gh_- \partial_x \zeta_w \end{cases} \quad (2)$$

where $\underline{P} = P|_{z=\zeta}$ is the pressure at the interface.

Theorem (Expression of the pressure at the interface)

$$\begin{cases} -\nabla \cdot \left(\left[\frac{h_+}{\rho_+} + \frac{h_-}{\rho_-} \right] \nabla(\underline{P}) \right) = -\partial_t^2 \zeta_w + a_{\text{FS}}, & \forall X \in \mathbb{R}^d, \\ \lim_{|X| \rightarrow \infty} \underline{P} = P_{\text{atm}} + \rho_- g h_-^0. \end{cases} \quad (3)$$

with $a_{\text{FS}} = a_{\text{FS},+} + a_{\text{FS},-}$, where $a_{\text{FS},i} = -\partial_t \partial_x Q_i$ when there is no boat.

The hyperbolic system

New unknown : $V(t, x) = \frac{Q_+(t, x+x_G(t))}{h_+(t, x+x_G(t))} - \gamma \frac{Q_-(t, x+x_G(t))}{h_-(t, x+x_G(t))}$ with $\gamma = \frac{\rho_-}{\rho_+}$.

Theorem (Hyperbolic system in (ζ, V))

With the notation $\bar{V}_\pm = \frac{Q_\pm}{h_\pm}$

$$\begin{cases} \partial_t \zeta + \partial_x (h_+ (\bar{V}_+ - \dot{x}_G)) = 0 \\ \partial_t V - \dot{x}_G \partial_x V + (1 - \gamma) g \partial_x \zeta + \bar{V}_+ \partial_x \bar{V}_+ - \gamma \bar{V}_- \partial_x \bar{V}_- = 0 \end{cases} \quad (4)$$

Reconstruction of \bar{V}_+ and \bar{V}_-

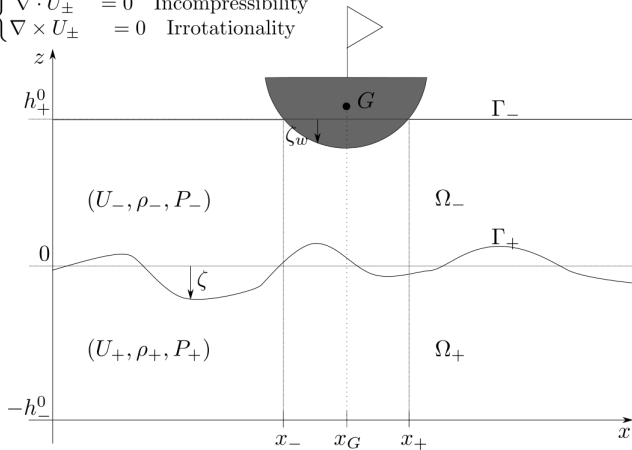
Using the constraint $h_+ + h_- = \zeta_e(x - x_G)$, we can obtain

Theorem (Reconstruction formula)

$$\begin{cases} \bar{V}_+ &= \frac{h_- V + \gamma \dot{x}_G \zeta_w}{h_- + \gamma h_+}, \\ \bar{V}_- &= \frac{-h_+ V + \dot{x}_G \zeta_w}{h_- + \gamma h_+}. \end{cases} \quad (5)$$

The 1D case allows for explicit computation. Proving that there is a reconstruction formula in 2D is non trivial.

$$\begin{cases} \nabla \cdot U_{\pm} = 0 & \text{Incompressibility} \\ \nabla \times U_{\pm} = 0 & \text{Irrotationality} \end{cases}$$



The Newton's equation

Original Newton's equation : $m\ddot{x}_G = F_0 + F_P$ with

$$F_P = - \int_{\mathbb{R}} P_{z=h_-^0 + \zeta_w} \partial_x \zeta_w dx$$

Shallow water regime, we have $P|_{z=\zeta_w} = \underline{P} + \rho_- gh_-$, i.e. the non-hydrostatic component is neglected.

$$\begin{cases} M(\zeta, \zeta_e) = \int_{\mathbb{R}} \frac{\zeta_w^2}{h_+/\rho_+ + h_-/\rho_-} dx, \\ F_w = \rho_- g \int_{\mathbb{R}} \zeta_e \partial_x \zeta dx - g \int_{\mathbb{R}} \frac{\zeta_e (h_+ + h_-)}{h_+/\rho_+ + h_-/\rho_-} \partial_x \zeta_e dx \\ \quad - \int_{\mathbb{R}} \frac{\zeta_e}{h_+/\rho_+ + h_-/\rho_-} \partial_x (h_+^2 \bar{V}_+ + h_-^2 \bar{V}_-) dx. \end{cases} \quad (6)$$

Theorem (The Newton's equation with the added mass)




$$(m + M(\zeta, \zeta_e))\ddot{x}_G = F_0 + F_w \quad (7)$$

With periodic boundary conditions and a large grid, using a finite volume method and a Lax-Friedrichs scheme we obtain the following numerical results.

Simulation

- Add transparent boundary conditions and study the IBVP associated, coupled with the ODE \rightarrow long time existence result
- Take into account dispersive effects \rightarrow dispersive IBVP : appearance of boundary layers
- Extend the study to the case of a non flat surface \rightarrow four equations and the contact points between the boat and the wave are no longer fixed
- Extend our study to the 2D case \rightarrow non explicit computations

Thank you for your attention !

-  Tatsuo Iguchi and David Lannes.
Hyperbolic free boundary problems and applications to wave-structure interactions.
2018.
-  David Lannes.
On the dynamics of floating structures.
Annals of PDE, 3(1):11, 2017.
-  Matthieu J Mercier, Romain Vasseur, and Thierry Dauxois.
Resurrecting dead-water phenomenon.
Nonlinear Processes in Geophysics, 18(2):193–208, 2011.



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