

A Reduced Basis technique for Long-Time Unsteady Turbulent Flows

Tommaso Taddei

Université Pierre et Marie Curie, LJLL

European workshop on ROMs for Industrial Applications, Turin,
October 17th

Work in collaboration with Lambert Fick (Texas A&M), Yvon Maday (UPMC, Brown University), Anthony T Patera (MIT).

Acknowledgments: Paul F Fischer, Elia Merzari (Argonne)

Objective

Develop a **model order reduction** procedure for the parametrized unsteady Navier-Stokes equations in the turbulent regime.

Develop a **model order reduction** procedure for the parametrized unsteady Navier-Stokes equations in the turbulent regime.

We wish to *efficiently* and *accurately* estimate QOIs associated with the velocity field

$$u(\mu) = u(x, t; \mu),$$

$$\begin{aligned} x &\in \Omega \subset \mathbb{R}^d, \\ t &\in (0, \infty), \\ \mu &\in \mathcal{P} \subset \mathbb{R}^P \end{aligned}$$

in the limit of many queries.

Efficiency: measured wrt the FOM in terms of memory requirements; computational time.

Accuracy: measured wrt the FOM in terms of

the long-time averaged flow $\langle u \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T u(t) dt$,

the TKE¹ $\text{TKE}(t) = \frac{1}{2} \int_{\Omega} \|u(x, t) - \langle u \rangle(x)\|_2^2 dx$.

For chaotic flows, prediction of the *instantaneous* velocity is out of reach.

¹More precisely, we shall estimate the *moments* of the TKE.

The parametric problem: the offline/online paradigm

We seek an estimate of $u(\mu)$ of the form:

$$\hat{u}(x, t; \mu) = \sum_{n=1}^N a_n(t, \mu) \zeta_n(x) \text{ for all } \mu \in \mathcal{P}.$$

The parametric problem: the offline/online paradigm

We seek an estimate of $u(\mu)$ of the form:

$$\hat{u}(x, t; \mu) = \sum_{n=1}^N a_n(t, \mu) \zeta_n(x) \text{ for all } \mu \in \mathcal{P}.$$

Offline stage: expensive, performed once

given $\{u(\cdot, t^k, \mu^\ell)\}_{k,\ell}$, $\{t^k\}_{k=1}^K \subset (0, T)$, $\{\mu^\ell\}_{\ell=1}^L \subset \mathcal{P}$,

generate the reduced space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$, and

formulate the Reduced Order Model

Online stage: inexpensive, performed many times

given $\mu \in \mathcal{P}$,

estimate the coefficients $\{a_n(t; \mu)\}_{n=1}^N$ for $t > 0$.

A simplified task: solution reproduction problem ($\mathcal{P} = \{\bar{\mu}\}$)

We seek an estimate of $u(\bar{\mu})$ s.t. $\hat{u}(x, t) = \sum_{n=1}^N a_n(t) \zeta_n(x)$

Offline stage:

given $\{u(\cdot, t^k, \bar{\mu})\}_{k=1}^K$,

generate the reduced space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$, and
formulate the Reduced Order Model

Online stage:

query the ROM for **the same** $\mu = \bar{\mu}$ to estimate
 $\{a_n(t)\}_{n=1}^N$ for $t > 0$.

A simplified task: solution reproduction problem ($\mathcal{P} = \{\bar{\mu}\}$)

We seek an estimate of $u(\bar{\mu})$ s.t. $\hat{u}(x, t) = \sum_{n=1}^N a_n(t) \zeta_n(x)$

Offline stage:

given $\{u(\cdot, t^k, \bar{\mu})\}_{k=1}^K$,

generate the reduced space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$, and
formulate the Reduced Order Model

Online stage:

query the ROM for **the same** $\mu = \bar{\mu}$ to estimate
 $\{a_n(t)\}_{n=1}^N$ for $t > 0$.

Limited practical interest, but

key intermediate step toward the development of the ROM
formulation.

1. A model lid-driven cavity problem

2. Solution reproduction problem

Galerkin ROM
constrained Galerkin ROM

3. Parametric problem

a posteriori error estimation
POD-*h*Greedy

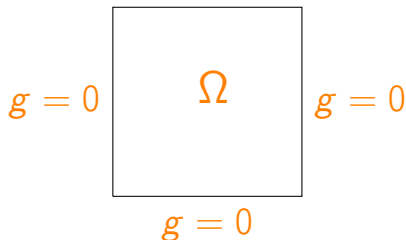
A model lid-driven cavity problem

A lid-driven cavity problem²

Consider the problem:

$$\begin{cases} \partial_t u + (u \cdot \nabla)u - \frac{1}{\text{Re}} \Delta u + \nabla p = 0 & \Omega \times \mathbb{R}_+ \\ \nabla \cdot u = 0 & \Omega \times \mathbb{R}_+ \\ u|_{\partial\Omega} = g, \quad u(0) = 0 \end{cases}$$

$$g = (1 - x_1^2)^2 \mathbf{e}_1$$



$$\Omega = (-1, 1)^2$$

$$\text{Re} \in \mathcal{P} = [15000, 25000]$$

(turbulent regime)

²Model problem considered in Balajewicz, Dowell, Nonlinear Dyn (2012).

Weak formulation for the lifted equations ($\dot{u} := u - R_g$)

Given R_g s.t. $R_g|_{\partial\Omega} = g$, $\nabla \cdot R_g \equiv 0$, find (\dot{u}, p) s.t.

$$\left\{ \begin{array}{l} \langle \partial_t \dot{u}(t), v \rangle_* + \frac{1}{\text{Re}} \int_{\Omega} \nabla(\dot{u}(t) + R_g) : \nabla v \, dx \\ \quad + c(\dot{u}(t) + R_g, \dot{u}(t) + R_g, v) + b(v, p(t)) = 0 \\ b(\dot{u}(t), q) = 0 \quad \forall v \in V, \quad q \in Q, \quad \text{a.e. } t > 0. \end{array} \right.$$

where $V = [H_0^1(\Omega)]^2$, $Q = \{q \in L^2(\Omega) : \int_{\Omega} q = 0\}$, and

$$c(w, v, z) = \int_{\Omega} (w \cdot \nabla) v \cdot z \, dx, \quad b(v, q) = - \int_{\Omega} (\nabla \cdot v) q \, dx.$$

Choice for the lift: $R_g =$ Stokes solution

The choice $R_g = \langle u \rangle$ is not suitable for the parametric case.

We rely on the **spectral element** solver Nek5000 to generate the DNS data.

We refer to nek5000.mcs.anl.gov for details concerning the software.

Simulations were performed by Dr. Lambert Fick (Texas A&M) at Argonne National Lab.

Deville, Fischer, Mund, Cambridge University Press (2002).

Solution reproduction problem

- A first attempt: POD-Galerkin
- Our proposal: POD-constrained Galerkin

Solution reproduction problem

- A first attempt: POD-Galerkin
- Our proposal: POD-constrained Galerkin

Galerkin ROM (semi-implicit time integration)

Given $\mathcal{Z}^u := \text{span}\{\zeta_n\}_{n=1}^N \subset V_{\text{div}} = \{v \in V : \nabla \cdot v = 0\}$,
and $\{t^j = j\Delta t\}_{j=0}^J$, find $\{\hat{u}^j\}_j \subset \mathcal{Z}^u$ such that

$$\left(\frac{\hat{u}^{j+1} - \hat{u}^j}{\Delta t}, v \right)_{L^2(\Omega)} + \frac{1}{\text{Re}} \int_{\Omega} \nabla(\hat{u}^{j+1} + R_g) : \nabla v \, dx \\ + c(\hat{u}^j + R_g, \hat{u}^{j+1} + R_g, v) = 0 \quad \forall v \in \mathcal{Z}^u, \quad j = 0, 1, \dots$$

Galerkin ROM (semi-implicit time integration)

Given $\mathcal{Z}^u := \text{span}\{\zeta_n\}_{n=1}^N \subset V_{\text{div}} = \{v \in V : \nabla \cdot v = 0\}$,
and $\{t^j = j\Delta t\}_{j=0}^J$, find $\{\hat{u}^j\}_j \subset \mathcal{Z}^u$ such that

$$\left(\frac{\hat{u}^{j+1} - \hat{u}^j}{\Delta t}, v \right)_{L^2(\Omega)} + \frac{1}{\text{Re}} \int_{\Omega} \nabla(\hat{u}^{j+1} + R_g) : \nabla v \, dx \\ + c(\hat{u}^j + R_g, \hat{u}^{j+1} + R_g, v) = 0 \quad \forall v \in \mathcal{Z}^u, \quad j = 0, 1, \dots$$

The space \mathcal{Z}^u is built through the DNS data $\{\hat{u}^k = u(t^k) - R_g\}_{k=1}^K \subset V_{\text{div}}$ using POD.

We consider the following choice of the inner product (\cdot, \cdot) :

$$(w, v) = \int_{\Omega} \nabla w : \nabla v \, dx \quad H^1 - \text{POD}$$

Galerkin ROM: algebraic formulation (semi-implicit in time)

The coefficients $\mathbf{a}^j = [a_1^j, \dots, a_N^j]$ ($\leftrightarrow \{\hat{u}^j\}_j$) solve

$$\mathbb{A}(\mathbf{a}^j) \mathbf{a}^{j+1} = \mathbf{F}(\mathbf{a}^j) \quad j = 0, 1, \dots, \quad (\hat{u}^j = \sum_n a_n^j \zeta_n)$$

Galerkin ROM: algebraic formulation (semi-implicit in time)

The coefficients $\mathbf{a}^j = [a_1^j, \dots, a_N^j]$ ($\leftrightarrow \{\hat{u}^j\}_j$) solve

$$\mathbb{A}(\mathbf{a}^j) \mathbf{a}^{j+1} = \mathbf{F}(\mathbf{a}^j) \quad j = 0, 1, \dots, \quad (\hat{u} = \sum_n a_n \zeta_n)$$

where $\mathbb{A} : \mathbb{R}^N \rightarrow \mathbb{R}^{N,N}$, and $\mathbf{F} : \mathbb{R}^N \rightarrow \mathbb{R}^N$ are

$$\begin{aligned} \mathbb{A}_{m,n}(\mathbf{w}) = & \frac{1}{\Delta t} \int_{\Omega} \zeta_n \cdot \zeta_m \, dx + \frac{1}{\text{Re}} \int_{\Omega} \nabla \zeta_n : \nabla \zeta_m \, dx \\ & + c(R_g, \zeta_n, \zeta_m) + \sum_{i=1}^N w_i c(\zeta_i, \zeta_n, \zeta_m) \end{aligned}$$

$$\begin{aligned} \mathbf{F}_m(\mathbf{w}) = & \sum_{n=1}^N w_n \left(\frac{1}{\Delta t} \int_{\Omega} \zeta_n \cdot \zeta_m \, dx - c(\zeta_n, R_g, \zeta_m) \right) \\ & - \frac{1}{\text{Re}} \int_{\Omega} \nabla R_g : \nabla \zeta_m \, dx \end{aligned}$$

Offline stage:

Compute DNS data $\{u^k = u(\cdot, t^k)\}_{k=1}^K$, $t^k = T_0 + k$
 $T_0 = 500$, $K = 500$

Use POD to build the space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$

Define $\mathbf{A} : \mathbb{R}^N \rightarrow \mathbb{R}^{N,N}$, and $\mathbf{F} : \mathbb{R}^N \rightarrow \mathbb{R}^N$

Online stage:

Solve the discrete dynamical system:

$$\mathbf{A}(\mathbf{a}^j)\mathbf{a}^{j+1} = \mathbf{F}(\mathbf{a}^j), \quad j = 0, \dots, J-1$$

Offline stage:

Compute DNS data $\{u^k = u(\cdot, t^k)\}_{k=1}^K$, $t^k = T_0 + k$
 $T_0 = 500$, $K = 500$

Use POD to build the space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$

Define $\mathbf{A} : \mathbb{R}^N \rightarrow \mathbb{R}^{N,N}$, and $\mathbf{F} : \mathbb{R}^N \rightarrow \mathbb{R}^N$

Online stage:

Solve the discrete dynamical system:

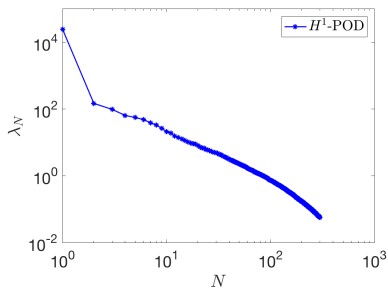
$$\mathbf{A}(\mathbf{a}^j)\mathbf{a}^{j+1} = \mathbf{F}(\mathbf{a}^j), \quad j = 0, \dots, J-1$$

Online memory requirements: $\mathcal{O}(N^3)$.

Online cost: $\mathcal{O}(N^3 J)$.

POD eigenvalues (Re = 15000)

POD eigenvalues $\{\lambda_N\}_N$ decay slowly with N .



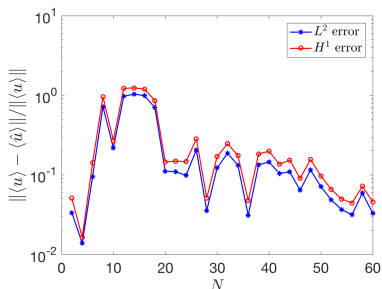
$$\begin{aligned}u^k &:= u(\cdot, t^k) \\t^k &:= 500 + k, \\k &= 1, \dots, K = 500\end{aligned}$$

$$\zeta_1 \approx C(\langle u \rangle - R_g)$$

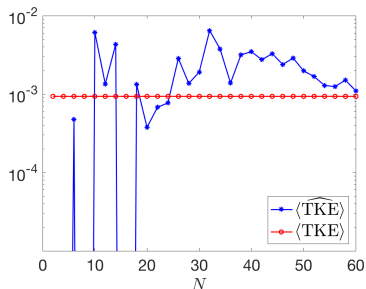
\Rightarrow no contribution to fluctuating field

$$\frac{\sum_{k'=2}^N \lambda_{k'}}{\sum_{k=2}^K \lambda_k} = \begin{cases} 16.5\% & N = 2 \\ 73.1\% & N = 20 \\ 79.7\% & N = 30 \\ 87.0\% & N = 50 \end{cases}$$

Numerical results ($Re = 15000$): performance (I)



Rel. error in $\langle u \rangle$



Mean TKE

We observe several **spurious** effects for moderate N :
false stable steady flows,
overly unstable flows...

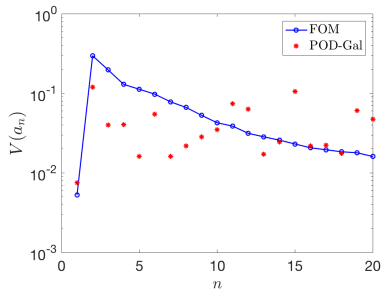
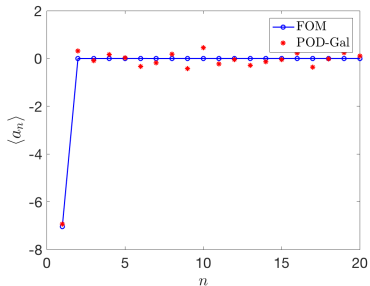
For $N \gtrsim 50$, accuracy improves.

Numerical results ($Re = 15000$): performance (II)

Moments of $\{a_n\}_n$ ($\dot{u}(\cdot, t) = \sum_{n=1}^{\infty} a_n(t)\zeta_n$): $\mathbf{N} = 20$

$$E(a_n, \{t^k\}) = \frac{1}{K} \sum_{k=1}^K a_n(t^k),$$

$$V(a_n, \{t^k\}) = \frac{1}{K-1} \sum_{k=1}^K (a_n(t^k) - E(a_n, \{t^k\}))^2$$

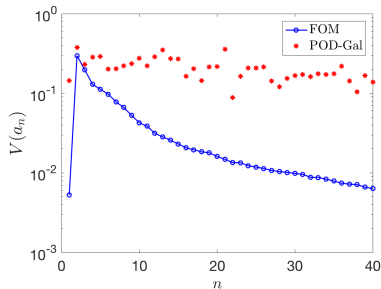
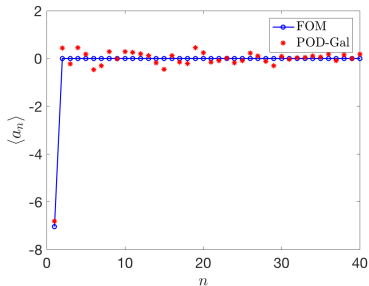


Numerical results ($Re = 15000$): performance (II)

Moments of $\{a_n\}_n$ ($\dot{u}(\cdot, t) = \sum_{n=1}^{\infty} a_n(t)\zeta_n$): **N = 40**

$$E(a_n, \{t^k\}) = \frac{1}{K} \sum_{k=1}^K a_n(t^k),$$

$$V(a_n, \{t^k\}) = \frac{1}{K-1} \sum_{k=1}^K (a_n(t^k) - E(a_n, \{t^k\}))^2$$

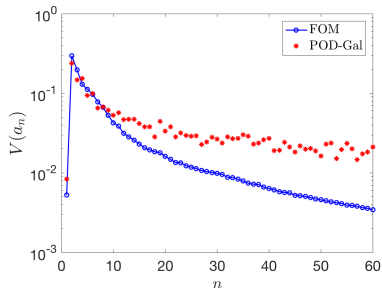
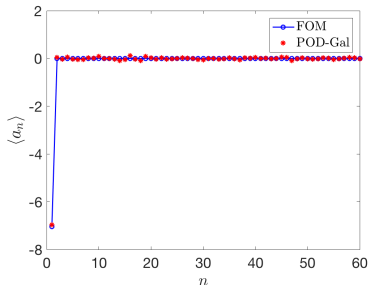


Numerical results ($Re = 15000$): performance (II)

Moments of $\{a_n\}_n$ ($\dot{u}(\cdot, t) = \sum_{n=1}^{\infty} a_n(t)\zeta_n$): **N = 60**

$$E(a_n, \{t^k\}) = \frac{1}{K} \sum_{k=1}^K a_n(t^k),$$

$$V(a_n, \{t^k\}) = \frac{1}{K-1} \sum_{k=1}^K (a_n(t^k) - E(a_n, \{t^k\}))^2$$



POD-Galerkin approach does not provide an adequate approximation of the long-time system dynamics, particularly for moderate N .

We observe several spurious effects
false stable steady flows,
overly unstable flows...

This behavior is similar to the one observed for highly-truncated spectral approximations to turbulent flows.

Curry, Herring, Loncaric, Orszag, J Fluid Mech (1984).

Solution reproduction problem

- A first attempt: POD-Galerkin
- Our proposal: POD-constrained Galerkin

We propose the following ROM (cGalerkin):

$$\mathbf{a}^{j+1} := \arg \min_{\mathbf{w} \in \mathbb{R}^N} \|\mathbb{A}(\mathbf{a}^j)\mathbf{w} - \mathbf{F}(\mathbf{a}^j)\|_2^2,$$

subject to $\alpha_n \leq w_n \leq \beta_n$, $n = 1, \dots, N$.

\mathbb{A} and \mathbf{F} are the matrix-valued and vector-valued functions introduced for the Galerkin ROM.

We propose the following ROM (cGalerkin):

$$\mathbf{a}^{j+1} := \arg \min_{\mathbf{w} \in \mathbb{R}^N} \|\mathbb{A}(\mathbf{a}^j)\mathbf{w} - \mathbf{F}(\mathbf{a}^j)\|_2^2,$$

subject to $\alpha_n \leq w_n \leq \beta_n, n = 1, \dots, N$.

\mathbb{A} and \mathbf{F} are the matrix-valued and vector-valued functions introduced for the Galerkin ROM.

If $\mathbf{a}_{\text{Gal}}^{j+1} := \mathbb{A}(\mathbf{a}^j)^{-1} \mathbf{F}(\mathbf{a}^j)$ satisfies the constraints, cGalerkin = Galerkin.

For semi-implicit and explicit time discretizations, cGalerkin corresponds to a **convex quadratic programming** problem, which can be solved using an interior point method.

Estimates of $\{\alpha_n\}_n$ and $\{\beta_n\}_n$

α_n and β_n are lower and upper bounds for³

$$a_n(t) := (\dot{u}(t) = u(t) - R_g, \zeta_n).$$

Given the snapshots $\{u^k\}_{k=1}^K$, we set $\{\alpha_n\}_n$ and $\{\beta_n\}_n$ as

$$\alpha_n = m_n^u - \epsilon(M_n^u - m_n^u), \quad \beta_n = M_n^u + \epsilon(M_n^u - m_n^u);$$

where $\epsilon = 0.01^4$, and

$$m_n^u := \min_{k=1, \dots, K} (\dot{u}^k, \zeta_n)_V, \quad M_n^u := \max_{k=1, \dots, K} (\dot{u}^k, \zeta_n)_V.$$

³**NOTE 1:** $(\zeta_m, \zeta_n) = \delta_{m,n}$

⁴**NOTE 2:** $\{t^k\}_k$ sampling times, $\{t^j\}_j$ time grid, $K \ll J$.

Estimates of $\{\alpha_n\}_n$ and $\{\beta_n\}_n$

α_n and β_n are lower and upper bounds for³

$$a_n(t) := (\dot{u}(t) = u(t) - R_g, \zeta_n).$$

Given the snapshots $\{u^k\}_{k=1}^K$, we set $\{\alpha_n\}_n$ and $\{\beta_n\}_n$ as

$$\alpha_n = m_n^u - \epsilon(M_n^u - m_n^u), \quad \beta_n = M_n^u + \epsilon(M_n^u - m_n^u);$$

where $\epsilon = 0.01^4$, and

$$m_n^u := \min_{k=1, \dots, K} (\dot{u}^k, \zeta_n)_V, \quad M_n^u := \max_{k=1, \dots, K} (\dot{u}^k, \zeta_n)_V.$$

The hyper-parameters $\{\alpha_n\}_n$ and $\{\beta_n\}_n$ of cGalerkin admit a simple interpretation, and can be easily tuned based on **sparse DNS data**.

³**NOTE 1:** $(\zeta_m, \zeta_n) = \delta_{m,n}$

⁴**NOTE 2:** $\{t^k\}_k$ sampling times, $\{t^j\}_j$ time grid, $K \ll J$.

Offline stage:

Compute DNS data $\{u^k = u(\cdot, t^k)\}_{k=1}^K$

Use POD to build the space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$

Define $\mathbf{A} : \mathbb{R}^N \rightarrow \mathbb{R}^{N,N}$, and $\mathbf{F} : \mathbb{R}^N \rightarrow \mathbb{R}^N$

Define $\{\alpha_n\}_n$ and $\{\beta_n\}_n$ based on the DNS data $\{\dot{u}^k\}_k$

Online stage:

Solve the discrete dynamical system:

$$\mathbf{a}^{j+1} = \arg \min_{\mathbf{w} \in \mathbb{R}^N} \|\mathbf{A}(\mathbf{a}^j)\mathbf{w} - \mathbf{F}(\mathbf{a}^j)\|_2^2, \quad \text{s.t. } \alpha_n \leq w_n \leq \beta_n$$

Offline stage:

Compute DNS data $\{u^k = u(\cdot, t^k)\}_{k=1}^K$

Use POD to build the space $\mathcal{Z}^u = \text{span}\{\zeta_n\}_{n=1}^N$

Define $\mathbf{A} : \mathbb{R}^N \rightarrow \mathbb{R}^{N,N}$, and $\mathbf{F} : \mathbb{R}^N \rightarrow \mathbb{R}^N$

Define $\{\alpha_n\}_n$ and $\{\beta_n\}_n$ based on the DNS data $\{\dot{u}^k\}_k$

Online stage:

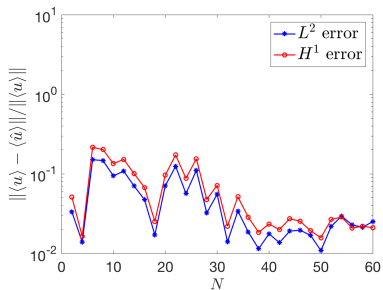
Solve the discrete dynamical system:

$$\mathbf{a}^{j+1} = \arg \min_{\mathbf{w} \in \mathbb{R}^N} \|\mathbf{A}(\mathbf{a}^j)\mathbf{w} - \mathbf{F}(\mathbf{a}^j)\|_2^2, \quad \text{s.t. } \alpha_n \leq w_n \leq \beta_n$$

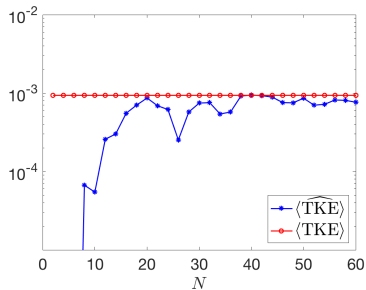
Online memory requirements: $\mathcal{O}(N^3)$.

Online cost: $\mathcal{O}(N^3 \underbrace{J_{\text{pure}}}_{\text{Gal. solves}} + \underbrace{\kappa N^3}_{\text{cost QP}} (J - J_{\text{pure}}))$.

Numerical results ($Re = 15000$): performance (I)



Rel. error in $\langle u \rangle$

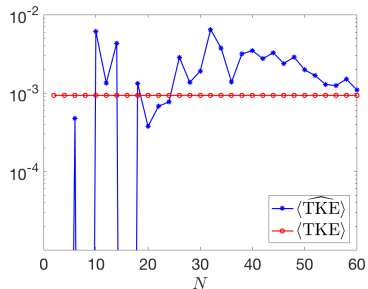


Mean TKE

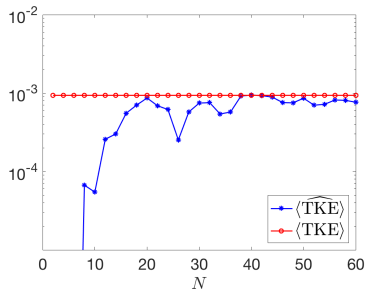
The constrained Galerkin formulation consistently underestimates the TKE.

For $N \gtrsim 40$, $\mathbf{a}^{j+1} = \mathbf{a}_{Gal}^{j+1}$ for roughly 90% time steps.

Numerical results ($Re = 15000$): performance (II)



Galerkin



constrained Galerkin

For some values of N , $\langle TKE_{cGal} \rangle > \langle TKE_{Gal} \rangle$. For some other values $\langle TKE_{cGal} \rangle < \langle TKE_{Gal} \rangle$.

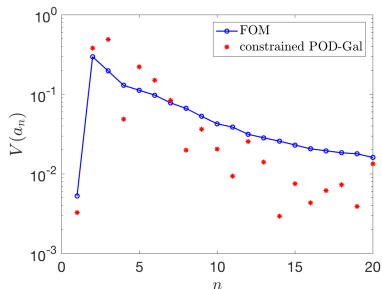
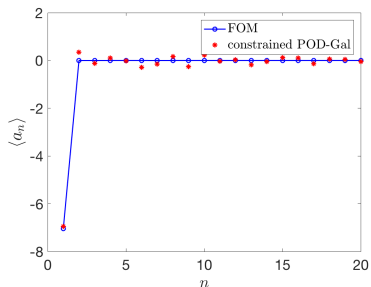
\Rightarrow cGalerkin does **not** add artificial viscosity to Galerkin.

Numerical results ($Re = 15000$): performance (III)

Moments of $\{a_n\}_n$ ($\dot{u}(\cdot, t) = \sum_{n=1}^{\infty} a_n(t)\zeta_n$): **N = 20**

$$E(a_n, \{t^k\}) = \frac{1}{K} \sum_{k=1}^K a_n(t^k),$$

$$V(a_n, \{t^k\}) = \frac{1}{K-1} \sum_{k=1}^K (a_n(t^k) - E(a_n, \{t^k\}))^2$$

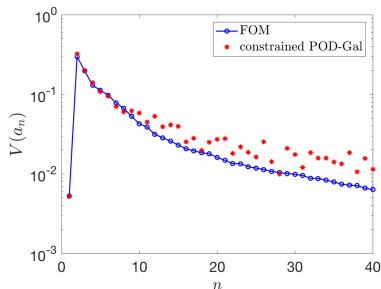
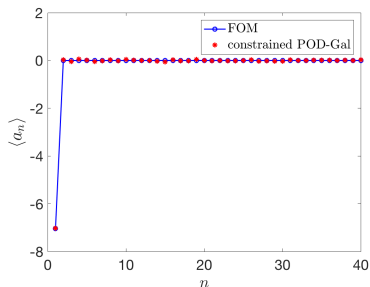


Numerical results ($Re = 15000$): performance (III)

Moments of $\{a_n\}_n$ ($\dot{u}(\cdot, t) = \sum_{n=1}^{\infty} a_n(t)\zeta_n$): **N = 40**

$$E(a_n, \{t^k\}) = \frac{1}{K} \sum_{k=1}^K a_n(t^k),$$

$$V(a_n, \{t^k\}) = \frac{1}{K-1} \sum_{k=1}^K (a_n(t^k) - E(a_n, \{t^k\}))^2$$

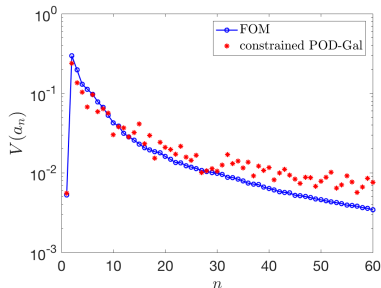
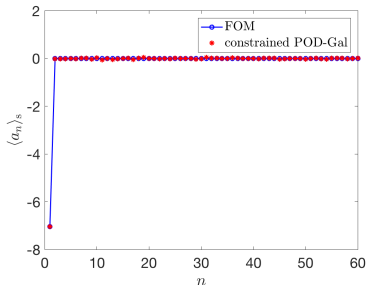


Numerical results ($Re = 15000$): performance (III)

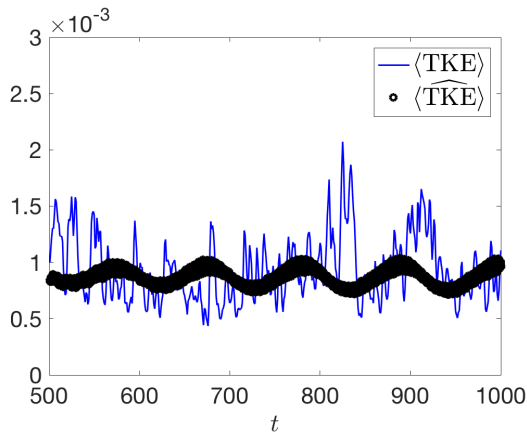
Moments of $\{a_n\}_n$ ($\dot{u}(\cdot, t) = \sum_{n=1}^{\infty} a_n(t)\zeta_n$): **N = 60**

$$E(a_n, \{t^k\}) = \frac{1}{K} \sum_{k=1}^K a_n(t^k),$$

$$V(a_n, \{t^k\}) = \frac{1}{K-1} \sum_{k=1}^K (a_n(t^k) - E(a_n, \{t^k\}))^2$$



Behavior of the turbulent kinetic energy ($N = 20$)



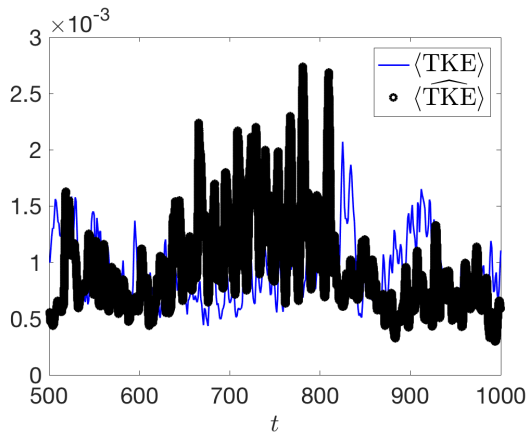
$$\langle \text{TKE} \rangle = 9.4 \cdot 10^{-4},$$

$$\langle \widehat{\text{TKE}} \rangle = 8.6 \cdot 10^{-4};$$

$$\mathbb{V}(\text{TKE}) = 8.5 \cdot 10^{-8};$$

$$\mathbb{V}(\widehat{\text{TKE}}) = 5.5 \cdot 10^{-9}.$$

Behavior of the turbulent kinetic energy ($N = 40$)



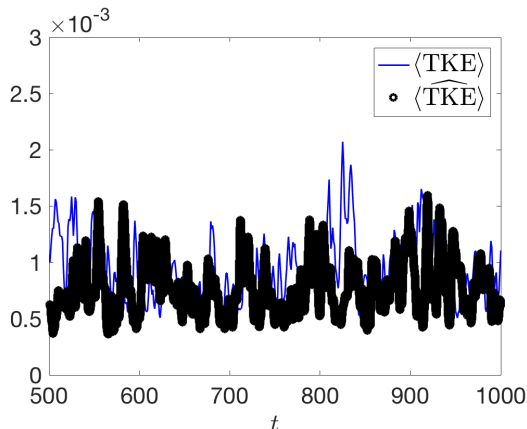
$$\langle \text{TKE} \rangle = 9.4 \cdot 10^{-4},$$

$$\langle \widehat{\text{TKE}} \rangle = 9.4 \cdot 10^{-4};$$

$$\mathbb{V}(\text{TKE}) = 8.5 \cdot 10^{-8};$$

$$\mathbb{V}(\widehat{\text{TKE}}) = 1.7 \cdot 10^{-7}.$$

Behavior of the turbulent kinetic energy ($N = 60$)



$$\langle \text{TKE} \rangle = 9.4 \cdot 10^{-4},$$

$$\langle \widehat{\text{TKE}} \rangle = 7.65 \cdot 10^{-4};$$

$$\mathbb{V}(\text{TKE}) = 8.5 \cdot 10^{-8};$$

$$\mathbb{V}(\widehat{\text{TKE}}) = 5.8 \cdot 10^{-8}.$$

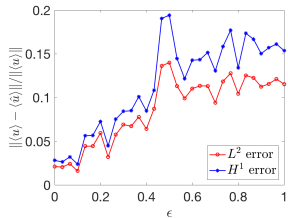
Prediction of instantaneous TKE is out of reach.

Our results suggest that estimation of TKE moments is achievable.

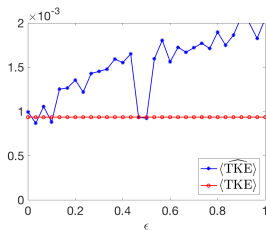
Sensitivity analysis wrt ϵ (Re = 15000, $N = 40$)

ϵ enters in the definition of the bounds α_n and β_n :

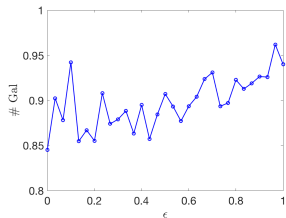
$$\alpha_n = m_n^u - \epsilon(M_n^u - m_n^u), \quad \beta_n = M_n^u + \epsilon(M_n^u - m_n^u);$$



Rel. error in $\langle u \rangle$



Mean TKE

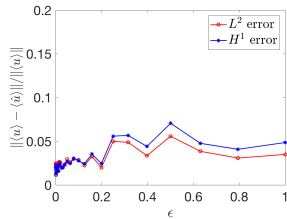


$\% \mathbf{a}^{j+1} = \mathbf{a}_{\text{Gal}}^{j+1}$

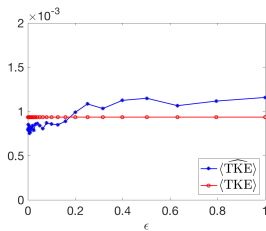
Sensitivity analysis wrt ϵ (Re = 15000, $N = 60$)

ϵ enters in the definition of the bounds α_n and β_n :

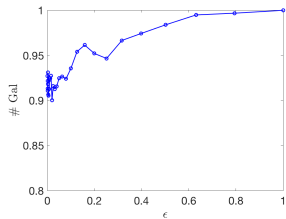
$$\alpha_n = m_n^u - \epsilon(M_n^u - m_n^u), \quad \beta_n = M_n^u + \epsilon(M_n^u - m_n^u);$$



Rel. error in $\langle u \rangle$



Mean TKE



$$\% \mathbf{a}^{j+1} = \mathbf{a}_{Gal}^{j+1}$$

Interpretation: as N increases, the Galerkin model becomes more and more accurate, and box constraints become less and less important.

Parametric problem

- Error estimation
- POD - h Greedy

Offline stage:

Select $\text{Re}_1^*, \dots, \text{Re}_L^*$ in a Greedy fashion based on an error indicator Δ^u

Use snapshots $\{u^{k,l} = u(\cdot, t^k, \text{Re}_\ell^*)\}$ to generate the reduced space \mathcal{Z}^u

Build the ROM associated with the reduced space \mathcal{Z}^u

Haasdonk, Ohlberger, M2AN, (2008).

Offline stage:

Select $\text{Re}_1^*, \dots, \text{Re}_L^*$ in a Greedy fashion based on an error indicator Δ^u

Challenge 1: error estimation

Use snapshots $\{u^{k,l} = u(\cdot, t^k, \text{Re}_\ell^*)\}$ to generate the reduced space \mathcal{Z}^u

Challenge 2: combination of modes from different regimes

Build the ROM associated with the reduced space \mathcal{Z}^u

Haasdonk, Ohlberger, M2AN, (2008).

Challenge 1: error estimation

Error estimators for evolution problems are based on energy estimates, or

Haasdonk, Ohlberger, 2008

Grepl, Patera, 2005

BRR theory and space-time formulations.

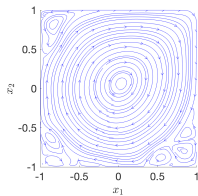
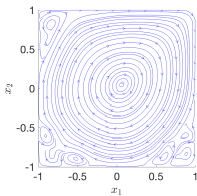
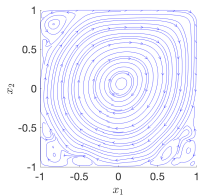
Urban, Patera, 2014

Yano, 2014

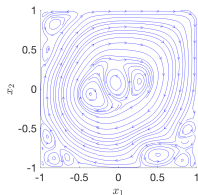
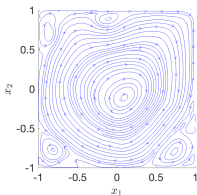
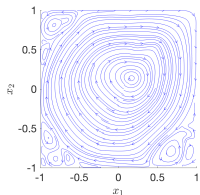
These estimators bound the error in the full trajectory
⇒ inappropriate for turbulent flows.

Challenge 2: combination of modes from different regimes

$Re = 15000$, $t = 501, 600, 700$



$Re = 20000$, $t = 1252, 1266, 1344$



Combining modes associated with different regimes lead to poor performance.

Parametric problem

- Error estimation
- POD - h Greedy

Our proposal: time-averaged error indicator

Given $\{w^j\}_j \subset V_{\text{div}}$, define the residuals

$$e^j(\text{Re}) = \frac{w^{j+1} - w^j}{\Delta t} - \frac{1}{\text{Re}} \Delta(w^{j+1} + R_g) \\ + (w^j + R_g) \cdot \nabla(w^{j+1} + R_g)$$

Then, define the time-averaged residual for all $v \in V_{\text{div}}$:

$$\langle R \rangle(\{w^j\}_j; v; \text{Re}) = \frac{1}{J - J_0} \sum_{j=J_0}^{J-1} \langle e^j(\text{Re}), v \rangle_{V'_{\text{div}} \times V_{\text{div}}},$$

and the error indicator

$$\Delta^u(\{w^j\}_j; \text{Re}) = \|\langle R \rangle(\{w^j\}_j; \cdot; \text{Re})\|_{V'_{\text{div}}}.$$

If $J - J_0 \rightarrow \infty$, $\langle R \rangle$ converges to the discretized residual of RANS

Intuition: Δ^u correlated to error in mean flow prediction.

Δ^u admits an offline/online decomposition, which requires

$\mathcal{O}(N^2)$ Stokes' solves offline

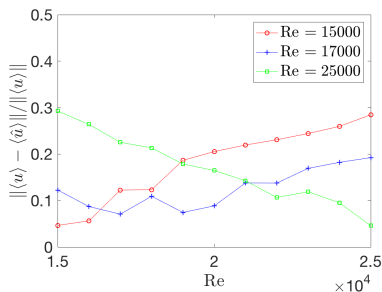
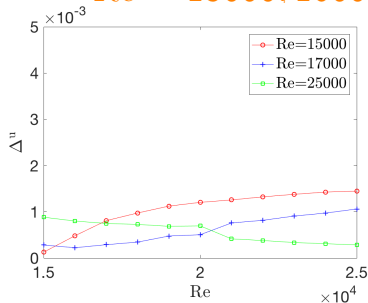
large storage cost if $N^2 > K$;

$\mathcal{O}(N^4 + N^2 J)$ online computational cost

negligible computational cost compared to $\mathcal{O}(N^3 J)$.

Evaluation of the error indicator

Test: generate ROMs for $Re = 15000, 17000, 25000$;
evaluate Δ^u and the relative H^1 error for
 $Re = 15000, 16000, \dots, 25000$.



Error estimator is good indicator but poor quantitative agreement with true error.

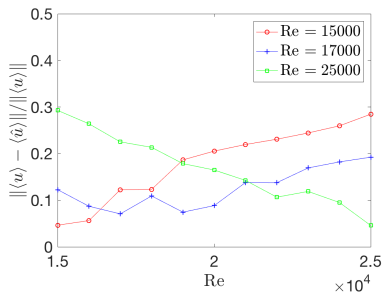
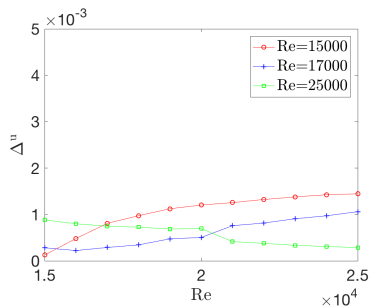
for $10/11$ Re , the same ROM minimizes both the relative error and Δ^u .

Parametric problem

- Error estimation
- POD - *h*Greedy

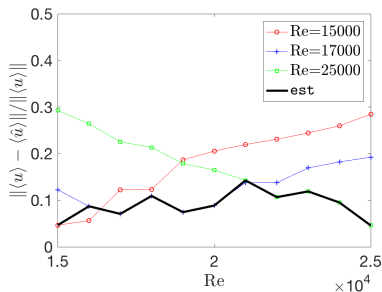
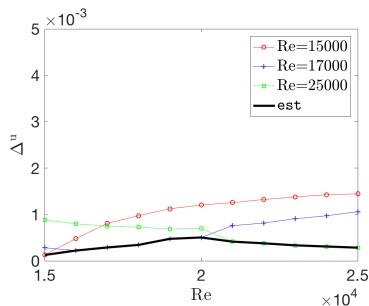
Proposal:

given the three ROMs for $Re = 15000, 17000, 25000$,
 for a new value of the Reynolds number,
 select the ROM that minimizes the error indicator



Proposal:

given the three ROMs for $Re = 15000, 17000, 25000$,
 for a new value of the Reynolds number,
 select the ROM that minimizes the error indicator



The relative error is less than **13%** for all values of the Reynolds number considered.

The h Greedy partitions the parameter domain \mathcal{P} to deal with different behaviors.

The h Greedy requires the solution to n_{cand} ($= 3$ in this case) ROMs during the online stage.

The anchor points $\text{Re} = 15000, 17000, 25000$ can be chosen in a Greedy fashion based on the error indicator.

Eftang, Knezevic, Patera, Math Comput Model Dyn Syst, (2011).

Conclusions

Turbulent flows present several challenges.

Slow decay of the POD eigenvalues λ_N ;

Several spurious behaviors

Poor effectivity of traditional error indicators

Difficulty in combining modes from different regimes

Turbulent flows present several challenges.

Slow decay of the POD eigenvalues λ_N ;

reduce the goal of MOR $\langle u \rangle$, TKE

Several spurious behaviors

constrained formulation

Poor effectivity of traditional error indicators

time-avg residual indicator

Difficulty in combining modes from different regimes

h Greedy

Thank you for your
attention!

For more information,
Fick, Maday, Patera, Taddei, *A Reduced Basis Technique for Long-
Time Unsteady Turbulent Flows*

available on Arxiv, and ResearchGate