

# Constraint Programming

## Lecture 1. Constraint Satisfaction Problems

Ruslan Sadykov

INRIA Bordeaux — Sud-Ouest



6th January 2022

# Course organisation

- ▶ 5 lectures/exercice labs + 5 computer labs.
- ▶ Exercice labs : solving exercises on a paper
- ▶ 2-3 labs : introduction to a CP solver
- ▶ 2-3 labs : **project**
- ▶ Evaluation : 50% of the mark for the project + 50% of the mark for the exam (TD notés).
- ▶ Course web-page :

[www.math.u-bordeaux.fr/  
~sadykov/teaching/MSE3315C/](http://www.math.u-bordeaux.fr/~sadykov/teaching/MSE3315C/)

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Applications of Constraint Programming

Constraint Satisfaction Problems

Modelling examples

Solving Constraint Satisfaction Problems



# Solving technology

A **solving technology** offers methods and tools for :

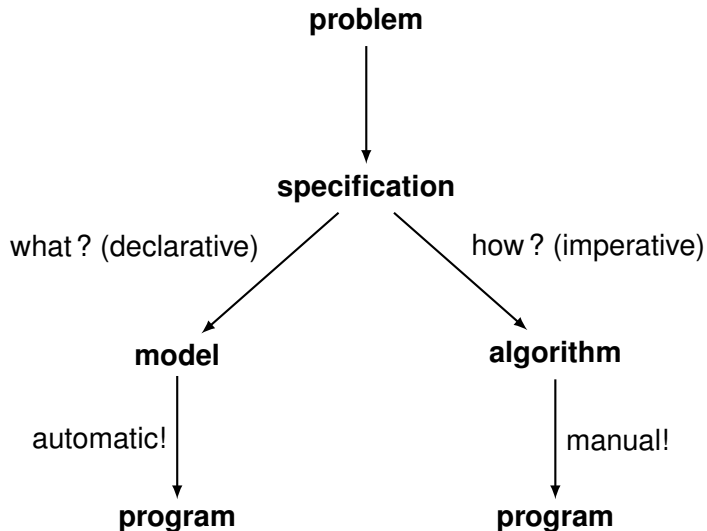
- ▶ **Modelling** constraint problems in **declarative** and/or
- ▶ **Solving** constraint problems intelligently
  - Search** : Explore the space of candidate solutions
  - Inference** : Reduce the space of candidate solutions
  - Search** : Exploit solutions to easier (sub)problems

A **solver** is a software that takes a model as input and tries to solve the modelled problem.

**Combinatorial (=discrete) optimisation** covers satisfaction and optimisation problems, for variables over *discrete sets*

Source : Pierre Flener

# Modelling vs. Programming



Source : [Pierre Flener](#)

# Examples of solving technologies

General-purpose solvers, taking a model as input :

- ▶ Boolean satisfiability (SAT)
- ▶ SAT modulo theories (SMT)
- ▶ (Mixed) integer linear programming (IP and MIP)
- ▶ Constraint Programming (CP)
- ▶ ...
- ▶ Hybrid technologies

Techniques, usually without modelling and solvers :

- ▶ Dynamic programming (DP)
- ▶ Greedy algorithms
- ▶ Approximation algorithms
- ▶ Generic algorithms (GA)
- ▶ ...

# Constraint Programming Technology

Constraint Programming (CP) offers methods and tools for :

- ▶ **Modelling** constraint problems in a **high-level** language and
- ▶ **Solving** constraint problems intelligently by :
  - ▶ either default **search** upon pushing a button
  - ▶ or **systematic search** guided by user-given strategies
  - ▶ or **local search** guided by user-given (meta-)heuristics
  - ▶ or **hybrid search**

plus **inference**, called **propagation**, but little relaxation.

Slogan of CP :

**Constraint Program** = **Model** [+ **Search**]

Source : Pierre Flener

# Limitations of CP

CP is **definitely not**

- ▶ a **magic method**
  - ▶ A priori, it is not better than other methods (integer linear programming, dynamic programming, local search, etc...)
  - ▶ It depends on the problem type !
- ▶ a ~~« **press button** »~~ method, at least for the moment
  - ▶ It is necessary to understand the method (what is going on « inside » it)
  - ▶ It is necessary to « guide » the solution

Source : [Antoine Jeanjean](#)

# Objectives of the course

- ▶ To know for which (classes of) problems the CP methods is good
- ▶ To know how to model efficiently these problems
- ▶ To know which modelling languages and CP solvers exist and to know how to use them
- ▶ To understand how these solvers work inside

# Particularities of CP

- ▶ We work with decision problems — **constraint satisfaction problems (CSP)**  
(if an optimisation problem, a series of CSPs is solved)
- ▶ Large modelling possibilities  
(non-linear, logical, explicit constraints)
- ▶ Use of problem constraints in an active way to limit the search space  
(Additional constraints may make a problem easier)

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7					1			9
2		6			3	8		
						2		3
	1	3	6			9	5	
		8		4	7			
								6
		9		5		3	8	2

- ▶ There are 81 cells where a digit from 1 to 9 can be put
- ▶ We need to put digits to cells in such a way that every row (column, or a block of 9 cells) contains different numbers

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In CP, the problem is solved more or less the same way you solve a sudoku(!)

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# Application domains

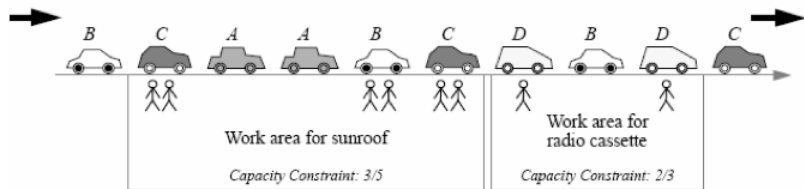
- ▶ Location problems
- ▶ Diagnosis and verification
- ▶ Planning problems
- ▶ Scheduling and timetabling problems
- ▶ Cutting and packing
- ▶ Logistic problems



# Real-life application I — Car Sequencing

## Production Requirements:

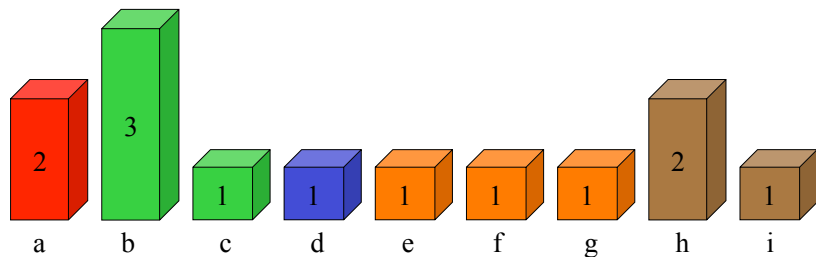
	Model A	Model B	Model C	Model D	
Options (✓ = required, ✗ = not):					
Sunroof	✗	✓	✓	✗	
Radio cassette	✓	✗	✓	✓	
Air-conditioning	✓	✓	✗	✓	
Anti-rust treatment	✗	✓	✓	✓	
Power brakes	✓	✗	✓	✗	
Number of cars required:	30	30	20	40	Total: 120



Source : Alan M. Frisch

## Real-life application II — Steel mill slab design

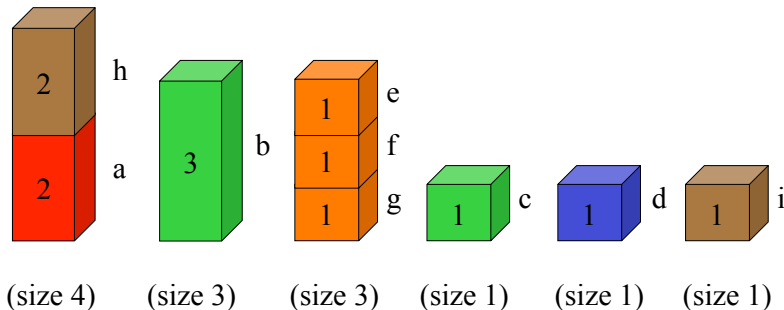
- ▶ The mill can make  $\sigma$  different slab sizes.
- ▶ For each order  $j \in J$ , we know a *colour* (route through the mill) and a *weight*
- ▶ We need to pack orders onto slabs such that the total slab capacity is minimized subject to
  - ▶ capacity (slab size) constraints
  - ▶ colour constraints (no more than  $p$  colours per slab)



Source : Alain Frisch

# Steel mill slab design — an example solution

- ▶ Slab sizes :  $\sigma = \{1, 2, 4\}$ .
- ▶ 9 orders
- ▶ 5 different colours
- ▶ Maximum number of different colours per slab is 2



Source : [Alain Frisch](#)

## Real-life application III — Sports scheduling

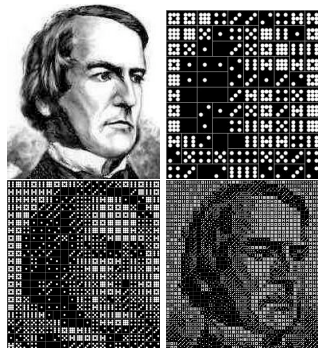
There several sport teams. In the championship, each team should play with each other team. We need a schedule : for each round we need to determine the pairs of teams playing with each other. We can have additional constraints.

Round 1	Round 2	Round 3	Round 4	Round 5	Round 6	Round 7
1 vs 8	2 vs 8	4 vs 7	3 vs 6	3 vs 7	1 vs 5	2 vs 4
2 vs 3	1 vs 7	3 vs 8	5 vs 7	1 vs 4	6 vs 8	5 vs 6
4 vs 5	3 vs 5	1 vs 6	4 vs 8	2 vs 6	2 vs 7	7 vs 8
6 vs 7	4 vs 6	2 vs 5	1 vs 2	5 vs 8	3 vs 4	1 vs 3

# A « fun » application — Domino portraits

**Aim** : find a good approximation of an image using the dominos from an integer number of boxes.

**Example** on the right : A portrait of *George Boole*, and then a sequence of domino portraits generated using 1, 4, 16 domino boxes.



Source : (Cambazard, Horan, O'Mahony, O'Sullivan, 2008)

# Success stories by CP users and contributors



cādence

Google

JEPPESEN  
A BOEING COMPANY

QUINTIQ

SAP

THALES



CISCO

IBM



RedPrairie

SIEMENS

XEROX



FICO

intel

ORACLE



TACTON

...

Success stories : CP = **technology of choice** in scheduling, configuration, personnel rostering, timetabling, ...

Source : Pierre Flener

# Real-life application at Bouygues e-lab

- ▶ Table plans for the group conferences
- ▶ Planning for interior works on construction sites
- ▶ Personnel planning
- ▶ Marketing campaign planning
- ▶ Projects exploiting the CP method
  - ▶ Aids planning (on TF1)
  - ▶ Planning for « call-centers »

Source : Antoine Jeanjean

# Other applications

More applications of the web-site

`www.csplib.org`

There are 88 applications !



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# Constraint Satisfaction Problem (CSP)

CSP is a triple  $\langle \mathbf{X}, \mathbf{D}, \mathbf{C} \rangle$ , where :

- ▶  $\mathbf{X}$  is the set of variables  $\{x_1, \dots, x_n\}$ ,
- ▶  $\mathbf{D}$  is the set of domains  $\{D_{x_1}, \dots, D_{x_n}\}$  (sets of possible values) for these variables,
- ▶  $\mathbf{C}$  is the set of constraints

$$\{C_i(x_{i_1}, \dots, x_{i_n})\}_{i \in |\mathbf{C}|}.$$

Every constraint  $C_i$  restricts the values that variables  $\{x_{i_1}, \dots, x_{i_n}\}$  can take simultaneously.

# Domains

The domains can be

- ▶ finite sets :

$\{1, 2, \dots, n\}$ ,  $\{2, 3, 5\}$ ,  $\{\text{red, black, blue}\}$ ;

- ▶ intervals :

$[0, k]$ ,  $[1.2, 5.9]$ ;

- ▶ trees (not in this course).

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# Constraints

Constraints can be

- ▶ logic :

$$x = 1 \text{ or } y = 3, \quad x = 2 \Rightarrow y = 4;$$

- ▶ arithmetic :

$$x > y, \quad z = 2x + 3y - 5;$$

- ▶ explicit (tuples of possible values) :

$$(x, y) \in \{(0, 0), (1, 0), (2, 2)\}, \quad (x, y, z) \in \{(1, 2, 3), (2, 3, 4)\};$$

- ▶ complex (global) :

$$\text{all-different}(x_1, \dots, x_n).$$

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# Arity of constraints

Constraint can have an arbitrary **arity** :

- ▶ A constraint is **unary** if it contains one variable ( $x = 4$ )
- ▶ A constraint is **binary** if it contains two variables ( $x + y = 9$ )
- ▶ A constraint is  **$n$ -ary** if it contains  $n$  variables

The notion «  $n$ -ary » is used for a constraint such that the number of variables it contains is not known a priori (for example, `all - different`)

# Solutions

**Solution** is an assignment of values  $(v_1, \dots, v_n)$  to variables  $(x_1, \dots, x_n)$  such that

- ▶ the values are in domains of variables :  $v_j \in D_{x_j}, \forall j$ ;
- ▶ all constraints  $C_i$  are satisfied.

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Solve a CSP  $\Leftrightarrow$  determine if it is satisfiable or not.

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## An example

- ▶ Variables :  $x, y$  and  $z$ .
- ▶ Domains :  $D_x = D_y = D_z = \{1, 2, 3\}$ .
- ▶ One constraint :  $x + y = z$ .
- ▶ Solutions :  $(1, 1, 2), (1, 2, 3), (2, 1, 3)$ .

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# Problem types in CP

- ▶ Find a solution, if one exists (classic).
- ▶ Find all solutions.
- ▶ Find a solution which minimizes or maximizes a criterion (solved using **dichotomy**).



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# Dichotomy

## General algorithm (minimisation)

Find a lower bound (**LB**) and upper bound (**UB**) for the value of the objective function;

**while** **UB** – **LB** *is large* **do**

    test  $\leftarrow$  **LB** +  $\frac{\mathbf{UB}-\mathbf{LB}}{2}$ ;

**if** *exists a solution*  $\leq$  test **then**

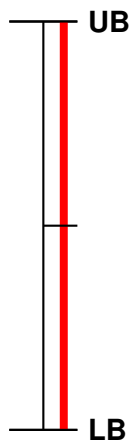
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        save this solution;

**else**

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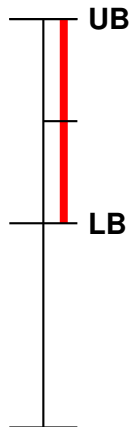
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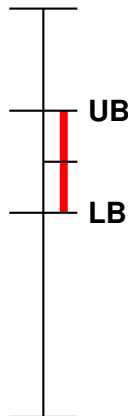
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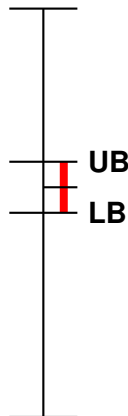
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## Example



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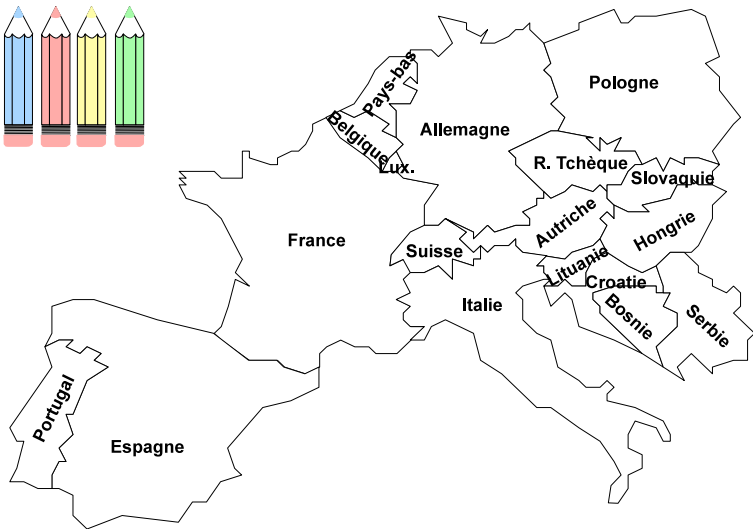
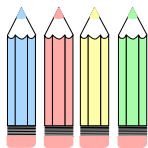
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**Modelling examples**

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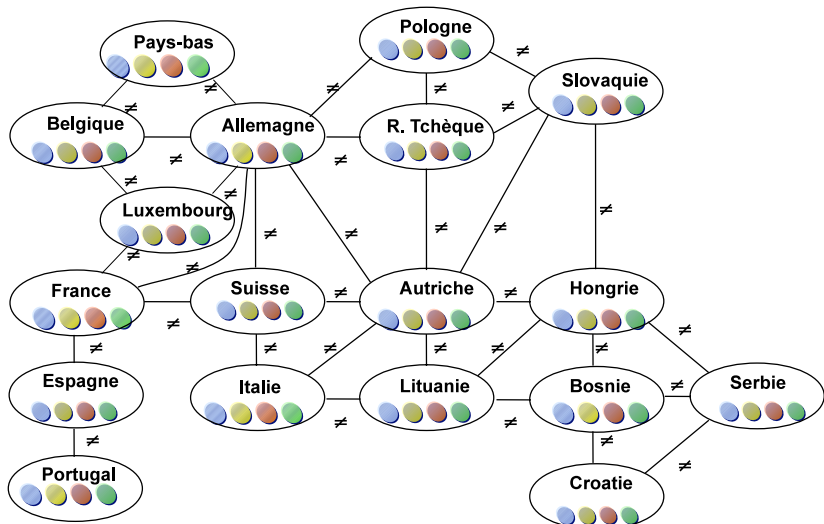
# Example I — Map coloring



Source : [Philippe Baptiste](#)

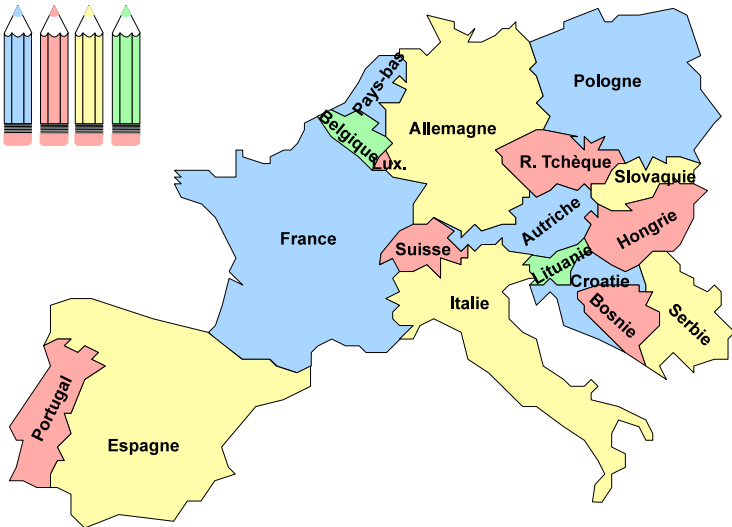
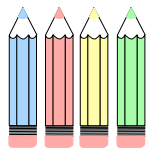


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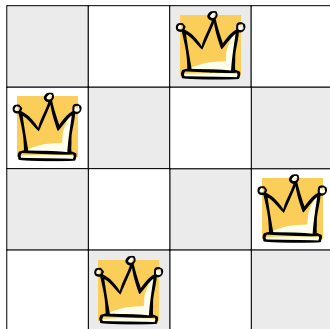
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Source : Philippe Baptiste

## Example II — $N$ queens

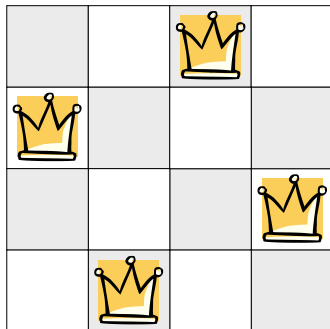
Given a chessboard with  $N \times N$  cells, put  $N$  queens in such a way that no queen is able to capture another one.



- ▶ Variables :
- ▶ Domains :
- ▶ Constraints :

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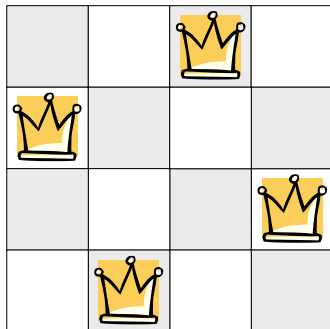
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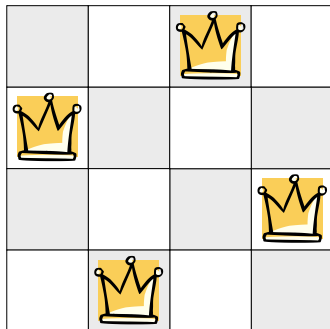
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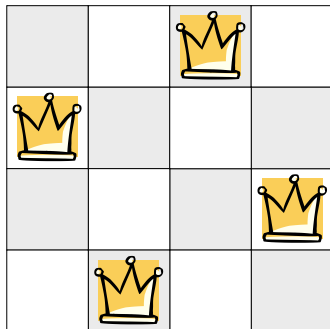
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  - ▶  $x_i \neq x_j, \forall i, j, 1 \leq i < j \leq N,$
  - ▶  $x_i \neq x_j + (j - i), 1 \leq i < j \leq N,$
  - ▶  $x_i \neq x_j + (i - j), 1 \leq i < j \leq N.$

## Example II — $N$ queens

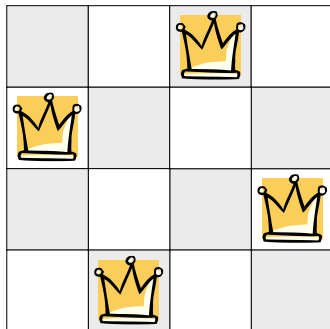
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## Example III — Sudoku

	3		4		5		7	
6	2			8		4		
7					1			9
2		6			3	8		
						2		3
	1	3	6			9	5	
		8		4	7			
								6
		9		5		3	8	2

► Variables :

► Domains :

Constraints :

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Constraints :

- ▶ **Variables** :  $x_{ij}$  — digit in cell  $(i, j)$ .
- ▶ **Domains** :

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	3		4		5		7	
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- ▶ **Variables** :  $x_{ij}$  — digit in cell  $(i, j)$ .
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- ▶ **Variables** :  $x_{ij}$  — digit in cell  $(i, j)$ .
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### Constraints :

- ▶ The digits in each line are different :  
 $\text{all-different}(x_{i1}, x_{i2}, \dots, x_{i9}), 1 \leq i \leq 9,$
- ▶ The digits in each column are different :  
 $\text{all-different}(x_{1j}, x_{2j}, \dots, x_{9j}), 1 \leq j \leq 9,$
- ▶ The digits in each block  $3 \times 3$  are different :  
 $\text{all-different}(x_{3k+1,3l+1}, x_{3k+1,3l+2}, \dots, x_{3k+3,3l+3}),$   
 $0 \leq k, l \leq 2.$

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## Example IV - Giving a change

We are interested in modelling a vending machine. A user inserts coins for a total value of  $T$  eurocents, then he selects a drink for the price of  $P$  eurocents. We need to calculate the change to give, knowing that the machine has  $E_2$  coins of 2€,  $E_1$  coins of 1€,  $C_{50}$  coins of 50 eurocents,  $C_{20}$  coins of 20 eurocents, and  $C_{10}$  coins of 10 eurocents.

- ▶ **Variables** :  $x_{E_2}, x_{E_1}, x_{C_{50}}, x_{C_{20}}, x_{C_{10}}$ .
- ▶ **Domains** :  $D_{x_{E_2}} = \{0, 1, \dots, E_2\}, D_{x_{E_1}} = \{0, 1, \dots, E_1\}, \dots$
- ▶ **Constraint** :

$$200x_{E_2} + 100x_{E_1} + 50x_{C_{50}} + 20x_{C_{20}} + 10x_{C_{10}} = T - P$$

- ▶ If we want to minimize a number of coins to give, we need to specify the **objective function** :

$$\min x_{E_2} + x_{E_1} + x_{C_{50}} + x_{C_{20}} + x_{C_{10}}$$

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# Contents

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Applications of Constraint Programming

Constraint Satisfaction Problems

Modelling examples

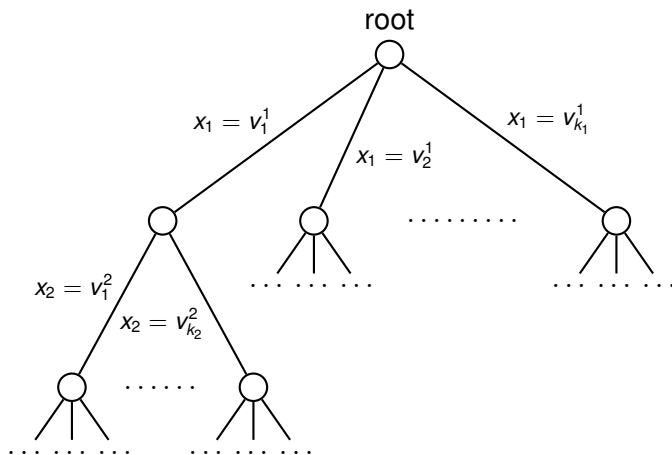
**Solving Constraint Satisfaction Problems**

# Main idea

The method of Constraint Programming (which solves a CSP) is based on working with **partial solutions** and **enumeration tree** :

- ▶ We assign a value to a variable and see if all constraints are still satisfied.
- ▶ If not, we « backtrack » and try another value.
- ▶ To avoid complete enumeration, each time a variable takes a value, incompatible (with this decision) variables are removed (this process called **propagation**).

# Enumeration tree



## An example of simple propagation

	3	?	4		5		7	
6	2			8		4		
7					1			9
2		6			3	8		
						2		3
	1	3	6			9	5	
		8		4	7			
								6
		9		5		3	8	2

$$D = \{1, 2, 3, 4, 5, 6, 7, 8, 9\}$$

## An example of simple propagation

	3	?	4		5		7	
6	2			8		4		
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	1	3	6			9	5	
		8		4	7			
								6
		9		5		3	8	2

$$D = \{1, 2, \cancel{3}, 4, 5, \cancel{6}, 7, \cancel{8}, \cancel{9}\}$$

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	3	?	4		5		7	
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		8		4	7			
								6
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$$D = \{1, 2, 3, 4, 5, 6, 7, 8, 9\}$$



## An example of simple propagation

	3	1	4		5		7	
6	2			8		4		
7					1			9
2		6			3	8		
						2		3
	1	3	6			9	5	
		8		4	7			
								6
		9		5		3	8	2

$$D = \{1, 2, 3, 4, 5, 6, 7, 8, 9\}$$

## An example of advanced propagation

	3	1	4		5		7	
6	2			8		4	<sup>1</sup> <sub>3</sub>	
7					1		<sup>2</sup> <sub>3</sub> <sub>6</sub>	9
2		6			3	8	<sup>1</sup> <sub>4</sub>	
						2	<sup>1</sup> <sub>4</sub> <sub>6</sub>	3
	1	3	6			9	5	
		8		4	7		<sup>1</sup> <sub>9</sub>	
			9				<sup>1</sup> <sub>4</sub>	6
		9		5		3	8	2

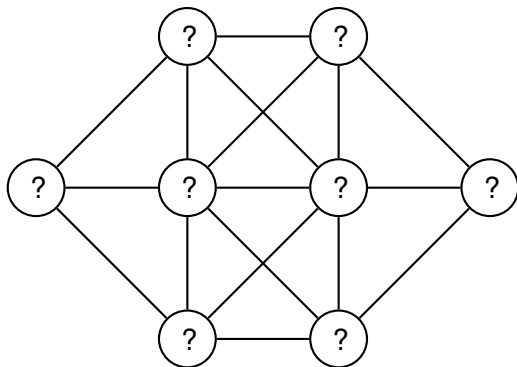
## An example of advanced propagation

	3	1	4		5		7	
6	2			8		4	<del>1</del> 3	
7					1		<del>2</del> <del>3</del> 6	9
2		6			3	8	<del>1</del> 4	
						2	<del>1</del> <del>4</del> 6	3
	1	3	6			9	5	
		8		4	7		<del>1</del> 9	
			9				<del>1</del> 4	6
		9		5		3	8	2

## An example of advanced propagation

	3	1	4		5		7	
6	2			8		4	3	
7					1		2	9
2		6			3	8	<sup>1</sup> <sub>4</sub>	
						2	6	3
	1	3	6			9	5	
		8		4	7		9	
			9				<sup>1</sup> <sub>4</sub>	6
		9		5		3	8	2

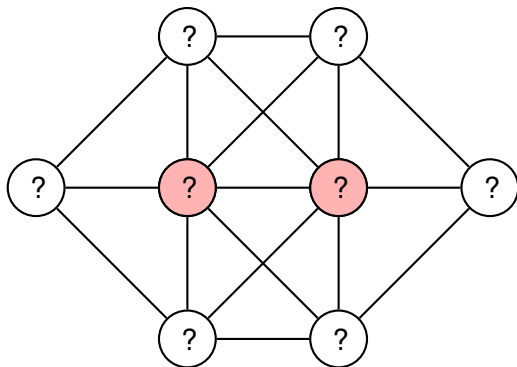
## An example of complete solution



**Problem** : assign values from 1 to 8 to vertices, each value should appear once, consecutive values should not be assigned to adjacent vertices

Source : Patrick Prosser

## An example of complete solution



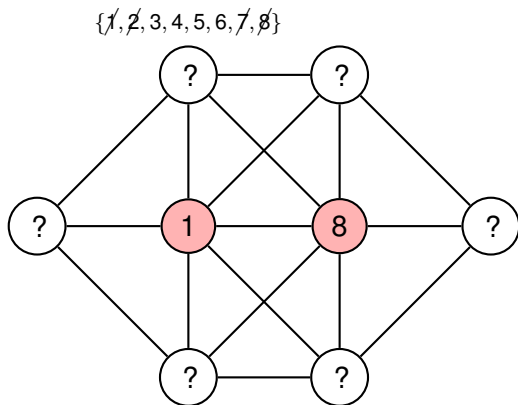
Be ready to do a backtrack.

Which vertices are more difficult to enumerate ?

Which values are less restraining ?

Source : Patrick Prosser

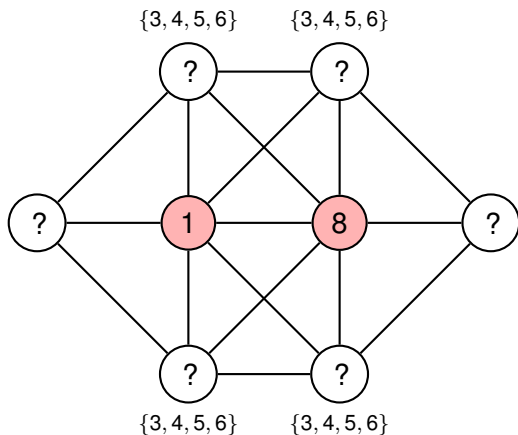
## An example of complete solution



We can now remove several variables from the domains of other vertices.

Source : Patrick Prosser

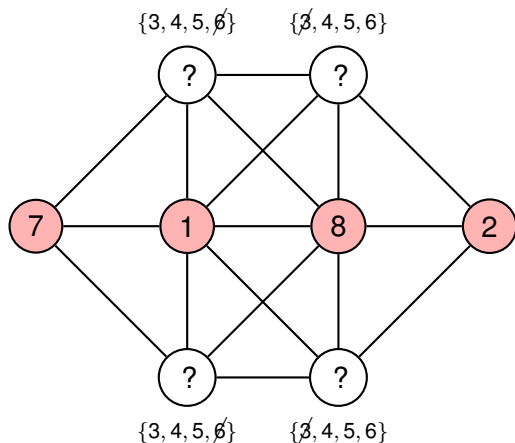
## An example of complete solution



We can now remove several variables from the domains of other vertices.

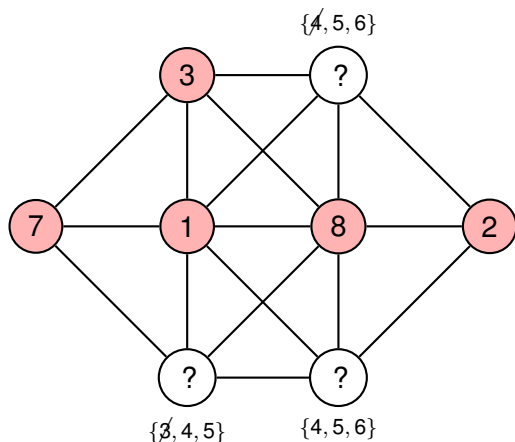


## An example of complete solution



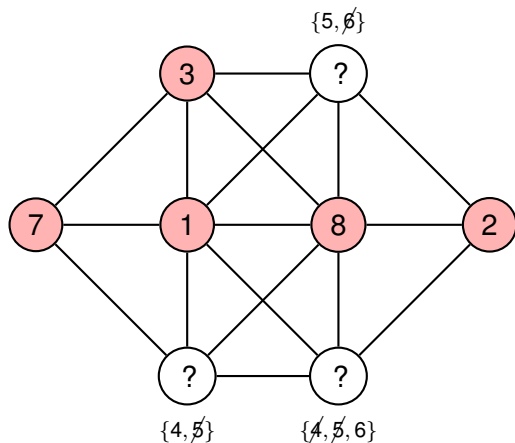
We can now remove several variables from the domains of other vertices.

## An example of complete solution



We guess now a value for a vertex.  
Be ready to do a backtrack.

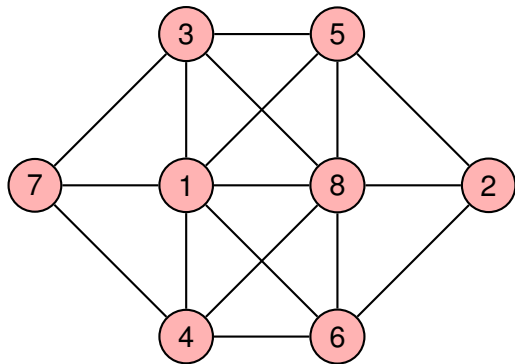
## An example of complete solution



We propagate this decision.

Source : Patrick Prosser

## An example of complete solution



A solution.

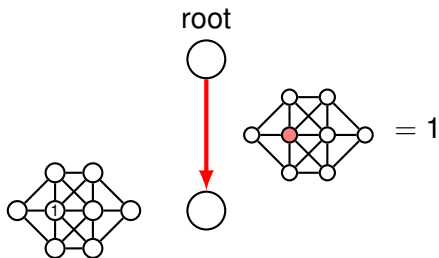
Source : Patrick Prosser

## Example : enumeration tree

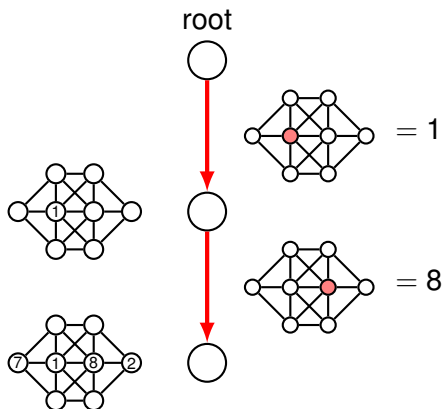
root



# Example : enumeration tree



# Example : enumeration tree



# Example : enumeration tree

