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Input to State Stability (ISS) for PDEs A Beginner's Guide Based on (interesting) Examples

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Plan



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luids and fluid-structure interactions

Definitions (I)

Let X (the state space) and U (the input space) be Banach spaces. Let X_+ (respectively U_+) be Banach spaces.

Definition

A well-posed control system with state space X and input space U is a family $\Sigma = (\Sigma_t)_{t \ge 0} \text{ of continuous maps from } X_+ \times L^p([0,\infty); U_+) \text{ to } X_+ \text{ such that,}$ setting $z(t) = \Sigma_t \begin{bmatrix} z_0 \\ u \end{bmatrix}$ we have (in an appropriate sense) $\dot{z}(t) = F(z(t), u(t)), \qquad z(0) = z_0.$

We refer to Mironchenko and Prieur [5] (2020), for a more precise (and slightly different) definition.

Definitions (II)

Definition

The well-posed control system Σ is said input-to-state stable (ISS) if there exist continuous functions $\alpha : [0, \infty) \times [0, \infty) \to [0, \infty)$ and $\gamma : [0, \infty) \to [0, \infty)$ such that:

1. For every r, s, t > 0 we have

$$\alpha(\mathbf{0}, \mathbf{s}) = \lim_{t \to \infty} \alpha(\mathbf{r}, t) = \gamma(\mathbf{0}) = \mathbf{0},$$

 $\alpha(\cdot, t), \ \alpha\left(r, \frac{1}{\cdot}\right)$ are strictly increasing on $(0, \infty)$.

2. For every $t \ge 0$, $z_0 \in X_+$ and $u \in L^\infty([0,\infty); U_+)$ we have

$$\|z(t)\|_X \leq \alpha(\|z_0\|_X, t) + \gamma(\sup_{\sigma \in [0, t]} \|u(\sigma)\|_U).$$
(1)

Since Sontag [7] (1989), an overwhelming literature is devoted to this subject. For PDEs, see Karafyllis and Krstic [3] (2019), Mironchenko and Prieur [5] (2020).

Introduction

Some remarks

- A linear system z
 = Az + Bu, with B ∈ L(U, X) is ISS iff A generates an exponentially stable semigroup.
- The property still holds if *B* is an admissible control operator for the exponentially stable semigroup generated by *A*.
- An abstract class of bilinear control systems has been considered in Hosfeld, Jacob and Schwenninger [2] (2020).
- Various PDE examples (mostly parabolic semilinear) have been tackled in the literature.
- Only a few results are available in the nonlinear hyperbolic or quasilinear case.
- For nonlinear system a local concept of ISS is also available.

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2 An age structured Kermack–Mckendrick epidemic model with intermittent vaccination



The governing equations

$$\begin{cases} \dot{S}(t) = u(t) - v(t)S(t) - \eta S(t) \int_0^\infty \beta(a)i(t, x) \, dx & (t \ge 0), \\ \frac{\partial i}{\partial t}(t, a) = -\frac{\partial i}{\partial a}(t, a) - \nu_l(a)i(t, a) & (t \ge 0, a \in (0, +\infty)), \\ i(t, 0) = \eta S(t) \int_0^\infty \beta(x)i(t, x) \, dx & (t \ge 0), \\ S(0) = S_0, & (t \ge 0, a \in (0, +\infty)), \\ i(0, a) = i_0(a) & (t \ge 0, a \in (0, +\infty)), \end{cases}$$

- S(t) denotes the total susceptible population at instant t.
- *i*(*t*, *a*) stands for the number of infected individuals with age of infection *a* at time *t*.
- $\eta > 0$ is the rate at which an infectious individual infects the susceptible individuals.
- The nonnegative number $\beta(a)$ designs the probability to be infectious (capable of transmitting the disease) with an age of infection equal to a.
- $t \mapsto v(t)$, the vaccination rate, is L^{∞} and positive.
- $u \in L^1_{loc}[0,\infty)$ is the input (disturbance), designing the flux of susceptible population.

Existence and uniqueness of solutions

Theorem (San Martin, Takahashi, Tucsnak, 2021)

Assume that β is bounded and uniformly continuous from $[0, +\infty)$ to $[0, +\infty)$. Moreover, assume that $\nu_I \in L^{\infty}[0, \infty)$, that

$$\nu_I(a) \ge 0$$
 $(a \in [0, \infty) \text{ a.e.}).$

Then for every $u \in L^1_{loc}[0,\infty)$, $v \in L^{\infty}([0,\infty); \mathbb{R}_+)$, $S_0 > 0$, $i_0 \in L^1[0,\infty)$, with $i_0(a) \ge 0$, and $S_0 + \int_0^{\infty} i_0(a) da \le 1$ there exists a unique solution with

$$S \in W^{1,\infty}(0,\infty), \qquad i \in C\left([0,\infty), L^1[0,\infty)
ight).$$

Some remarks:

- Similar existence and uniqueness results are given in Perthame and Tumuluri [6] (2008) and Magal and Ruan [4].
- The positivity constraints are essential in establishing this result.
- Our methodology seems adaptable to more complicated epidemic models.

Sketch of the proof(I)

Step 1. Let $\tau > 0$ and $C_{\tau} = S_0 + \|i_0\|_{L^1[0,\infty)} + \|u\|_{L^1[0,\tau]}$. We set

$$\mathcal{K}_{\tau} = \left\{ \varphi \in \mathcal{C}([0,\tau]; \mathcal{L}^1[0,\infty)) \ \big| \ \varphi \geqslant 0, \ \int_0^{\infty} \varphi(t, \mathbf{a}) \, \mathrm{d} \mathbf{a} \leqslant C_{\tau} \right\}.$$

For $\varphi \in K_{\tau}$ we solve

$$\dot{S}_{\varphi}(t) = u(t) - v(t)S_{\varphi}(t) - \eta S_{\varphi}(t) \int_{0}^{\infty} \beta(a)\varphi(t,x) \,\mathrm{d}x, \qquad S_{\varphi}(0) = S_{0},$$

$$\begin{cases} \frac{\partial i_{\varphi}}{\partial t}(t,a) = -\frac{\partial i_{\varphi}}{\partial a}(t,a) - \nu_{I}(a)i_{\varphi}(t,a) & (t \ge 0, \ a \in (0,+\infty)), \\ i_{\varphi}(t,0) = \eta S_{\varphi}(t) \int_{0}^{\infty} \beta(x)\varphi(t,x) \, \mathrm{d}x & (t \ge 0), \\ i_{\varphi}(0,a) = i_{0}(a) & (t \ge 0, \ a \in (0,\infty)), \end{cases}$$

$$(2)$$

and we define $N_{\tau}\varphi = i_{\varphi}$.

Sketch of the proof(II)

Step 2. We check easily that N_{τ} maps K_{τ} into K_{τ} and that, for every $k \in \mathbb{N}$ and every $\varphi_1, \varphi_2 \in K_{\tau}$ we have

$$\|N_{\tau}^{k}\varphi_{1}(t,\cdot)-N_{\tau}^{k}\varphi_{2}(t,\cdot)\|_{L^{1}[0,\infty)} \leqslant c_{\tau}^{2}\frac{t^{k}}{k!}\|\varphi_{1}-\varphi_{2}\|_{C([0,\tau];L^{1}[0,\infty)))}.$$
 $(t\in[0,\tau]).$

 N_{τ}^k is thus, for k large enough, a strict contraction of K_{τ} , which implies our existence and uniqueness result.

ISS of the epidemic system

Proposition

Assume that v is periodic of period τ with $\int_0^{\tau} v(t) dt > 0$. Moreover, suppose that $\nu_I(a) \ge \nu_0 > 0$ a.e. on $[0, \infty)$. Then the considered system is ISS.

Proof.

It suffices to remark that

$$\frac{\mathrm{d}}{\mathrm{d}t}\left(S(t)+\int_0^\infty i(t,x)\,\mathrm{d}x\right)\leqslant u(t)-\min\{v(t),\nu_0\}\left(S(t)+\int_0^\infty i(t,x)\,\mathrm{d}x\right),$$

to obtain that the ISS property holds with

$$\alpha(\mathbf{r}, \mathbf{t}) = M \mathbf{r} \mathrm{e}^{-\omega t}, \qquad \beta(\mathbf{s}) = \gamma \mathbf{s}.$$

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Fluids and fluid-structure interactions

The viscous Burgers equations with pointwise control

$$\begin{cases} \dot{v}(t,y) - v_{yy}(t,y) + v(t,y)v_{y}(t,y) = u(t)\delta_{\xi} & t \in (0,\infty), \ y \in (-1,1), \\ v(t,-1) = v(t,1) = 0 & t \in (0,\infty), \\ v(0,y) = v_{0}(y) & y \in (-1,1). \end{cases}$$
(3)

Proposition

The system (3) is ISS with $X = L^2(-1, 1)$, $U = \mathbb{C}$ and

$$\alpha(\mathbf{r}, \mathbf{t}) = M \mathbf{r} \mathrm{e}^{-\omega t}, \qquad \beta(\mathbf{s}) = \gamma \mathbf{s}.$$

A simplified fluid-structure system

$$\begin{cases} \dot{v}(t,y) - v_{yy}(t,y) + v(t,y)v_y(t,y) = 0 & t \in (0,\infty), \ y \in (-1,1), \ y \neq h(t) \\ v(t,-1) = v(t,1) = 0 & t \in (0,\infty), \\ \dot{h}(t) = v(t,h(t)) & t \in (0,\infty), \\ \ddot{h}(t) = [v_y](t,h(t)) + u(t) & t \in (0,\infty), \\ v(0,y) = v_0(y) & y \in (-1,1), \\ h(0) = h_0, \quad \dot{h}(0) = g_0. \end{cases}$$

$$(4)$$

Conjecture

The system (4) is ISS with $X = L^2(-1, 1) \times \mathbb{C}$, $U = \mathbb{C}$ and

$$\alpha(\mathbf{r}, \mathbf{t}) = M \mathbf{r} \mathrm{e}^{-\omega \mathbf{t}}, \qquad \beta(\mathbf{s}) = \gamma \mathbf{s}.$$

A list of potential ISS systems of interest

- Navier-Stokes in bounded domains with boundary control (what about velocities normal at the boundary?).
- Fluid-structure interactions in several space dimensions.
- Bilinear control.
- More elaborate epidemiological models (with age of infection and age structure).

The SIDHARTE system (I) (Giordano et al. [1] (2020))

$$\dot{S} = -S(\alpha I + \beta D + \gamma A + \delta R),$$
 (5a)

$$\dot{I} = S(\alpha I + \beta D + \gamma A + \delta R) - (\varepsilon + \zeta + \lambda)I,$$
(5b)

$$\dot{D} = \varepsilon I - (\eta + \rho)D,$$
 (5c)

$$\dot{A} = \zeta I - (\theta + \mu + \kappa) A,$$
 (5d)

$$\dot{R} = \eta D + \theta A - (\nu + \xi) R,$$
 (5e)

$$\dot{T} = \mu A + \nu R - (\sigma(T) + \tau(T))T, \qquad (5f)$$

$$\dot{H} = \lambda I + \rho D + \kappa A + \xi R + \sigma(T)T,$$
 (5g)

$$\dot{E} = \tau(T)T. \tag{5h}$$

S - **Susceptible**, **I** - **Infected** (asymptomatic, undetected), **D** - **Diagnosed** (asymptomatic, detected), **A** - **Ailing** (symptomatic, undetected), **R** - **Recognized** (symptomatic, detected), **T** - **Threatened** (symptomatic with life-threatening symptoms, detected), **H** - **Healed** (immune after prior infection, detected or undetected), **E** - **Extinct** (dead, detected).

The SIDHARTE system (II): Various inputs (disturbances)

- α, β, γ describe the infection rates for susceptible individuals, i.e., the rate at which susceptible individuals are infected by the states *I*, *D* or *R*, and *A*, respectively, and hence join the state *I*.
- ε, θ describe the testing rate, i.e., at which rate (asymptomatic or symptomatic) infected individuals go from undetected to detected.
- ζ describes the rate of asymptomatic (detected or undetected) infected individuals exhibiting symptoms, i.e., going from states *I* or *D* to *A* or *R*, respectively.
- μ is the rate at which infected individuals in A or R develop life-threatening symptoms, i.e., join the state T.
- λ, κ, σ(T) are recovery rates for individuals affected by COVID-19. The recovery rate for threatened individuals σ(T) depends on T.
- $\tau(T)$ is the mortality rate, i.e., the rate at which individuals with life-threatening symptoms decease, and it depends on T.

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